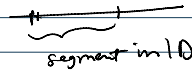


Manifold → simplest 1D manifold

← a point is a 0-manifold

disk of  
local property: radius  $\leq 1$   
(n-ball in any dimension)



sphere in 3D  
including the interior

$|x|=1 \rightarrow n$ -sphere

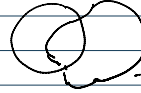
manifold = object where all points look like a ball

for every point, there is a neighborhood that looks like a segment (in 1D)

example:



T shape → not manifold



→ intrinsic dimension 1  
(1-manifold)

intrinsic vs embeddly (example: a surface is a 2D object but can be put into 3D)  
↓  
2D, 3D space

can be embedded  
using a bijective function  
(attach a unique continuous coordinate)

① half disk: manifold with boundary



boundary is NOT manifold  $|x| < \epsilon$  &  $x_0 \geq 0$   
(boundary case)

② 1-manifolds can not be embedded in 1D. (true for n-dimensions)  
they are just a bunch of circles

↓  
 $\mathbb{R}^n$  is an open space  
while manifold is "closed"

③ sphere vs disk/ball  
 $|x|=1$   $|x| \leq 1$

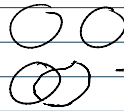
2-sphere is the boundary of 3-disk



→ 2-manifold with boundary

manifold is a special case of manifold with boundary

④ Klein bottle is a 2-manifold but can only be embedded in 4D  
because it does not enclose a space in 3D



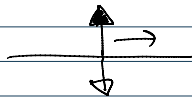
→ can be embedded in 2D



→ same manifold but can only be embedded in 3D

⑤ orientability:

the definition based on normals is bad



walking along the object to see if the normals are flipped

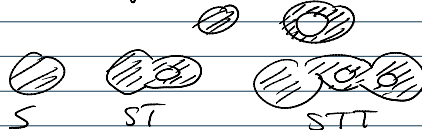
because it depends on embedding

a mobius strip is not orientable

nor any

↪ global property but can be derived locally

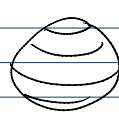
orientable 2-manifold: building blocks are sphere and torus



in 2D:  $\bigcirc$   $\bigcirc \bigcirc$   $\bigcirc \bigcirc \bigcirc$   
c cc ccc

non-orientable 2-manifold: projective plane

...  $c$   $cc$   $cccc$   
 non-orientable 2-manifold: projective plane



cross cap  
 (similar to a disk but is a Möbius strip)

simplest non-orientable 2-manifold: cross cap

— Question: is it possible to make a non-orientable 1-manifold?