## Advanced Data Visualization **CS 6965** Spring 2018 Prof. Bei Wang Phillips University of Utah





# Mapper, Clustering & beyond

HD



# The Mapper Algorithm: **History and Overview**

A tool for high-dimensional data analysis and visualization

### History of mapper algorithm

At the core of at least two data analysis startups:

visualization https://www.ayasdi.com/

Alpine Data: (topological) data analysis at scale, http://alpinedata.com/

- Ayasdi: topological data analysis, machine learning and

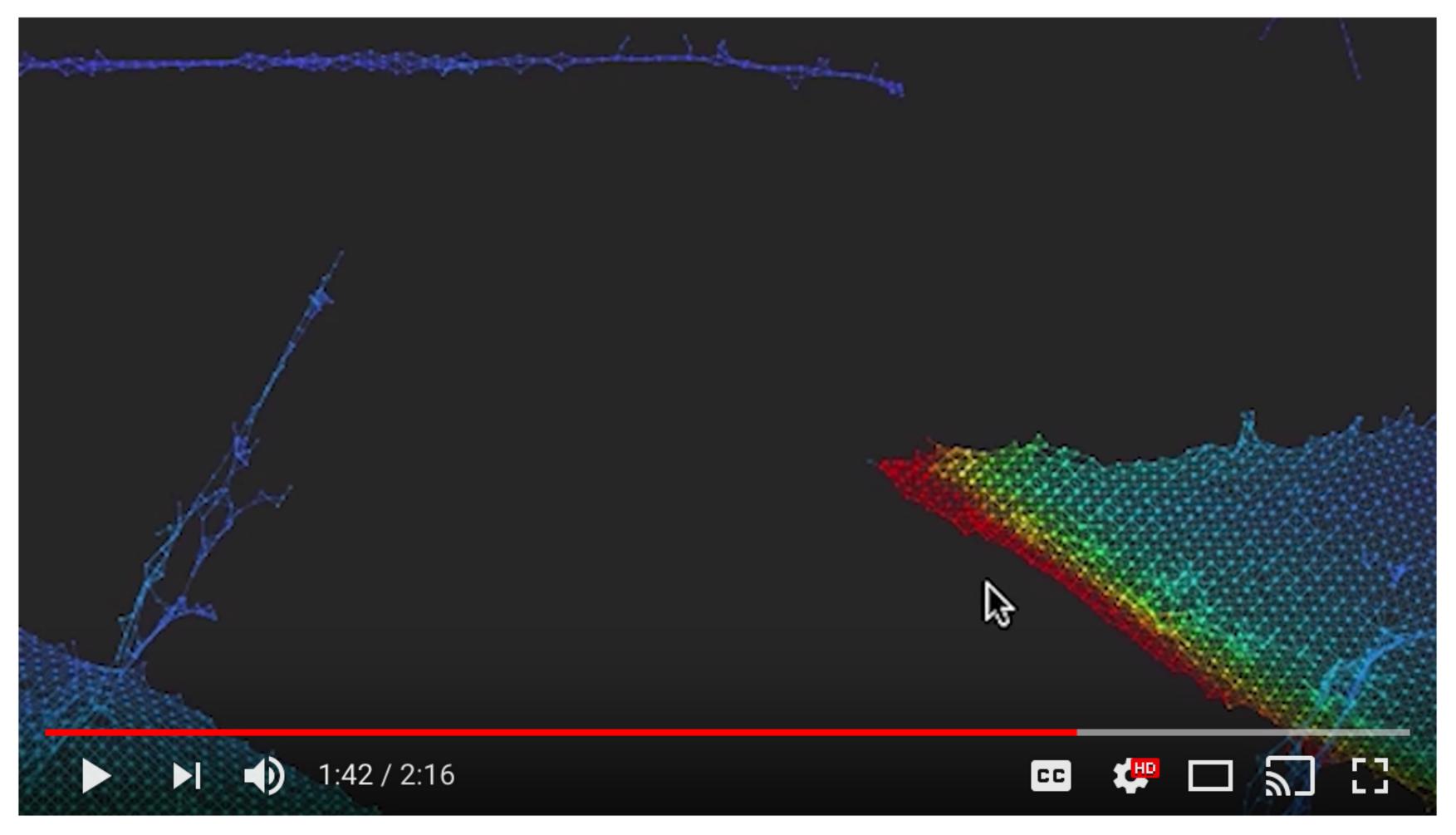




### Ayasdi

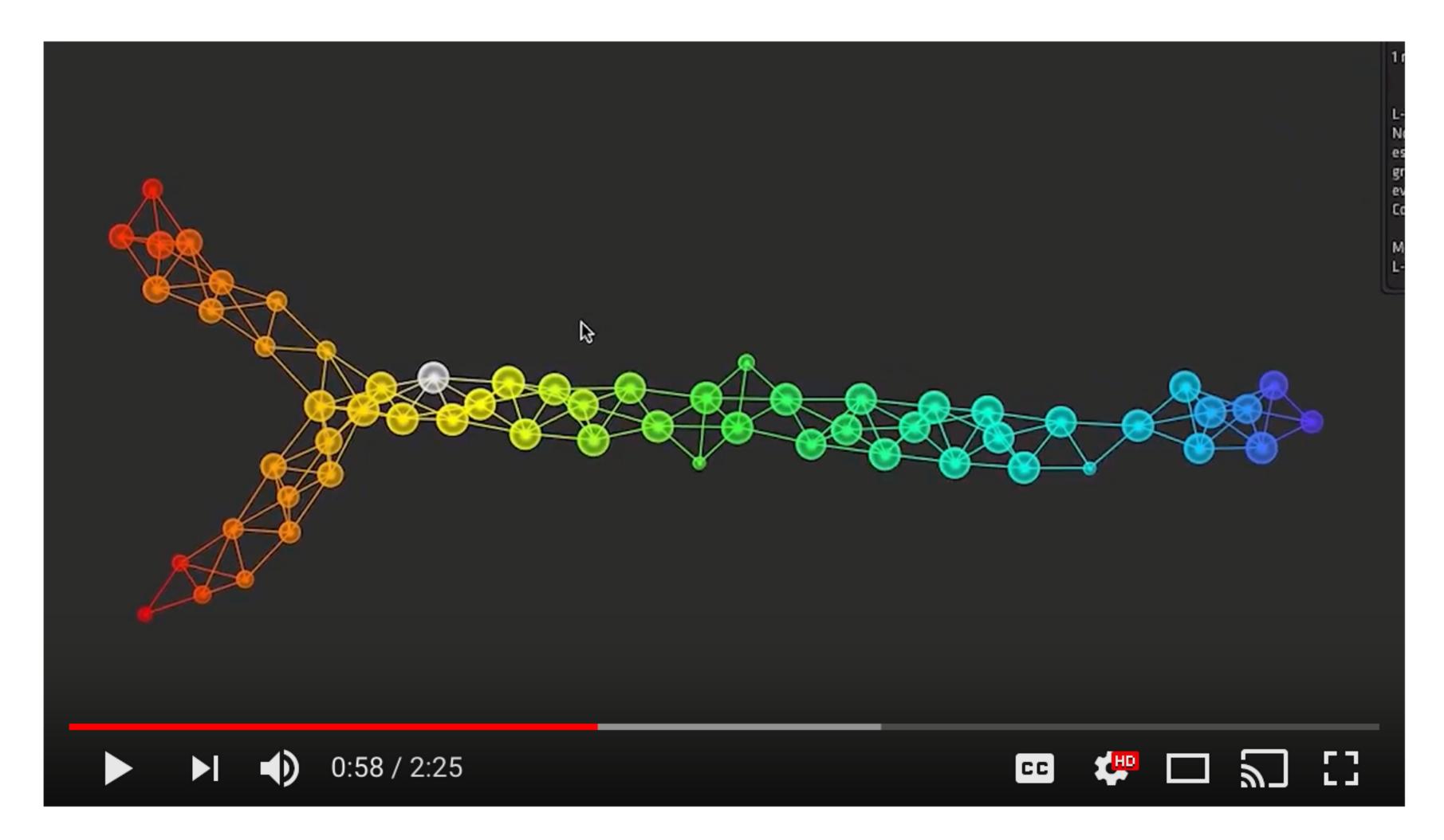
### https://www.youtube.com/watch?v=XfWibrh6stw

### Ayasdi: Fraud detection



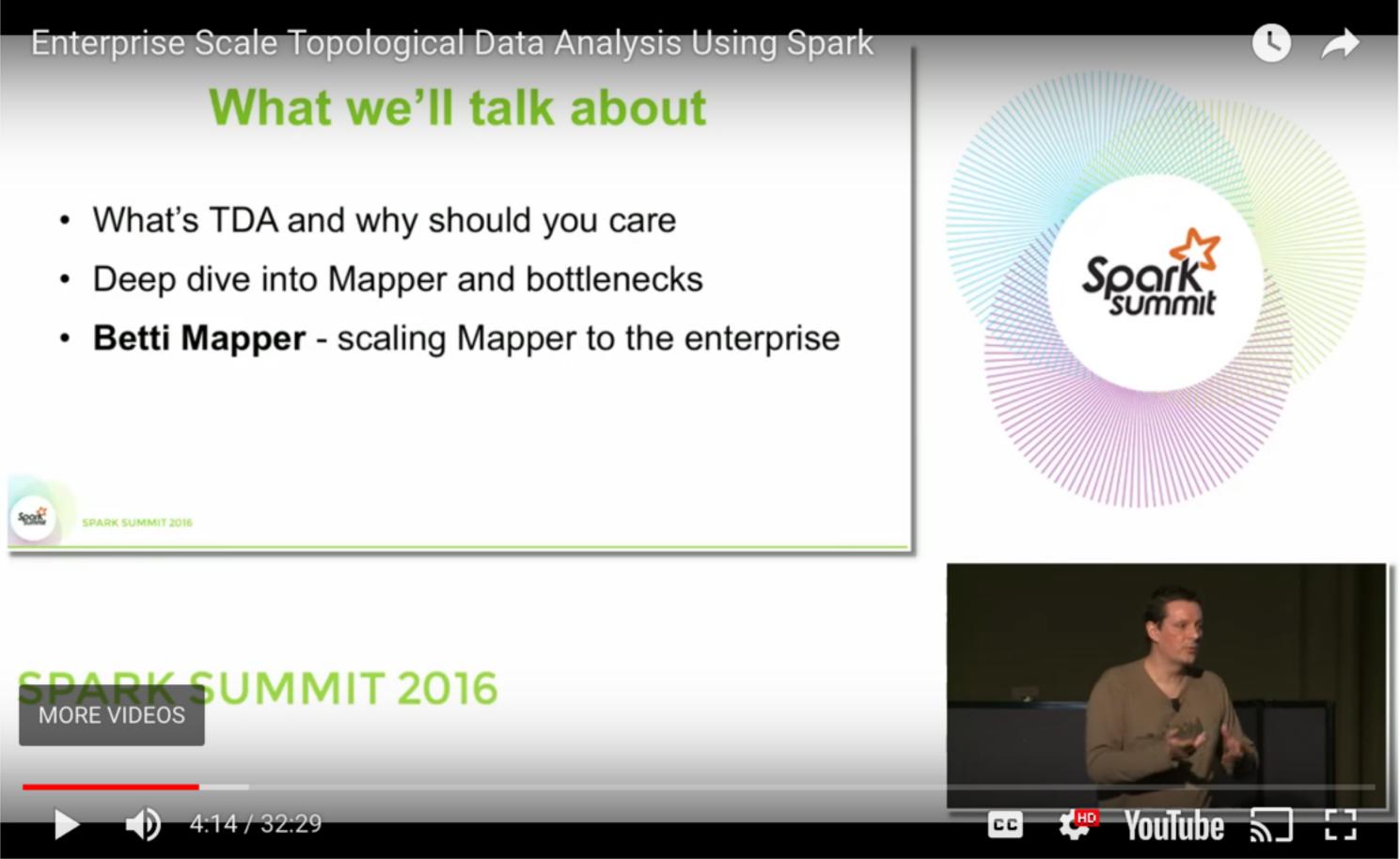
https://www.youtube.com/watch?v=L8o4an5nh4E

### Ayasdi: Patient Stratification



https://www.youtube.com/watch?v=FmflJ3-Uual

### Alpine Data



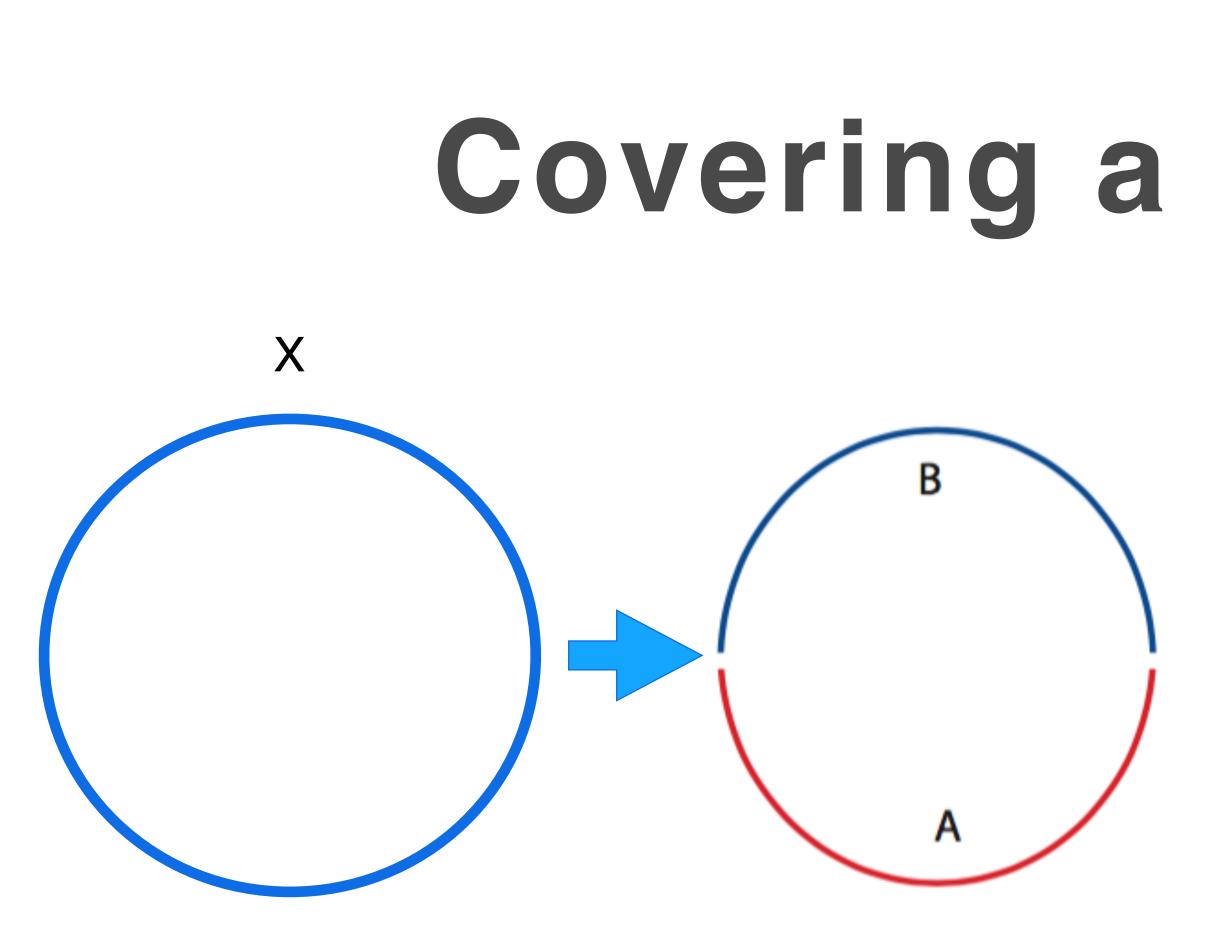
https://databricks.com/session/enterprise-scale-topological-data-analysis-using-spark

## Mapper Algorithm and Visualization

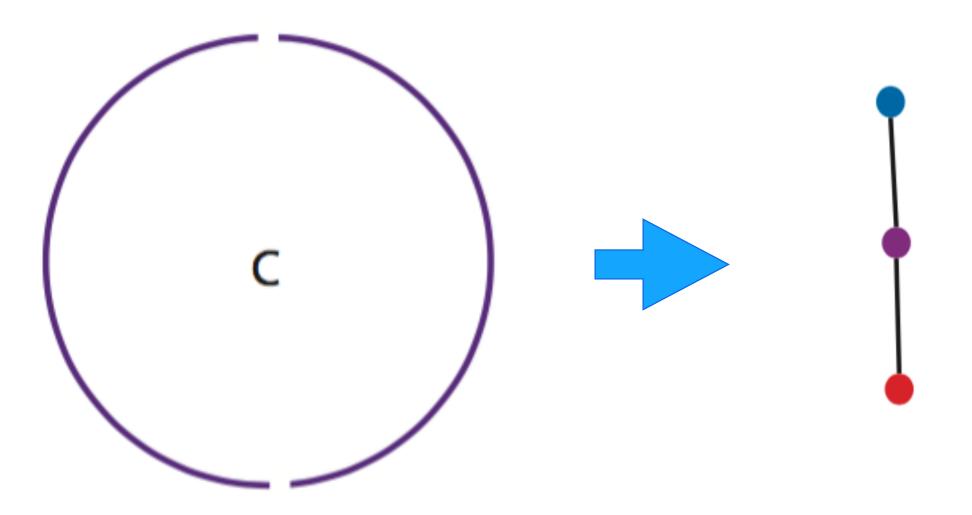
- A qualitative understanding of high-dim point cloud data through direct visualization
- Combining DR with graph visualization
- Obsirable properties of visualization for high-dimensional data Insensitive to metric (approximation to similarity): robust to small changes to the metric
  - summary of behavior under all choices of parameters, exploratory
  - Output Understanding sensitivity to parameter changes: provide useful Multi-scale representation: at various levels of resolution, comparison
- "Features which are seen at multiple scales will be viewed as more likely to be actual features as opposed to more transient features which could be viewed as artifacts of the imaging method."

[Carlsson2009]





### **Covering a circle by sets**

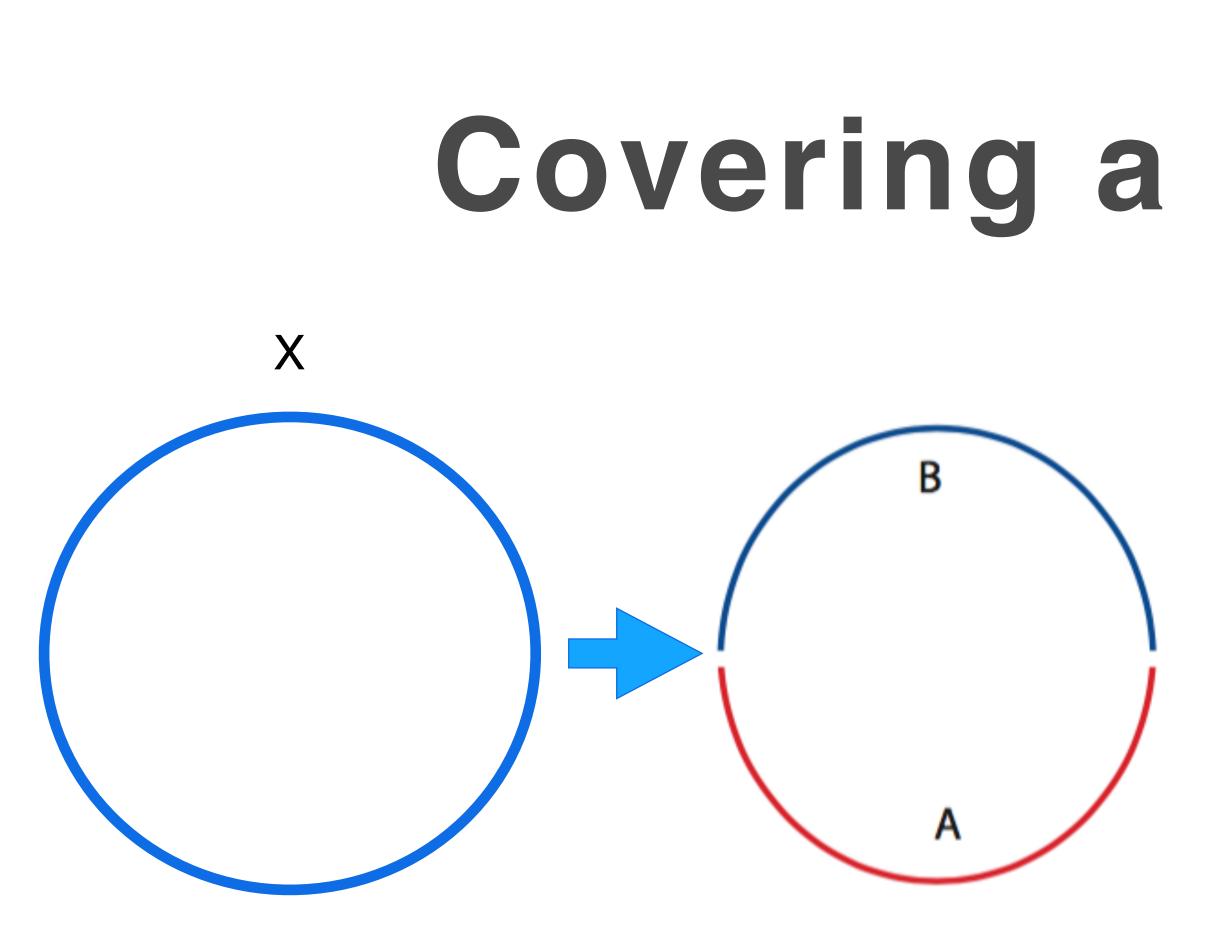


The abstraction of set relations based on overlaps of sets

**Example.** Let X denote the unit circle, and let a covering  $\mathcal{U}$  of X be given by the three sets  $A = \{(x, y) \mid y < 0\}, B = \{(x, y) \mid y > 0\}, \text{ and } C = \{(x, y) \mid y \neq \pm 1\}.$ 

[Carlsson2009]





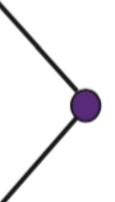
### **Covering a circle by sets**

The abstraction of set relations based on overlaps among connected components of the set (Nerve, roughly speaking)

**Example.** Let X denote the unit circle, and let a covering  $\mathcal{U}$  of X be given by the three sets  $A = \{(x, y) \mid y < 0\}, B = \{(x, y) \mid y > 0\}, \text{ and } C = \{(x, y) \mid y \neq \pm 1\}.$ 

[Carlsson2009]

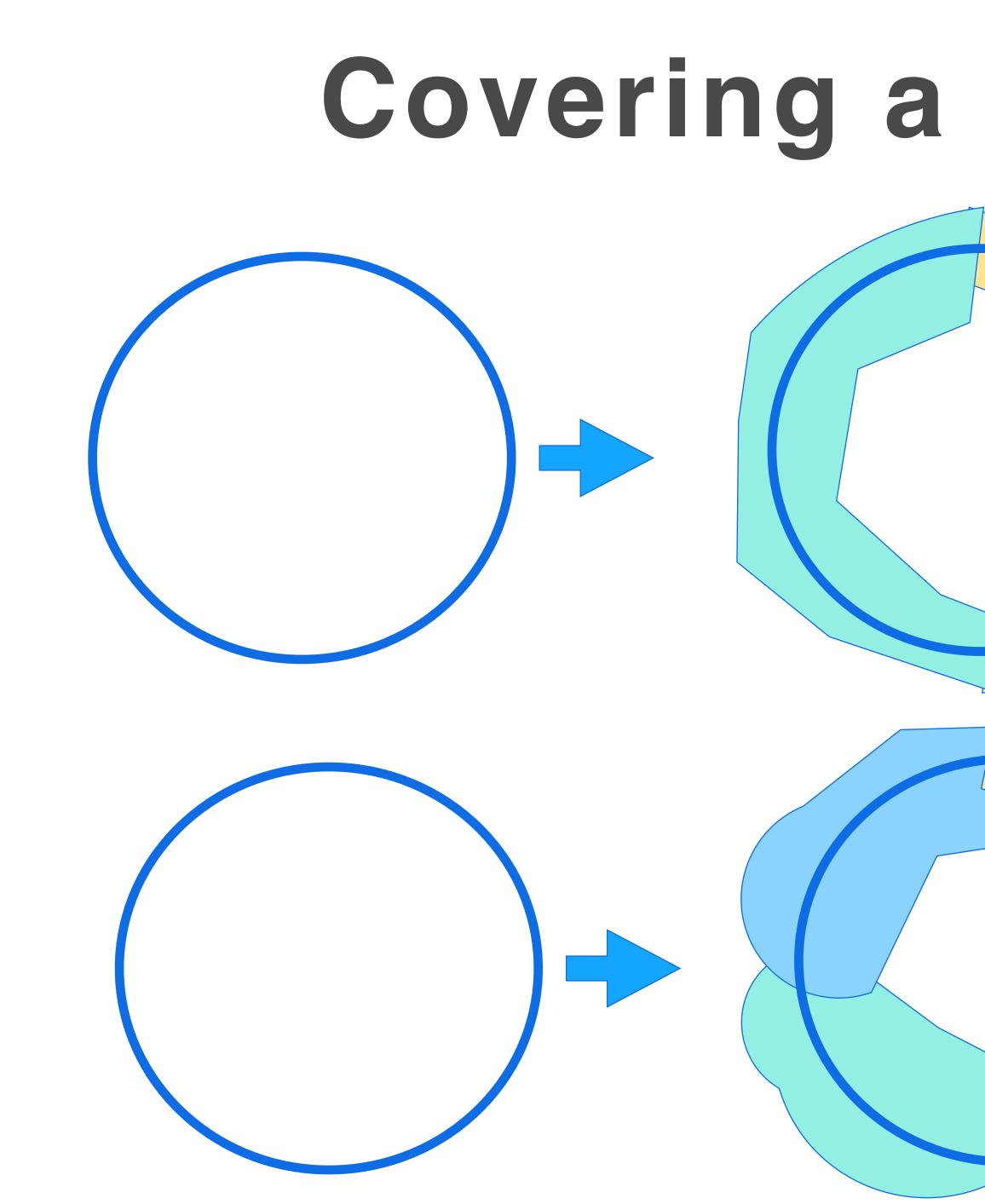




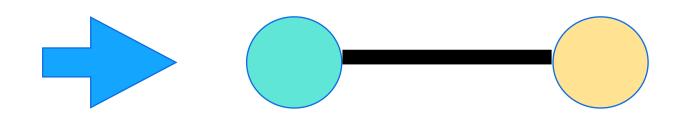


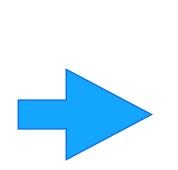


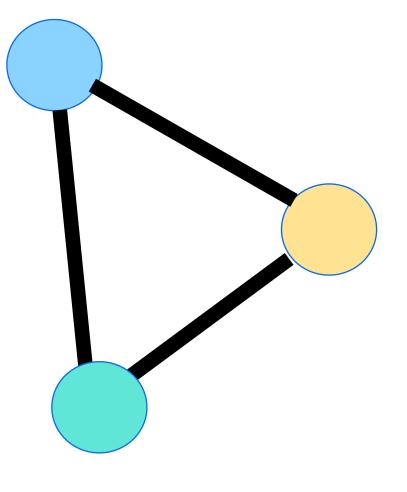




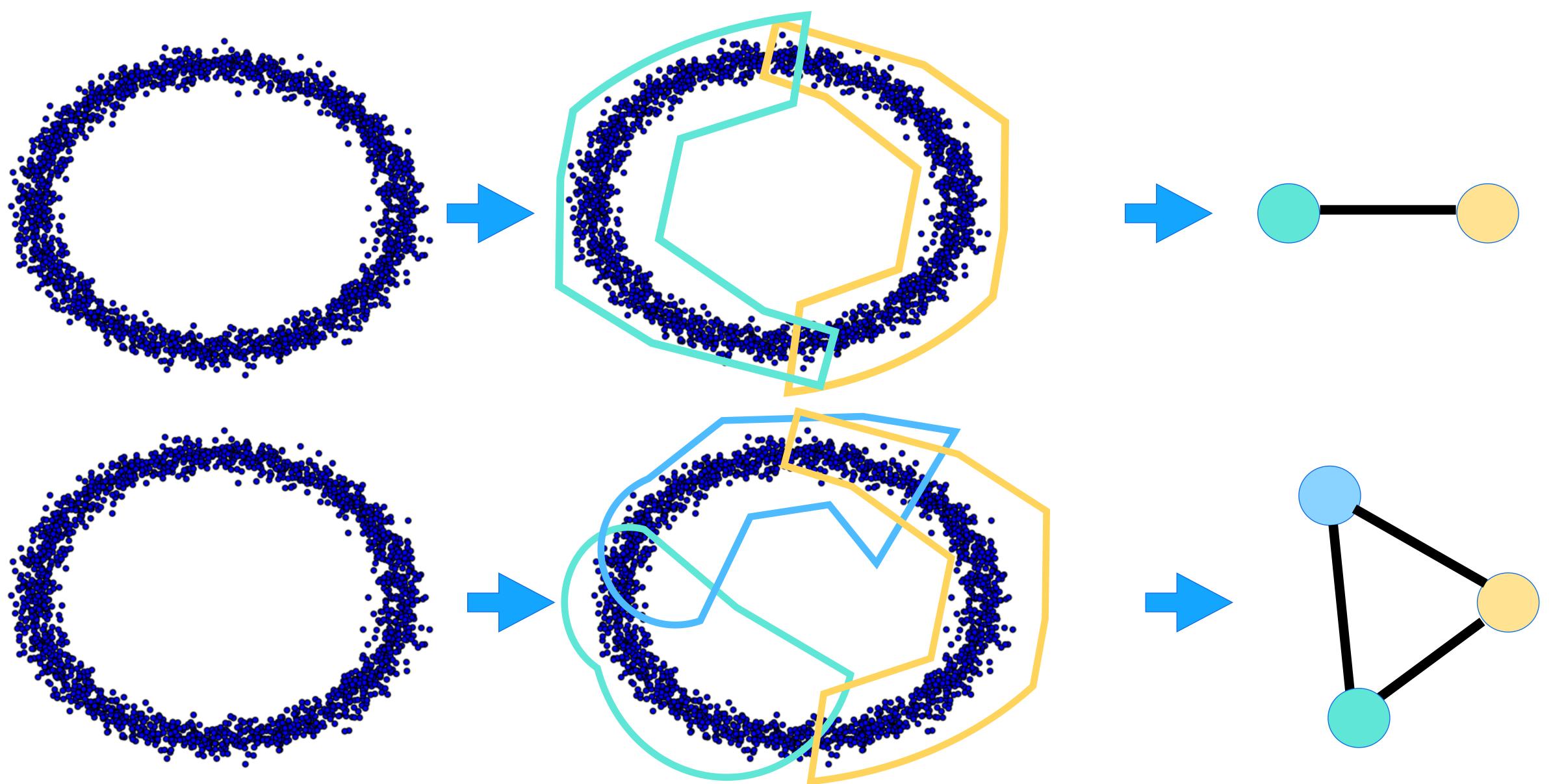
### Covering a circle by sets



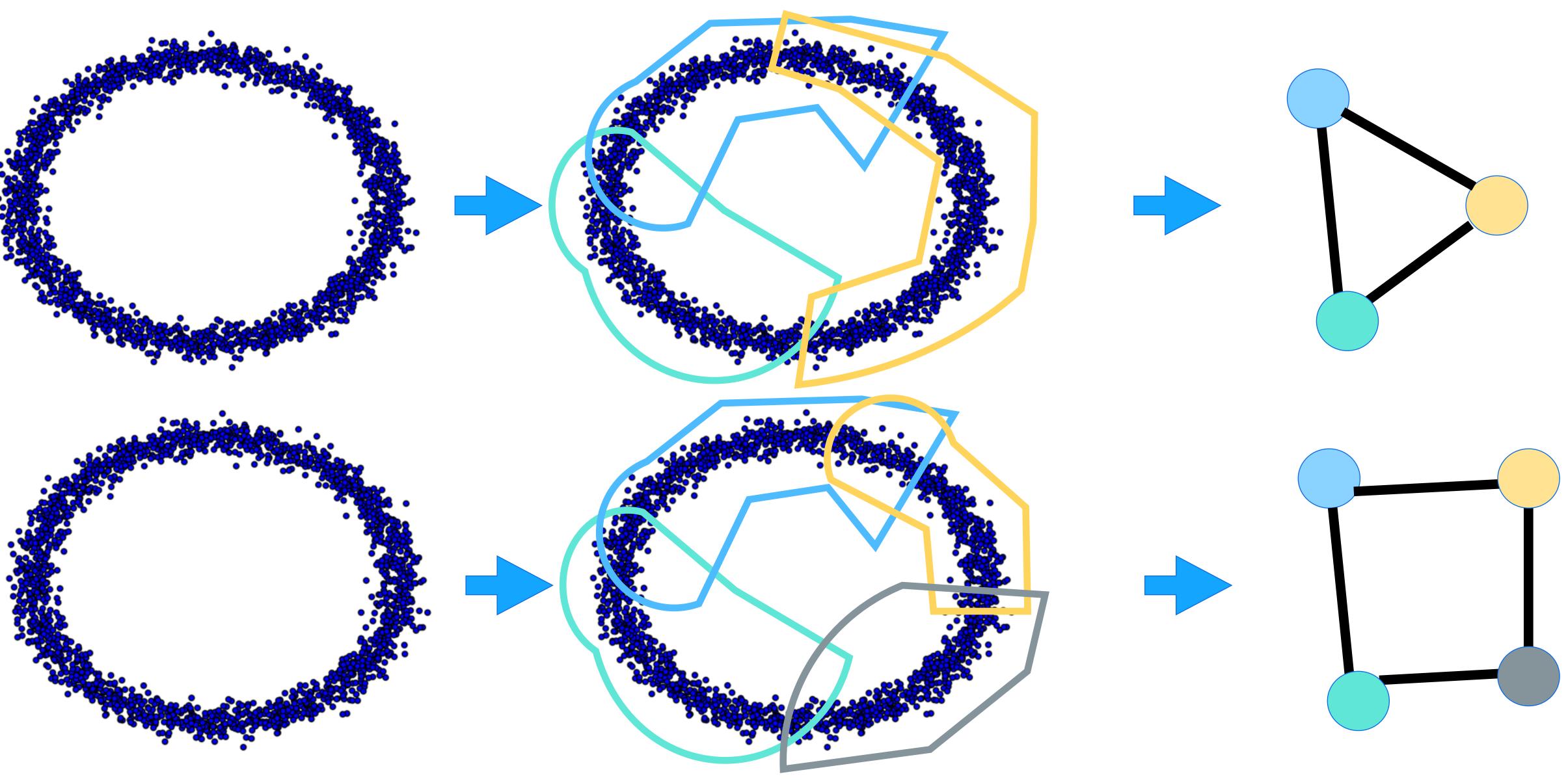




### Point cloud data: soft clustering



### Change of scale



### Covering of a point cloud

Given point cloud data and a covering...
 Taking the nerve of the covering can sometimes capture the shape of the data at the right scale(s)

## Mapper Algorithm at a Glance

dimensional data sets and functions on these data sets: graphs

- Function-induced clustering: partial clustering of the data guided by a set of functions defined on the data.
- Flexibility: any clustering algorithm may be used with Mapper.
- Exploratory and multi-scale: explore parameters at all scales if possible.

- Qualitative analysis, simplification and visualization of high-
- Data summarization/skeletonization: Extracting simple descriptions
  of high dimensional data sets in the form of simplicial complexes or

# Mapper Algorithm: Core

A main algorithm



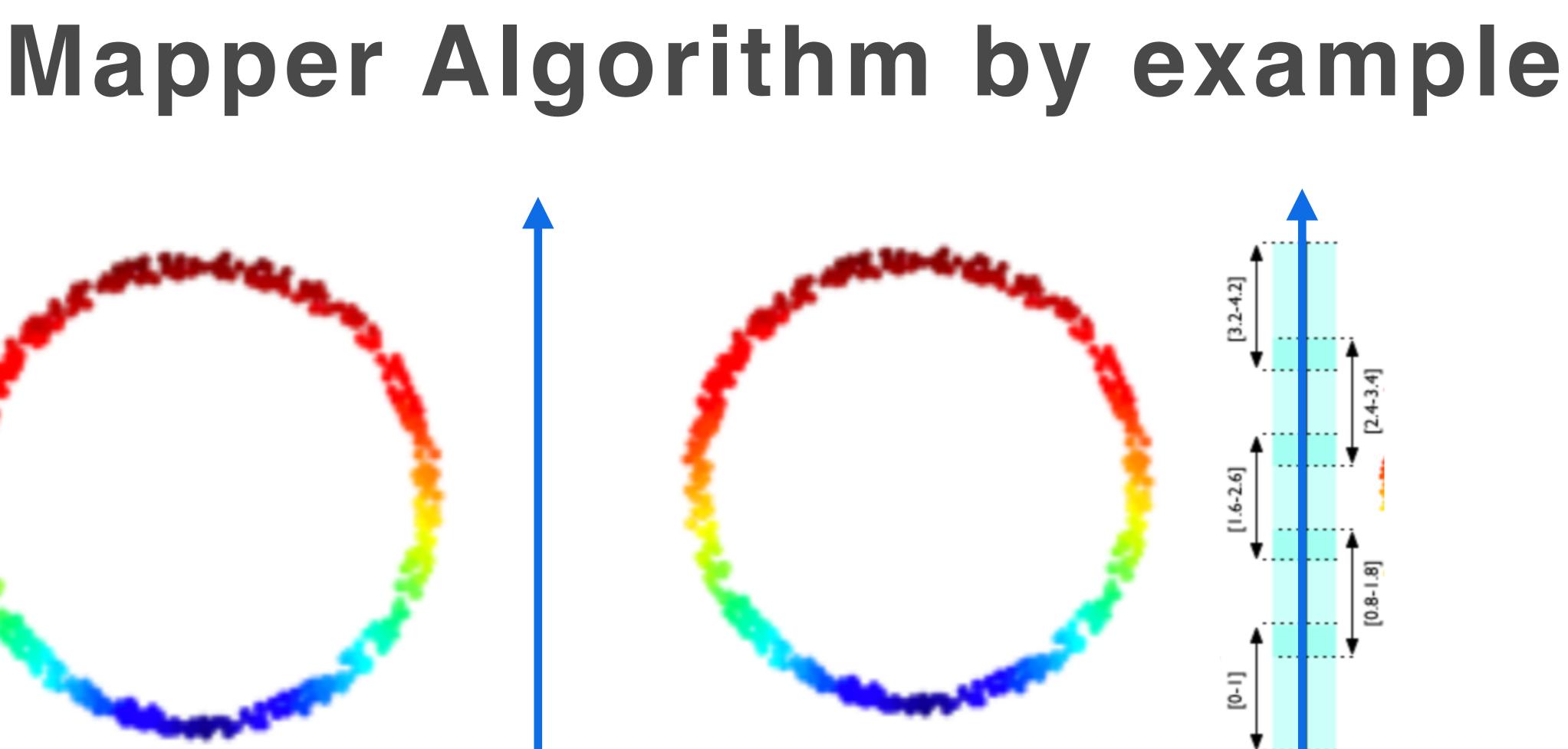


- Input:
  - Point cloud data, distance metric on the point cloud
  - Functions on the point cloud: filter function/lens
- Output:
  - simplicial complex based on function-induced clustering
  - algorithms
- Parameters:
  - Parameters related to the chosen clustering algorithms
  - Filter functions
  - Number of intervals
  - Amount of interval overlap
  - Color functions, etc.

### Mapper I/O, implementation

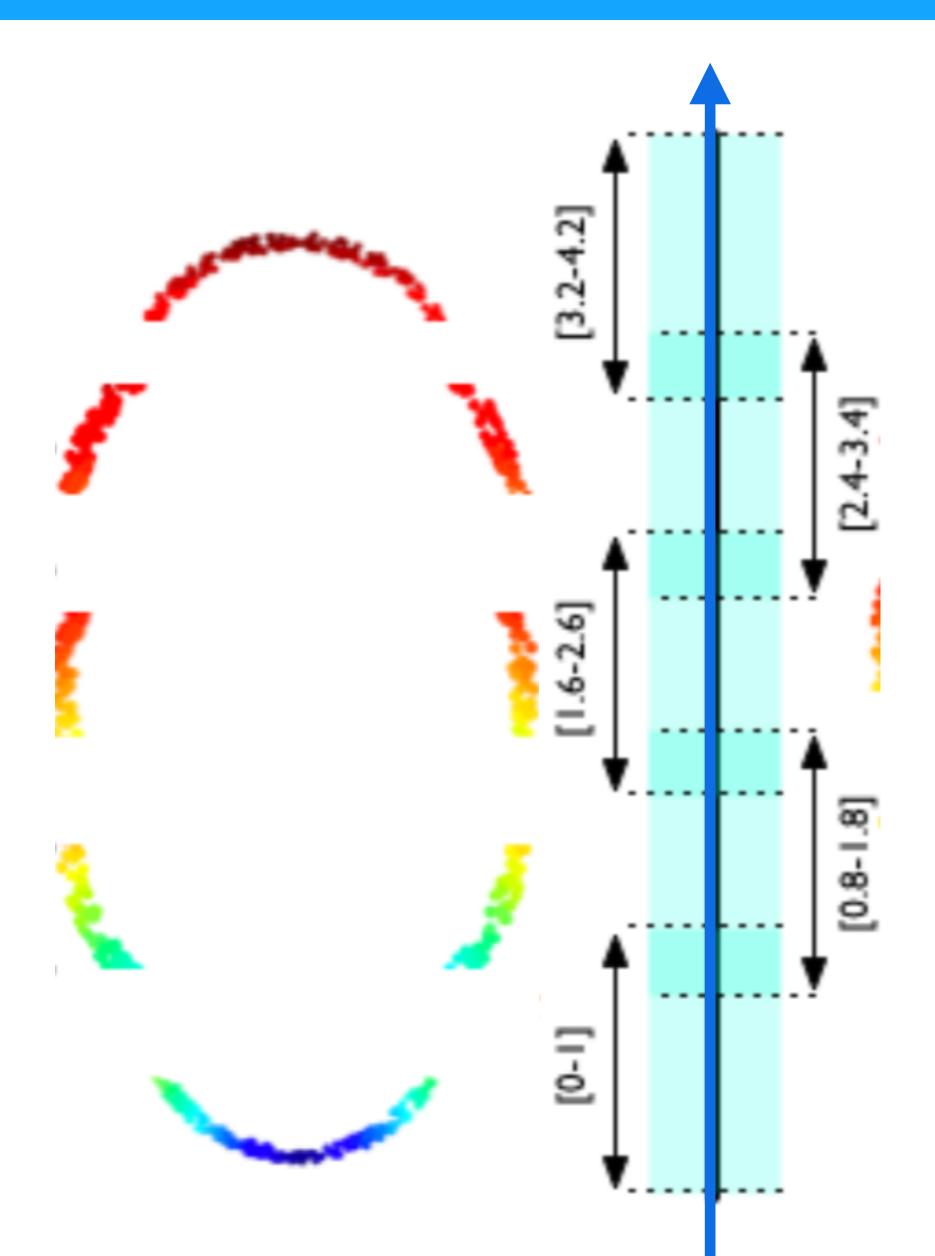
Interactive) visualization of a summary of the data as a graph or a Operation of the statistic of the sta

1. Input: a point cloud with a filter function e.g., a height function. Also assume that there is a distance (metric) defined between any two points in the point cloud.

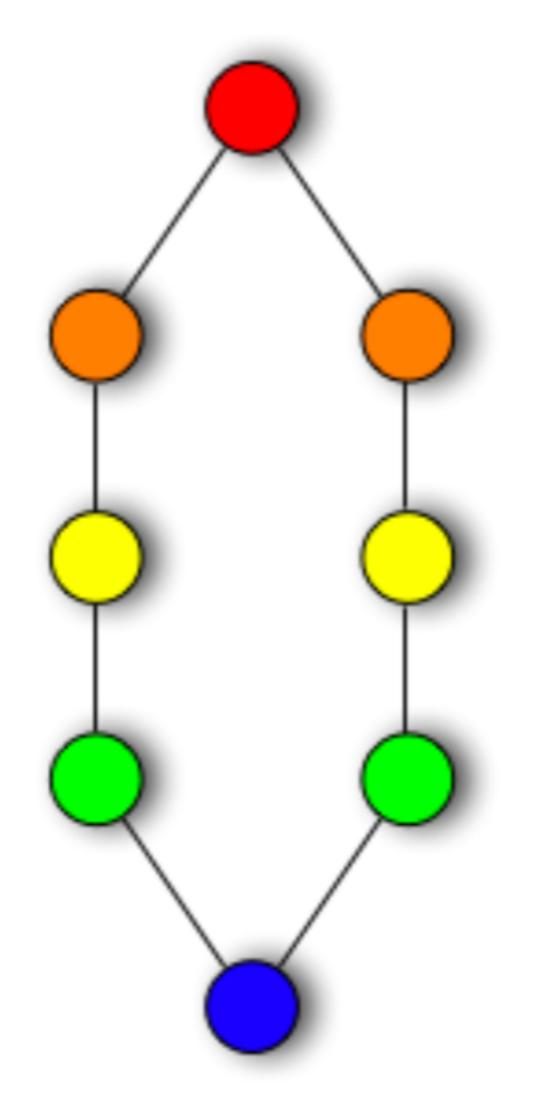


2. Cover the range of the function with intervals: using # of intervals, and amount % of overlap as parameters.

E.g., # of intervals = 5, overlap = 25%.



3. Look at the points in the domain that falls into each interval, and apply clustering to these points. E.g., following the inverse map.



4.Obtaining the nerve of all clusters (a covering) in the domain. E.g., here it is a graph representation that summarizes the data.

Such a graph can interface with machine learning and interactive visualization...



### Clustering

- Almost any clustering algorithm can be used
- point cloud setting
- Commonly used clustering algorithms:
  - (DBSCAN)
  - Single-linkage clustering
  - K-means, etc.
- Desirable properties:

Assume there is a notion of distance (metric) between a pair of points in the data domain (distance can be computed or provided) Clustering is equivalent to a notion of connected component in the

Opensity-based spatial clustering of applications with noise

Not restricted to Euclidean distance; can take distance matrix input Do not require specifying the number of clusters beforehand

### Parameters for the covering

Number of intervals: k

- Increasing k will increase the # of clusters we observe
- cluster)
- Finer features of the data
- If density varies, pick up clusters with high density
- Percentage of overlap: p

  - Sometimes robust in dealing with noise

May create more empty clusters (small number of points per

Increasing p will increase the connectivities among the clusters

### Filter functions

- A filter function can be given a prior, e.g. car purchasing price
- - Density estimation
  - Eccentricity
  - Distance to a point in the data
  - Graph laplacians

### It can also be derived from the properties of the point cloud itself

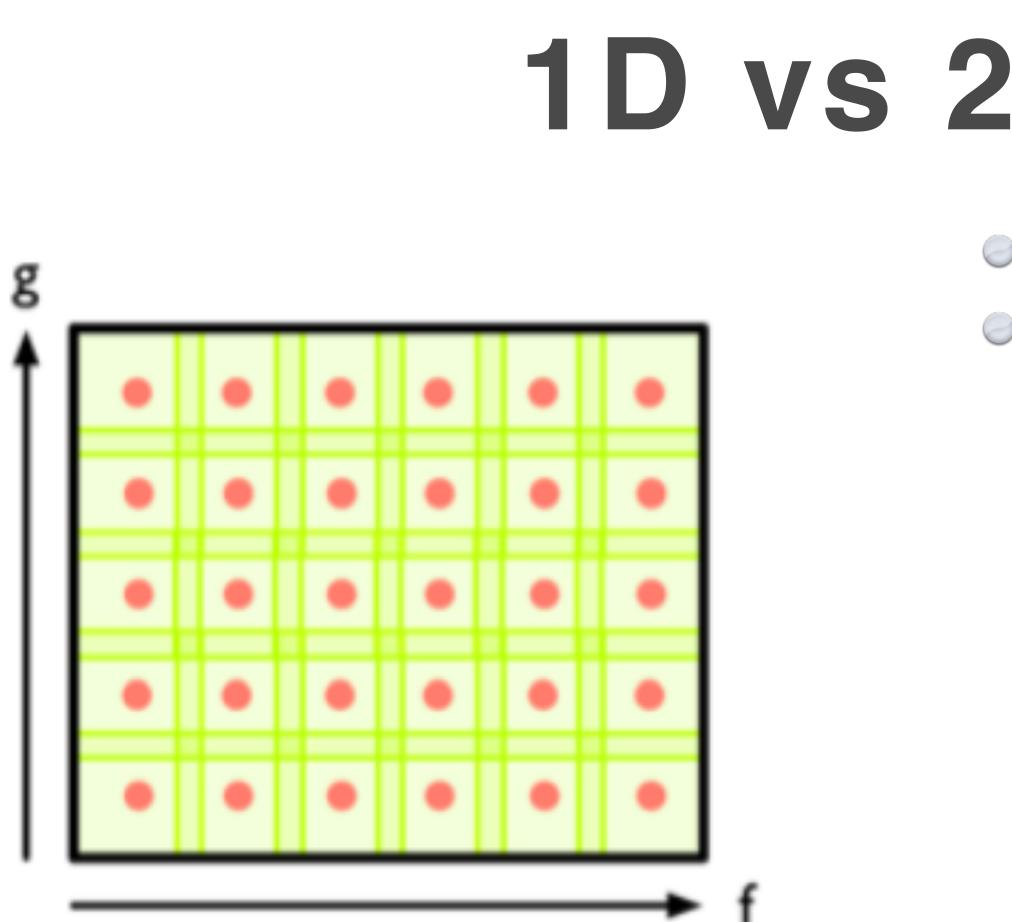
### Filter functions

Density:  $f_{\varepsilon}(x) = C_{\varepsilon} \sum_{v} c_{\varepsilon}$ 

Eccentricity  $E_p(x) = \left(\sum_{n=1}^{\infty} E_n(x)\right)$ 

$$\exp\left(\frac{-d(x,y)^2}{\varepsilon}\right)$$

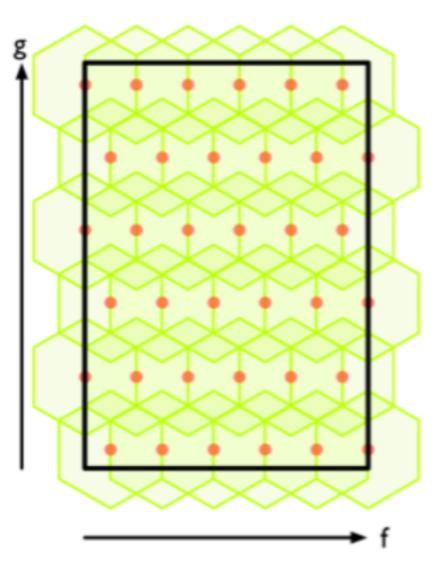
$$\frac{\sum_{y\in X}d(x,y)^p}{N}\right)^{\frac{1}{p}}$$



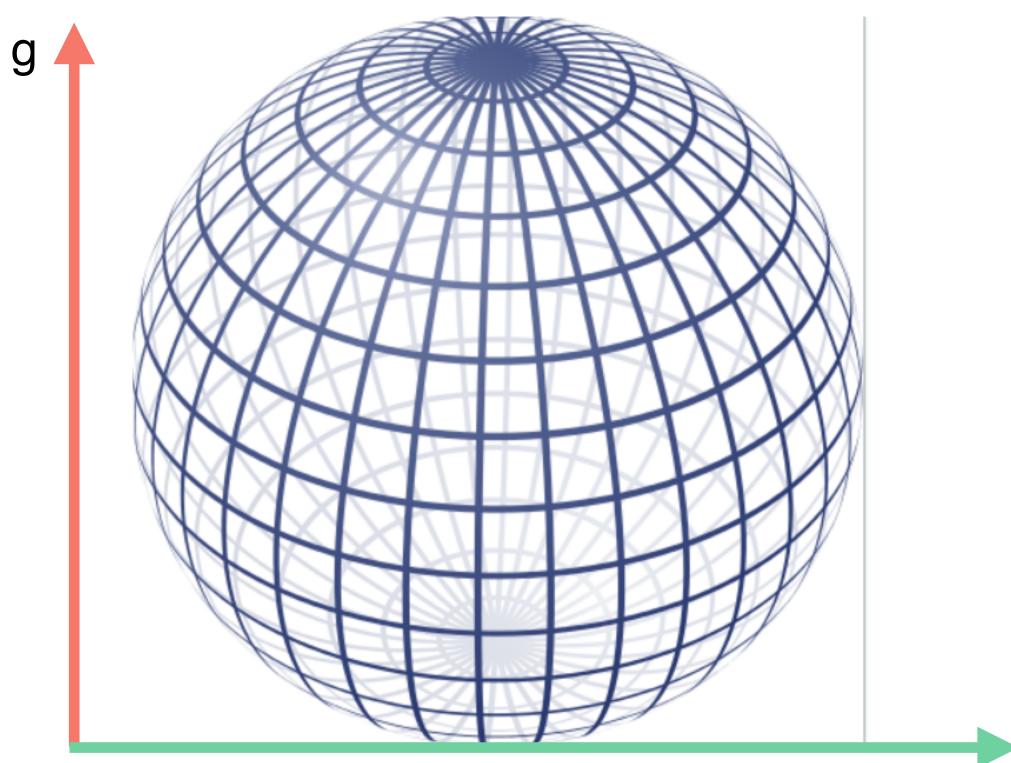
## 1D vs 2D Mapper

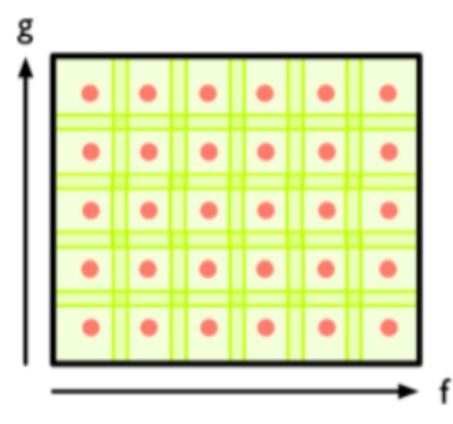
- ID Mapper: a single filter function
- O 2D Mapper: 2 filter functions
  - The covering of the domain of the function is no longer by intervals Instead, by rectangles or other geometric

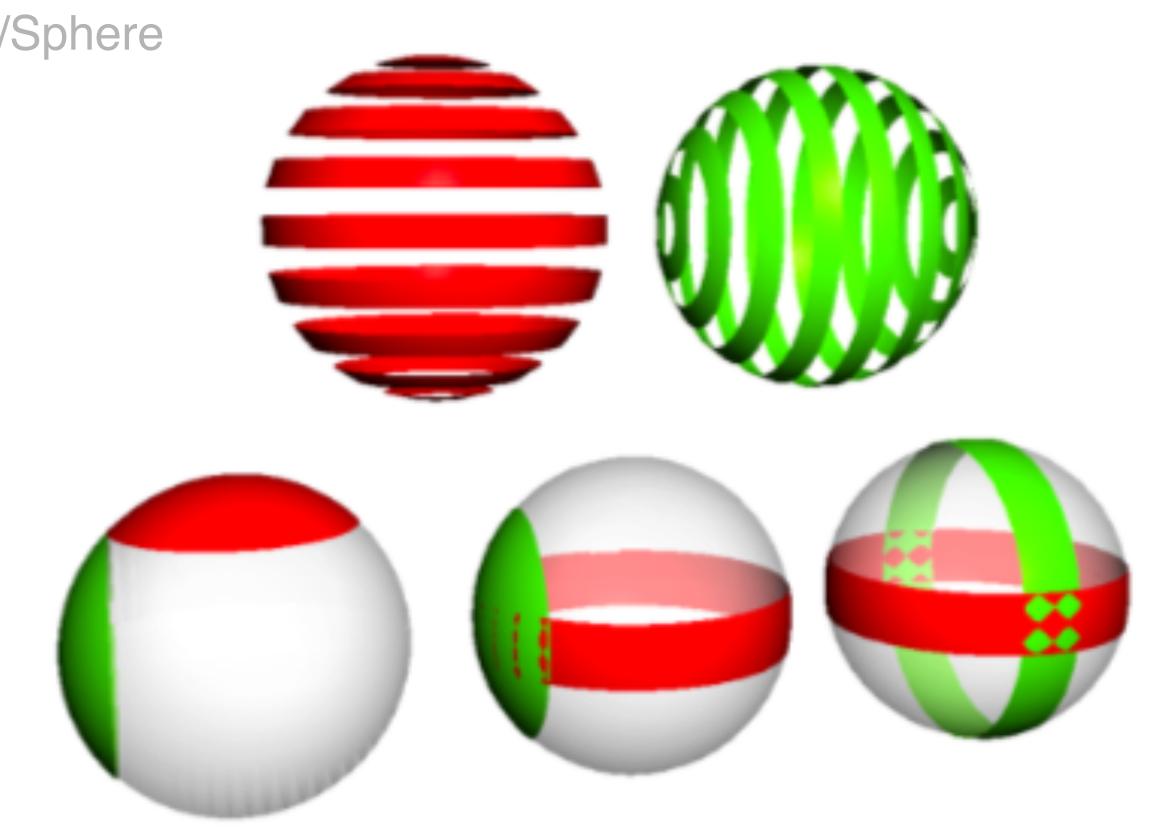
shapes, etc.

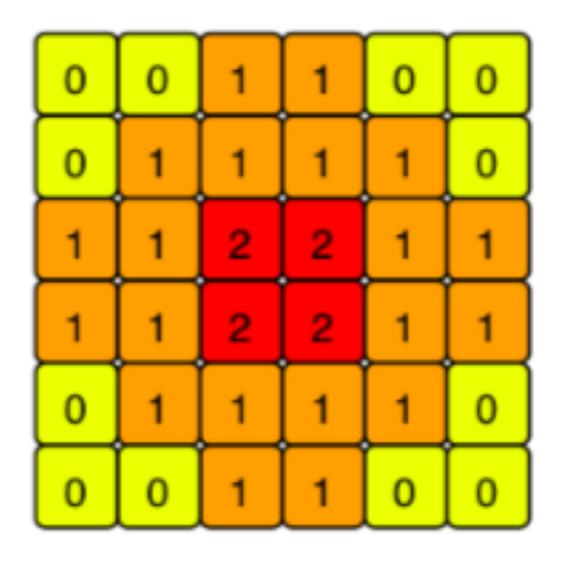


### https://en.wikipedia.org/wiki/Sphere 2D Mapper









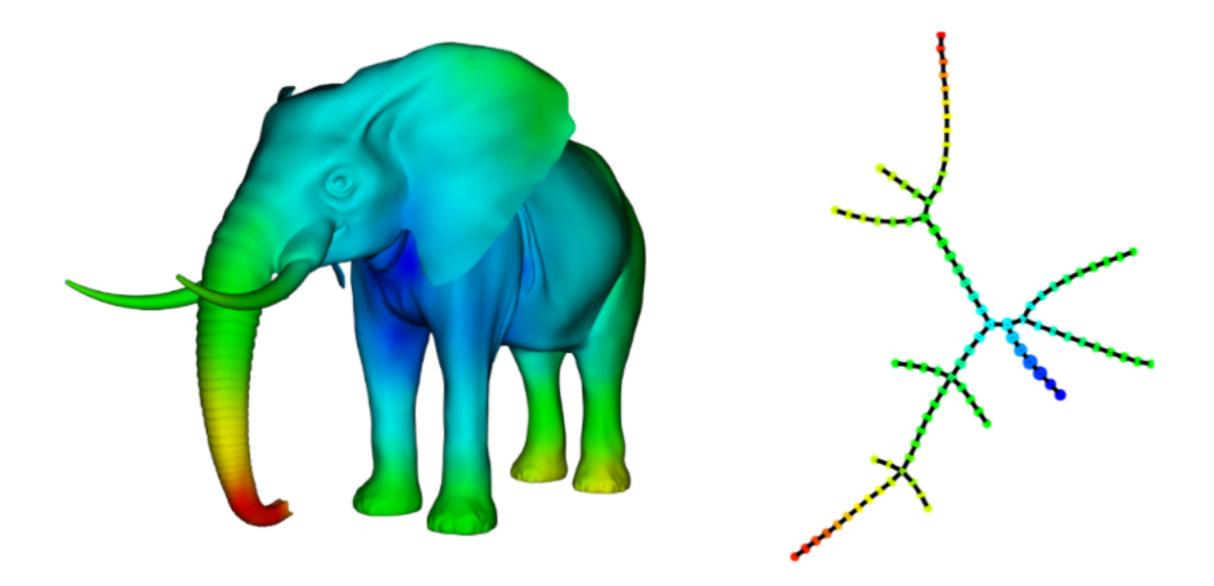
Count the number of connected components per "2D interval" (square in the range)



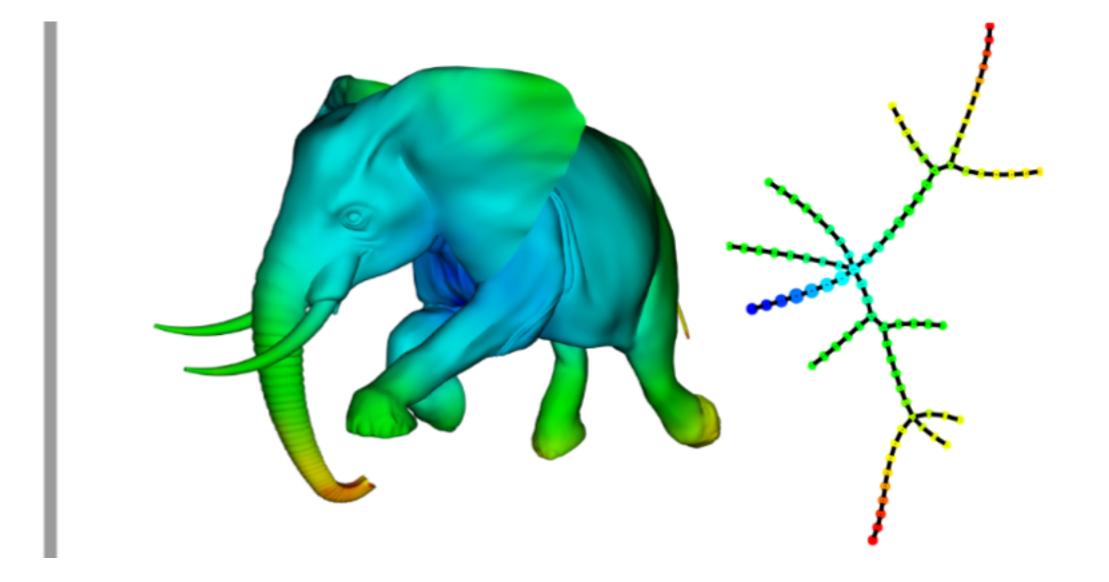
# Mapper Algorithm: Applications

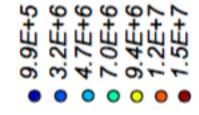
A few examples

### Shape skeletonization & classification



Also see Kepler Mapper demo examples: cat, lion, horse...





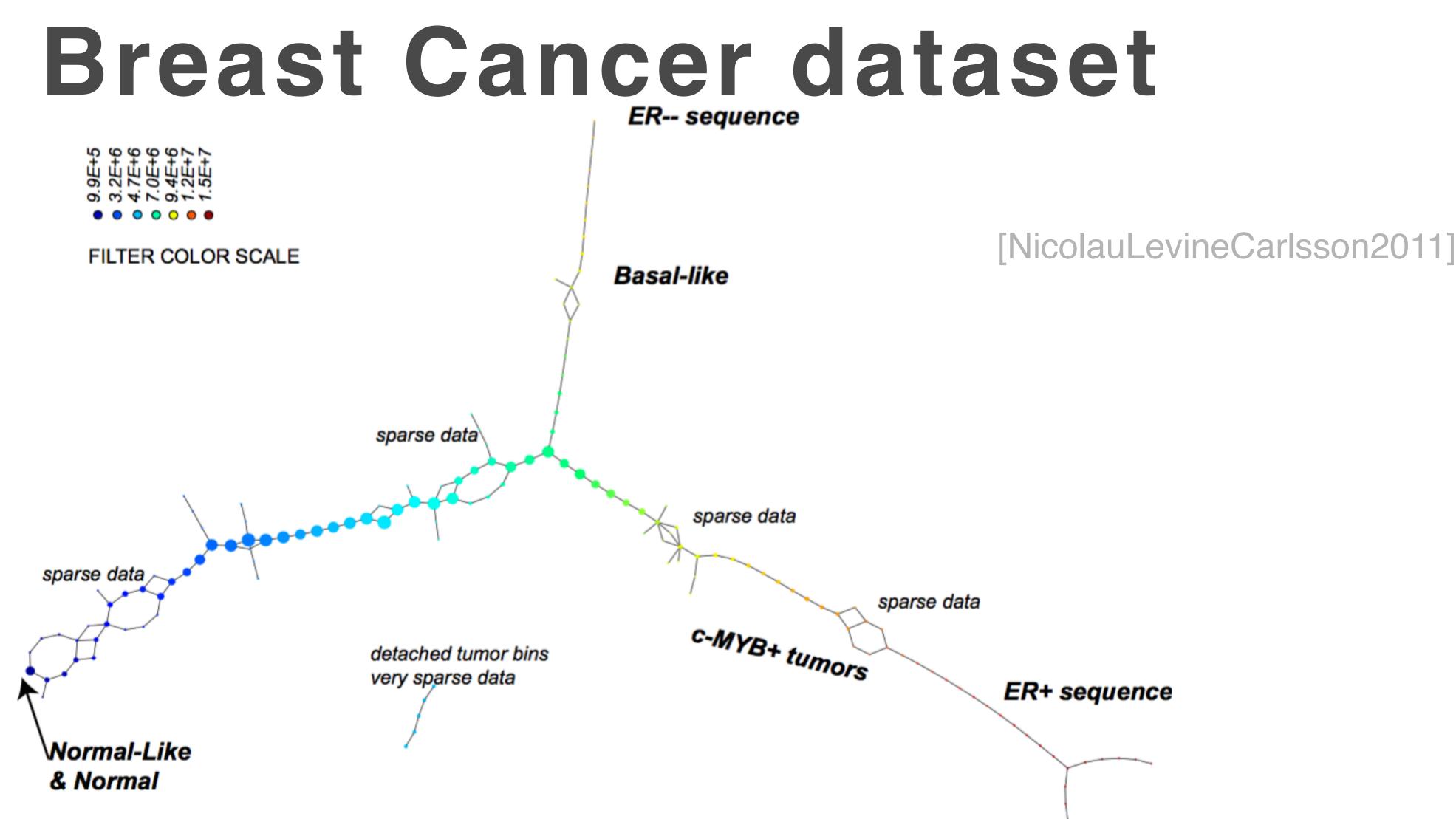
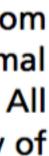
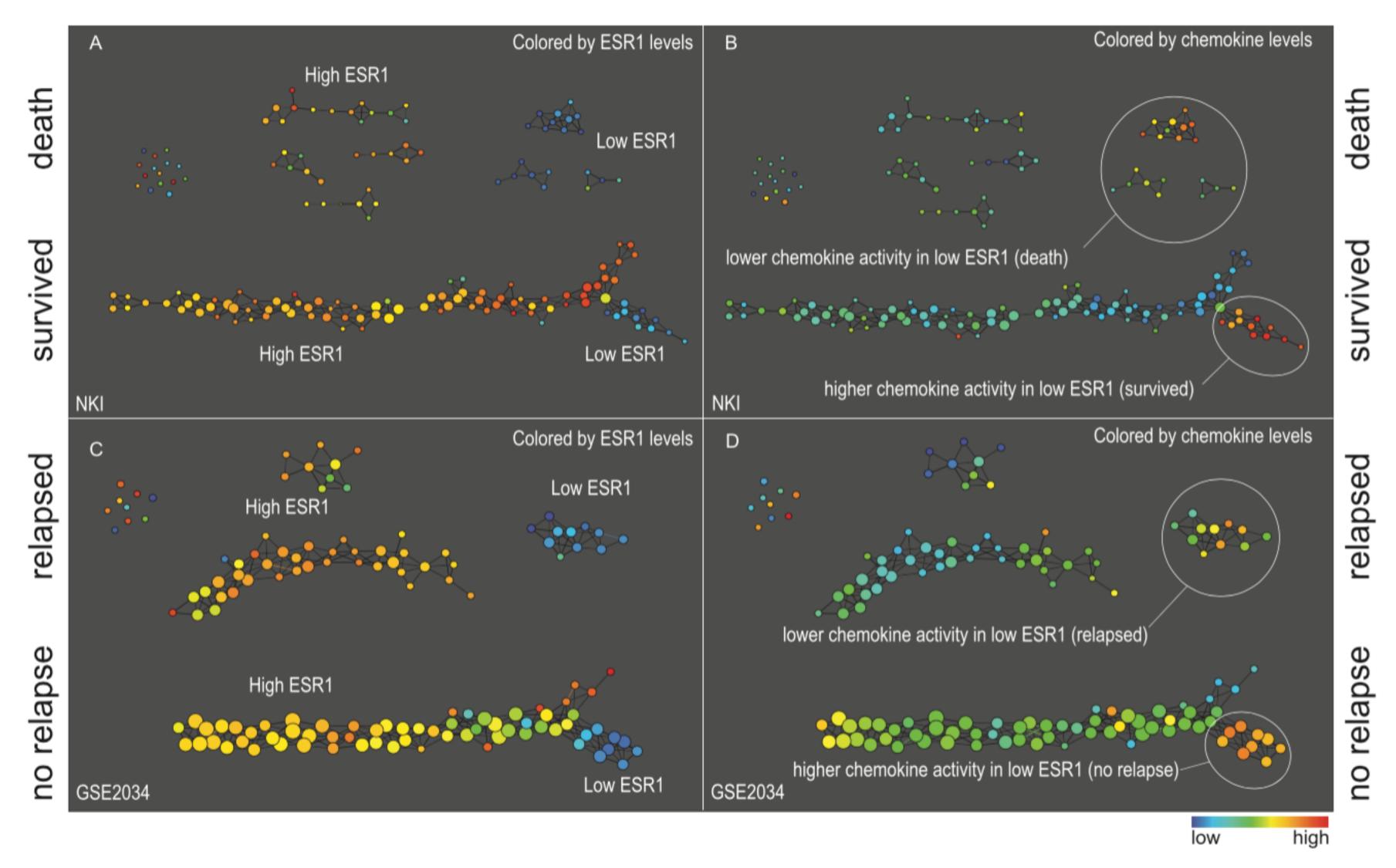


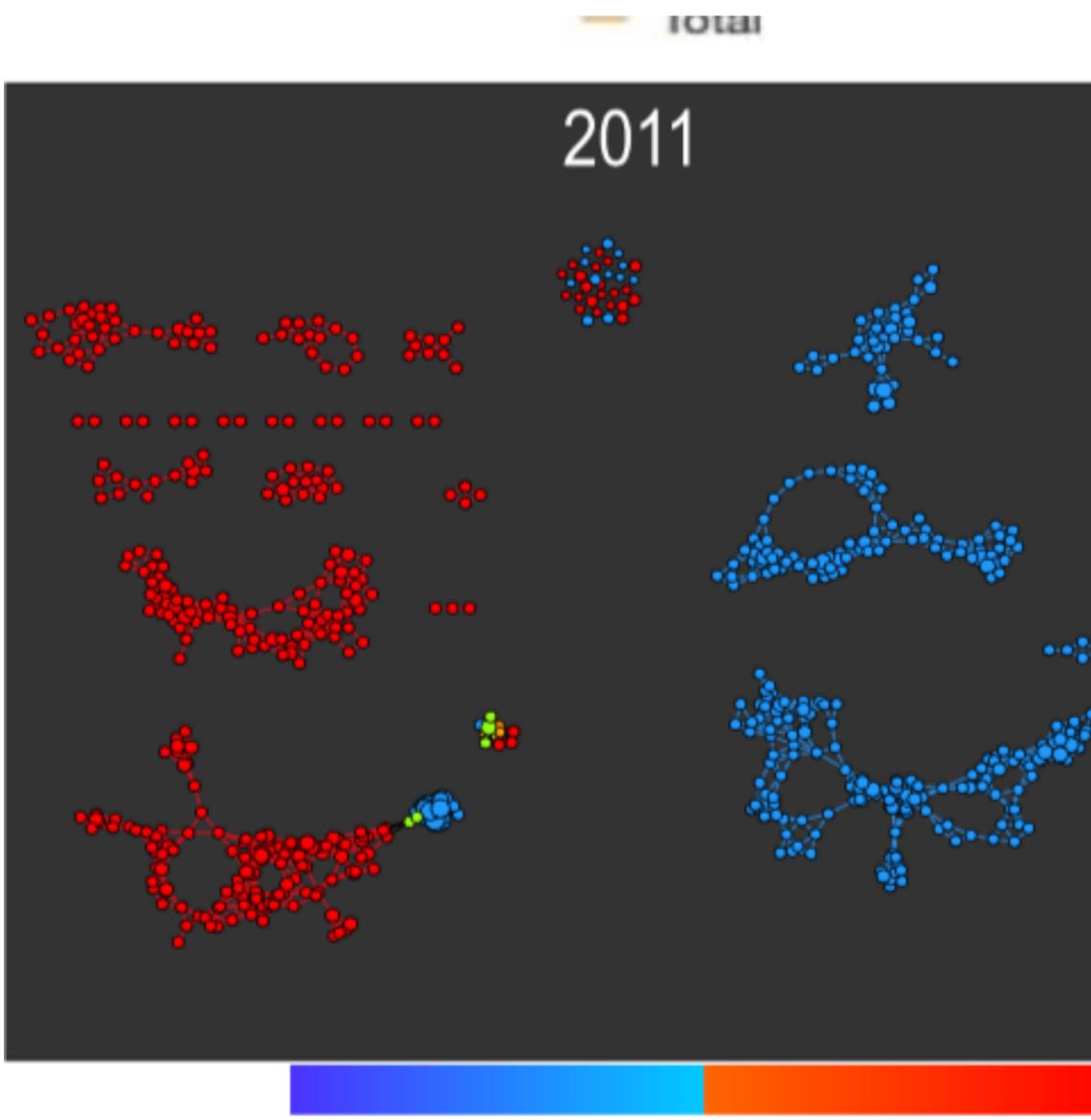
Fig. 3. PAD analysis of the NKI data. The output has three progression arms, because tumors (data points) are ordered by the magnitude of deviation from normal (the HSM). Each bin is colored by the mean of the filter map on the points. Blue bins contain tumors whose total deviation from HSM is small (normal and Normal-like tumors). Red bins contain tumors whose deviation from HSM is large. The image of f was subdivided into 15 intervals with 80% overlap. All bins are seen (outliers included). Regions of sparse data show branching. Several bins are disconnected from the main graph. The ER<sup>-</sup> arm consists mostly of Basal tumors. The c-MYB<sup>+</sup> group was chosen within the ER arm as the tightest subset, between the two sparse regions.



### Breast Cancer dataset 2



LumSinghLehman2012



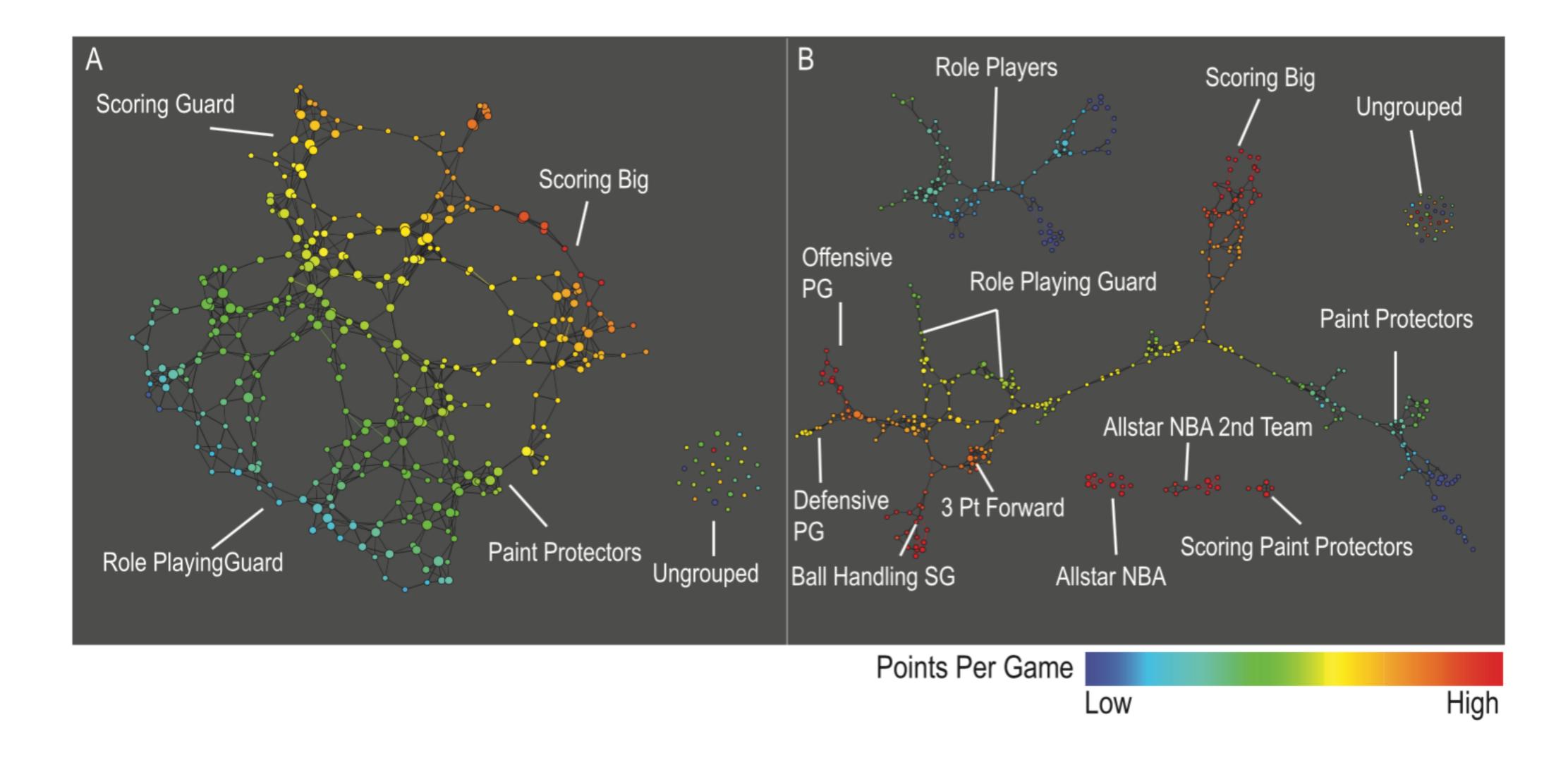
### Democrat

### Republican

### Politics



[LumSinghLehman2012]



### Sports

[LumSinghLehman2012]

## Discussions

Future directions...

### Limitations of Mapper

- How to choose the stable range of parameters (k, p) How to choose the clustering algorithms
- How to choose the filter functions
- Obtain insights with the right color function...

### **Future directions**

- Better automatic parameter tuning
- Multi-scale mapper
- Output 2D Mapper: theoretical understanding

# KepperMapper

A Demo

- Output Python Mapper
  - http://danifold.net/mapper/index.html
- R implementation: TDAmapper
  - https://cran.r-project.org/web/packages/TDAmapper/index.html
- Spark Mapper:
  - <u>https://github.com/log0ymxm/spark-mapper</u>

### **Open sourced implementation**

### Kepler-Mapper Demo

- The example with one circle
- The example with two circles
- Digits example
- Breast Cancer Example

A simple, first application of HD analysis

# Project 1 Explained

### Limitations of KeplerMapper

- KeplerMapper is still under active development: The visualization capabilities are limited (one color function) There are not much of interactive visualization
  - No integration with other machine learning algorithms

## Project 1 tips

- understand kmapper.py as much as possible
- Start your project early; start it today Read the paper:

The questions on KeplerMapper is rather fundamental, the goal is for you to understand the inner-working of the code; try to read and

### Final Project Idea

E.g. enhance the visualization capabilities of KeplerMapper Scalable solution using Spark Mapper Need to solve or give insight to a real-world problem

- A non-trivial extension to open sourced Mapper implementation
- A non-trivial application of mapper algorithms to real-world data set

## Thanks! Any questions?

You can find me at: beiwang@sci.utah.edu



### CREDITS

Special thanks to all people who made and share these awesome resources for free:

- Vector Icons by Matthew Skiles

Presentation template designed by <u>Slidesmash</u>

Photographs by <u>unsplash.com</u> and <u>pexels.com</u>

### **Presentation Design**

This presentation uses the following typographies and colors:

### Free Fonts used:

http://www.1001fonts.com/oswald-font.html

https://www.fontsquirrel.com/fonts/open-sans

### **Colors** used