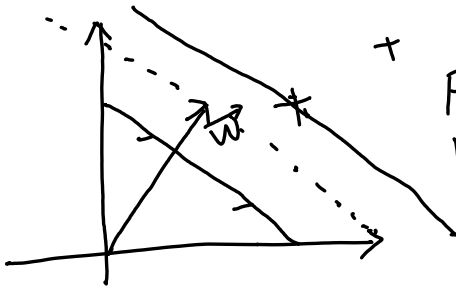


# Support Vector Machines



+ Data points  $\vec{x}_i$   
 Find a "gutter" of maximum width that separates the negative from the positive samples

$\vec{w}$  is the normal vector to the street  
 When we "project" a sample onto  $\vec{w}$ , the length of the projection determines whether the sample is positive or negative

$$(\vec{w} \cdot \vec{x}_+ + b) \geq 1 \text{ for positive samples (1)}$$

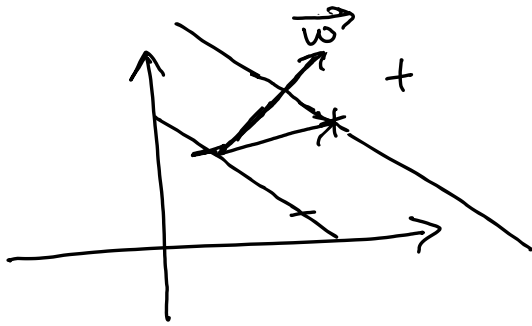
$$(\vec{w} \cdot \vec{x}_- + b) \leq -1 \text{ for negative samples (2)}$$

Invent variables  $y_i = \begin{cases} 1 & \text{for positive samples} \\ -1 & \text{for negative samples} \end{cases}$

So (1)  $\rightarrow y_i (\vec{w} \cdot \vec{x}_i + b) \geq 1$

(2)  $\rightarrow y_i (\vec{w} \cdot \vec{x}_i + b) - 1 = 0$  for samples in the gutter

Decision rule:  $(\vec{w} \cdot \vec{x} + b) \geq 0$  then +  
 else -



The width of the gutter is

$$\frac{\vec{w} \cdot (\vec{x}_+ - \vec{x}_-)}{\|\vec{w}\|}$$

$$= \frac{(1-b - (-1-b))}{\|\vec{w}\|} = \frac{2}{\|\vec{w}\|}$$

To maximize  $\frac{2}{\|\vec{w}\|}$ , we minimize  $\|\vec{w}\|$

or minimize  $\frac{1}{2} \|\vec{w}\|^2$

So the problem becomes:

Minimizing  $\frac{1}{2} \|\vec{w}\|^2$

Condition:  $y_i (\vec{w} \cdot \vec{x}_i + b) - 1 \geq 0$

Use Lagrange multiplier:

Minimize:

$$L = \frac{1}{2} \|\omega\|^2 - \sum d_i [y_i (\vec{\omega} \cdot \vec{x}_i + b) - 1]$$

$$\frac{\partial L}{\partial \vec{\omega}} = \vec{\omega} - \sum d_i y_i \vec{x}_i = 0 \quad (4)$$

$$\frac{\partial L}{\partial d_i} = y_i (\vec{\omega} \cdot \vec{x}_i) + b - 1 = 0 \quad (5)$$

$$\frac{\partial L}{\partial b} = -\sum d_i y_i = 0 \quad (6)$$

Plug (4) into L:

$$L = \frac{1}{2} \left( \sum d_i y_i \vec{x}_i \right) \cdot \left( \sum d_i y_i \vec{x}_i \right) - \sum d_i y_i b + \sum d_i$$

$$= \frac{1}{2} \sum_i \sum_j d_i d_j y_i y_j \vec{x}_i \cdot \vec{x}_j + \sum d_i \quad (7)$$

Plug  $\vec{\omega}$  into the decision rule:

$$\sum d_i y_i \vec{x}_i \cdot \vec{x} + b \geq 0 \text{ then } + \quad (8)$$

In (7), the  $d_i$  are the unknowns  
(7) is a quadratic programming problem  
and can be solved by standard quadratic  
programming packages

It is also convex and can be solved  
with gradient descent

Look at (8):

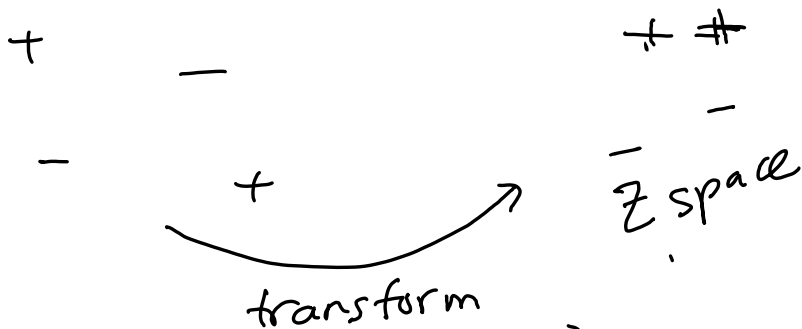
$$\sum d_i y_i \underbrace{\vec{x}_i \cdot \vec{x}}_{\text{(cosine distance)}} + b$$
  
↓  
weighted      ↓  
how "close"  $\vec{x}$  is to  $\vec{x}_i$

↳ to decide whether  $\vec{x}$  is + or -,  
we take a linear combination of the  
distances of  $\vec{x}$  to all the  $\vec{x}_i$ 's.

Ultimately, only some of the  $d_i$ 's will be  
non-zero, the rest are 0. (contribute  
nothing to the decision)

The  $\vec{x}_i$ 's with non-zero  $d_i$ 's are called  
the support vectors

In the linearly inseparable cases :



Call the transform  $\phi$ : take  $\vec{x}_i$ 's to  $Z$  space

Since in (7) :

$$L = \frac{1}{2} \sum \sum d_i d_j y_i y_j \vec{x}_i \cdot \vec{x}_j + \sum d_i$$

$L$  only depends on inner products, so we only need to define a function  $K$

$$K(\vec{x}_i, \vec{x}_j) = \phi(\vec{x}_i) \cdot \phi(\vec{x}_j)$$

dot product in  $Z$  space

Common kernels

$$K: (\vec{x}_i \cdot \vec{x}_j + 1)^n$$

$$\exp\left(\frac{\|\vec{x}_i - \vec{x}_j\|^2}{\lambda}\right)$$

Example: in 2D

$$K(\vec{x}, \vec{x}') = (\vec{x} \cdot \vec{x}' + 1)^2 = (1 + x_1 x_1' + x_2 x_2')^2$$
$$= 1 + x_1^2 x_1'^2 + x_2^2 x_2'^2 + 2x_1 x_1' + 2x_2 x_2' + 2x_1 x_1' x_2 x_2'$$

↓ this is an inner product;

$$(1, x_1^2, x_2^2, \sqrt{2} x_1, \sqrt{2} x_2, \sqrt{2} x_1 x_2)$$

$$(1, x_1'^2, x_2'^2, \sqrt{2} x_1', \sqrt{2} x_2', \sqrt{2} x_1' x_2')$$

additional dimensions

Similar to the case of linear regression where a line is insufficient to model the data

inner product



needs higher order terms, or "features"  
 $x^2, x^3, x^4, \dots$

Example:  $K(\vec{x}, \vec{x}') = \exp(-\|\vec{x} - \vec{x}'\|^2)$

in the case of the dot product kernel:

$$K(\vec{x}, \vec{x}') = \vec{x} \cdot \vec{x}'$$

Consider the decision rule:

$$\sum \alpha_i y_i K(\vec{x}_i, \vec{x}) + b \geq 0$$

From the point of view of generating a field, consider  $\alpha_i, y_i, b$ , and the  $\vec{x}_i$ 's fixed.

then, if  $K(\vec{x}_i, \vec{x}) = \vec{x}_i \cdot \vec{x}$ , this generates a linear field.

If  $K(\vec{x}_i, \vec{x}) = (\vec{x}_i \cdot \vec{x} + 1)^2$ , this generates a quadratic field.

Is  $K(x, x') = \exp(-(|x-x'|)^2)$   
an inner product in some space?

$$\begin{aligned} K(x, x') &= \exp(-(x-x')^2) \\ &= \exp(-x^2) \exp(-x'^2) \exp(2xx') \\ &= \exp(-x^2) \exp(-x'^2) \sum_{k=0}^{\infty} \frac{2^k (x)^k (x')^k}{k!} \end{aligned}$$



Taylor series  
Infinite dimensional space



Valid kernels.

- Is symmetric

$$\text{i.e. } K(\vec{x}, \vec{x}') = K(\vec{x}', \vec{x})$$

since the inner product is symmetric

- Matrix

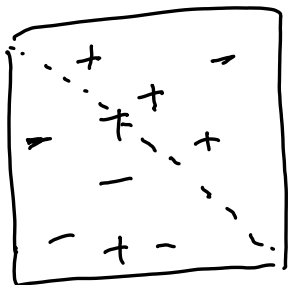
$$M = \begin{bmatrix} K(x_1, x_1) & K(x_1, x_2) & \dots & K(x_1, x_N) \\ K(x_2, x_1) & K(x_2, x_2) & \dots & K(x_2, x_N) \\ \dots & \dots & \dots & \dots \\ K(x_N, x_1) & K(x_N, x_2) & \dots & K(x_N, x_N) \end{bmatrix}$$

is positive semi-definite

( $\geq 0$  in matrix lingo)

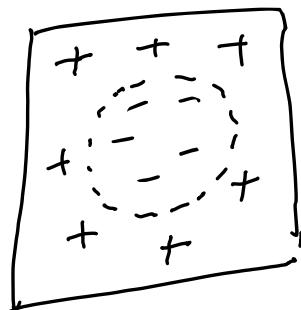
$$x^T M x \geq 0 \quad \forall x$$

# Soft SVM



some outliers

↓  
don't want kernel to overfit data



linearly non-separable

↓  
needs kernel



Allow some error:

$$y_i (\vec{w} \cdot x_i + b) \geq 1 - \epsilon_i \quad (\epsilon_i \geq 0)$$

before:  $y_i (\vec{w} \cdot x_i + b) \geq 1$

We want to minimize the total

violation:  $\sum_{i=1}^n \epsilon_i$

New optimization:

$$\frac{1}{2} \|\vec{w}\|^2 + C \sum \epsilon_i$$

subject to

$$y_i (\vec{w} \cdot x_i + b) \geq 1 - \epsilon_i$$

$$\epsilon_i \geq 0$$

Lagrange multiplier:

$$L = \frac{1}{2} \|\vec{w}\|^2 + C \sum \epsilon_i - \sum \alpha_i (y_i (\vec{w} \cdot \vec{x}_i) + b - 1 + \epsilon_i) - \sum \beta_i \epsilon_i$$

Minimize with respect to

$$\vec{w}, b, \epsilon_i$$

and maximize with respect to

$$\alpha_i \text{ and } \beta_i$$

$$\frac{\partial L}{\partial \vec{w}} = \vec{w} - \sum \alpha_i y_i \vec{x}_i = 0 \quad \text{like before}$$

$$\frac{\partial L}{\partial b} = - \sum \alpha_i y_i = 0$$

like before

$$\frac{\partial L}{\partial \epsilon_i} = C - \alpha_i - \beta_i = 0$$

different from  
before

$$\downarrow$$

Since  $\beta_i \geq 0$ ,  $\alpha_i \leq C$ .

So, maximize

$$L(\vec{\alpha}) = \sum \alpha_i - \frac{1}{2} \sum \sum y_i y_j \alpha_i \alpha_j \vec{x}_i \cdot \vec{x}_j$$

subject to  $0 \leq \alpha_i \leq C$



