

Math 5760/6890: Introduction to Mathematical Finance

The N -security Markowitz Portfolio

See Petters and Dong 2016, Section 3.3-3.4

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A quick recap

For Markowitz 2-security portfolio optimization:

- Return rates \mathbf{R} for the two securities are random variables
- Assume first- and second-order statistics of these are available: $\boldsymbol{\mu} = \mathbb{E}\mathbf{R}$ and $\mathbf{A} = \text{Cov}(\mathbf{R})$ (Book: $V = \text{cov}(R)$)
- The portfolio is defined by the weights \mathbf{w} Return rate: $R_p = \langle \mathbf{w}, \mathbf{R} \rangle$
- The expected return rate of the portfolio is $\mu_P = \langle \boldsymbol{\mu}, \mathbf{w} \rangle$
- The squared risk of the portfolio is $\sigma_P^2 = \text{Var} \langle \mathbf{R}, \mathbf{w} \rangle = \mathbf{w}^T \mathbf{A} \mathbf{w}$

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- The expected return rate of the portfolio is $\mu_P = \langle \boldsymbol{\mu}, \mathbf{w} \rangle$
- The squared risk of the portfolio is $\sigma_P^2 = \text{Var} \langle \mathbf{R}, \mathbf{w} \rangle = \mathbf{w}^T \mathbf{A} \mathbf{w}$
- Generally, no optimization is needed for 2-security portfolios: the weight constraints uniquely identify portfolios
- Many risk-optimal portfolios are *not* efficient
- The set of risk-optimal portfolios can be explicitly parameterized + plotted
- There is a global variance-minimizing portfolio – it's possible investors might not want this portfolio.
- The *efficient frontier* can be “easily” identified.

The N -security Markowitz portfolio

$$\text{Recall: } \sigma_p^2 = \mathbf{w}^T \mathbf{A} \mathbf{w}$$

We now consider the risk-minimization problem for an N -security portfolio:

$$\min_{\mathbf{w}} \mathbf{w}^T \mathbf{A} \mathbf{w} \text{ subject to } \langle \mathbf{w}, \mathbf{1} \rangle = 1, \text{ and}$$
$$\langle \mathbf{w}, \boldsymbol{\mu} \rangle = \mu_P.$$

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- The constraints are the same: we enforce \mathbf{w} is a valid portfolio weight, and that the portfolio has expected return rate μ_P .
- Just like before, we will see that risk-optimal portfolios need not be efficient ones.
- We make assumptions that are, by now, commonplace:
 - ▶ \mathbf{A} is positive-definite
 - ▶ $\boldsymbol{\mu}$ is not parallel to $\mathbf{1}$
 - ▶ We allow short selling

X, Y : scalar RV's

$$\underline{Z} = \begin{pmatrix} X \\ Y \end{pmatrix}$$

$$\text{Cov}(X, Y) = \mathbb{E}[(X - \mathbb{E}X)(Y - \mathbb{E}Y)]$$

$$\text{Cov}(X, X) = \text{Var}(X)$$

$$\text{Cov}(\underline{Z}) = \begin{pmatrix} \text{Cov}(Z_1, Z_1) & \text{Cov}(Z_1, Z_2) \\ \text{Cov}(Z_2, Z_1) & \text{Cov}(Z_2, Z_2) \end{pmatrix}$$

$$\rho_{X,Y} = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y} \quad \sigma_X^2 = \text{Var} X$$

$$\underline{\Sigma}^{\downarrow(Z)} = \text{diag}(\sigma_{Z_1}, \sigma_{Z_2} \dots \sigma_{Z_N})$$

$$\underline{\Sigma}^{-1} \text{Cov}(\underline{Z}) \underline{\Sigma}^{-1} \leftarrow \text{matrix of correlation coefficients.}$$

Computing the risk-optimal portfolio

L09-S04

$$\min_{\mathbf{w}} \mathbf{w}^T \mathbf{A} \mathbf{w} \text{ subject to } \langle \mathbf{w}, \mathbf{1} \rangle = 1, \text{ and} \\ \langle \mathbf{w}, \boldsymbol{\mu} \rangle = \mu_P.$$

We assume \mathbf{A} is positive-definite and $\boldsymbol{\mu}$ is not parallel to $\mathbf{1}$.

Unlike the 2-security case, we have a real optimization problem: the two linear constraints are not sufficient to uniquely characterize a vector with 3 or more entries.

To solve this constrained optimization problem, we'll use (+recall) Lagrange multipliers.

Simple version of Lagrange Multipliers: solve the constrained
Opt. problem: $\min_{\underline{x}} f(\underline{x})$ subject to $g(\underline{x}) = 0$. $\underline{x} \in \mathbb{R}^N$

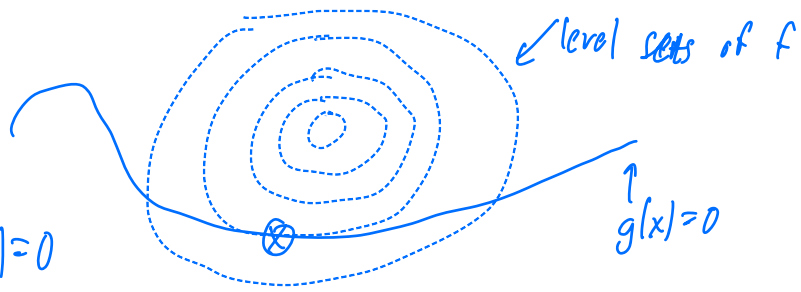
Plot this problem in $N=2$ dimensions?

at (x) (solution):

normal vector to $g(x)=0$

and the contour of f are

parallel: $\nabla f = \text{const. } \nabla g$. (at (x))



Lagrange multipliers: solving the constrained problem can

be achieved by solving: $\begin{cases} \nabla f = \lambda \nabla g, \lambda \in \mathbb{R} \\ g(x) = 0. \end{cases}$
3 unknowns (x, λ) , 3 eqns.

This procedure can be written as an unconstrained opt.

problem: Define $\mathcal{L}(\underline{x}, \lambda) = f(x) + \lambda g(x)$

$$\nabla_{\underline{x}} \mathcal{L} = 0 \iff \nabla f + \lambda \nabla g = 0$$

$$\nabla_{\lambda} \mathcal{L} = 0 \iff g(x) = 0$$

\mathcal{L} : "Lagrangian".

Lagrange Multipliers: compute ^{derivative = 0} critical point of \mathcal{L} as a function of (\underline{x}, λ)

With $m \geq 1$ constraints: $\mathcal{L}(\underline{x}, \underline{\lambda}) = f(x) + \sum_{i=1}^m \lambda_i g_i(x)$,
 $\lambda \in \mathbb{R}^m$

where this corresponds to the opt.-problem:

$$\min_{\underline{x}} f(\underline{x}) \text{ subject to } g(\underline{x}) = \underline{0}$$

$$g(\underline{x}) = (g_1(\underline{x}), g_2(\underline{x}), \dots, g_m(\underline{x}))^T$$

$$\mathcal{L}(\underline{x}, \underline{\lambda}) = f(\underline{x}) + g^T \underline{\lambda}$$

$$\text{Lagrange multipliers: } \nabla_{\underline{x}, \underline{\lambda}} \mathcal{L} = 0$$

$$\begin{array}{c} \Downarrow \\ \nabla_{\underline{x}} \rightarrow \nabla f + \sum_{i=1}^m \lambda_i \nabla g_i(\underline{x}) = 0 \end{array}$$

$$\begin{array}{l} \underline{\lambda} \in \mathbb{R}^m \\ f: \mathbb{R}^N \rightarrow \mathbb{R} \end{array}$$

$$\nabla_{\underline{\lambda}} \left\{ \begin{array}{l} g_1(\underline{x}) = 0 \\ g_2(\underline{x}) = 0 \\ \vdots \\ g_m(\underline{x}) = 0 \end{array} \right.$$

Remark: Critical points (sol'ns to Lagrange mult) need not be minima of f subject to $g(\underline{x}) = 0$.

Being a solution of a Lagrange mult problem is a necessary condition for local minimum, but not sufficient.

A sufficient condition can be formulated involving second derivatives of \mathcal{L} .

Back to portfolios:

$$\min_{\underline{w}} \underline{w}^T \underline{A} \underline{w} \quad \text{subject to} \quad \langle \underline{w}, \underline{1} \rangle = 1$$
$$\langle \underline{w}, \underline{\mu} \rangle = \mu_p$$

$$f(\underline{w}) = \underline{w}^T \underline{A} \underline{w} \quad g_1(\underline{w}) = \langle \underline{w}, \underline{1} \rangle - 1$$
$$g_2(\underline{w}) = \langle \underline{w}, \underline{\mu} \rangle - \mu_p$$

$$\mathcal{L}(\underline{w}, \underline{\lambda}) = \underbrace{\underline{w}^T \underline{A} \underline{w}}_{\sum_{i,j} w_i A_{ij} w_j} + \lambda_1 (\langle \underline{w}, \underline{1} \rangle - 1) + \lambda_2 (\langle \underline{w}, \underline{\mu} \rangle - \mu_p)$$

$$\nabla \mathcal{L} = \underline{0} \implies 2 \underline{A} \underline{w} + \lambda_1 \underline{1} + \lambda_2 \underline{\mu} = \underline{0} \quad (1)$$

$$\langle \underline{w}, \underline{1} \rangle = 1 \quad (2)$$

$$\langle \underline{w}, \underline{\mu} \rangle = \mu_p \quad (3)$$

$$(1) \implies \underline{w} = -\frac{1}{2} \lambda_1 \underline{A}^{-1} \underline{1} - \frac{1}{2} \lambda_2 \underline{A}^{-1} \underline{\mu}$$

$$(2): \lambda_1 \left[-\frac{1}{2} \underline{\underline{1}}^T \underline{\underline{A}}^{-1} \underline{\underline{1}} \right] + \lambda_2 \left[-\frac{1}{2} \underline{\underline{1}}^T \underline{\underline{A}}^{-1} \underline{\underline{\mu}} \right] = 1$$

$$(3): \lambda_1 \left[-\frac{1}{2} \underline{\underline{\mu}}^T \underline{\underline{A}}^{-1} \underline{\underline{1}} \right] + \lambda_2 \left[-\frac{1}{2} \underline{\underline{\mu}}^T \underline{\underline{A}}^{-1} \underline{\underline{\mu}} \right] = \underline{\underline{\mu}}_p$$

Define $a = \underline{\underline{1}}^T \underline{\underline{A}}^{-1} \underline{\underline{1}}$, $b = \underline{\underline{1}}^T \underline{\underline{A}}^{-1} \underline{\underline{\mu}}$, $c = \underline{\underline{\mu}}^T \underline{\underline{A}}^{-1} \underline{\underline{\mu}}$

$$(2)+(3): \underbrace{\begin{pmatrix} a & b \\ b & c \end{pmatrix}}_{\underline{\underline{M}}} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} = \begin{pmatrix} -2 \\ -2\underline{\underline{\mu}}_p \end{pmatrix}$$

$$\underline{\underline{\lambda}} = \underline{\underline{M}}^{-1} (-2) \cdot \begin{pmatrix} 1 \\ \underline{\underline{\mu}}_p \end{pmatrix}$$

$$= -2 \underline{\underline{M}}^{-1} \left[\begin{pmatrix} 1 \\ 0 \end{pmatrix} + \underline{\underline{\mu}}_p \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]$$

$$\underline{\underline{M}}^{-1} = \frac{1}{ac-b^2} \begin{pmatrix} c & -b \\ -b & a \end{pmatrix}$$

$$\Rightarrow \underline{\underline{\lambda}} = \frac{-2}{ac-b^2} \left[\begin{pmatrix} c & -b \\ -b & a \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \underline{\underline{\mu}}_p \begin{pmatrix} c & -b \\ -b & a \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right]$$

$$= \frac{-2}{ac-b^2} \left[\begin{pmatrix} c \\ -b \end{pmatrix} + \mu_p \begin{pmatrix} -b \\ a \end{pmatrix} \right]$$

$$= \frac{2}{ac-b^2} \begin{pmatrix} -c + b\mu_p \\ b - a\mu_p \end{pmatrix}$$

Recall: $\underline{w} = -\frac{1}{2} \lambda_1 \underline{A}^{-1} \underline{1} - \frac{1}{2} \lambda_2 \underline{A}^{-1} \underline{\mu}$

$$\underline{w} = \frac{-1}{ac-b^2} \left[(-c + b\mu_p) \underline{A}^{-1} \underline{1} + (b - a\mu_p) \underline{A}^{-1} \underline{\mu} \right]$$

$$= \frac{1}{ac-b^2} \left[c \underline{A}^{-1} \underline{1} - b \underline{A}^{-1} \underline{\mu} \right]$$

$$+ \frac{\mu_p}{ac-b^2} \left[-b \underline{A}^{-1} \underline{1} + a \underline{A}^{-1} \underline{\mu} \right]$$

\underline{w} is a critical pt of I (and we'll assume this corresponds to the global min of the

Opt. problem]

$$\Rightarrow \underline{v}_0 = \frac{c \underline{A}^{-1} \underline{1} - b \underline{A}^{-1} \underline{A}}{ac - b^2}$$

$$\underline{v}_1 = \frac{-b \underline{A}^{-1} \underline{1} + a \underline{A}^{-1} \underline{A}}{ac - b^2}$$

$$\Rightarrow \underline{w} = \underline{v}_0 + \mu_p \underline{v}_1$$

↑
Desired (risk-optimal) portfolio.

Q: How does the optimal risk depend on μ_p ?

$$\sigma_p^2 \stackrel{(\mu_p)}{=} \underline{w}^T \underline{A} \underline{w}$$

$$= (\underline{v}_0 + \mu_p \underline{v}_1)^T \underline{A} (\underline{v}_0 + \mu_p \underline{v}_1)$$

$$= \mu_p^2 [\underline{v}_1^T \underline{A} \underline{v}_1] + \mu_p [2 \underline{v}_0^T \underline{A} \underline{v}_1] + \underline{v}_0^T \underline{A} \underline{v}_0$$

$$\frac{\sigma_p^2}{\underline{v}_1^T \underline{A} \underline{v}_1} = \mu_p^2 + \mu_p \frac{2 \underline{v}_0^T \underline{A} \underline{v}_1}{\underline{v}_1^T \underline{A} \underline{v}_1} + \frac{\underline{v}_0^T \underline{A} \underline{v}_0}{\underline{v}_1^T \underline{A} \underline{v}_1}$$

$$= \left(\mu_p + \frac{\underline{v}_0^T \underline{A} \underline{v}_1}{\underline{v}_1^T \underline{A} \underline{v}_1} \right)^2 - \left(\frac{\underline{v}_0^T \underline{A} \underline{v}_1}{\underline{v}_1^T \underline{A} \underline{v}_1} \right)^2 + \frac{\underline{v}_0^T \underline{A} \underline{v}_0}{\underline{v}_1^T \underline{A} \underline{v}_1}$$

$$\frac{\sigma_p^2}{\left(v_1^T A v_1 \left[\frac{v_0^T A v_0}{v_1^T A v_1} - \left(\frac{v_0^T A v_1}{v_1^T A v_1} \right)^2 \right] \right)} - \frac{\left(\mu_p + \frac{v_0^T A v_1}{v_1^T A v_1} \right)^2}{\frac{v_0^T A v_0}{v_1^T A v_1} - \left(\frac{v_0^T A v_1}{v_1^T A v_1} \right)^2} = 1$$

$$\frac{\sigma_p^2}{\alpha^2} - \frac{\left(\mu_p + \frac{v_0^T A v_1}{v_1^T A v_1} \right)^2}{\beta^2} = 1 \quad \left(\text{This is the graph of a hyperbola.} \right)$$

$\alpha^2 > 0$ by Cauchy-Schwarz

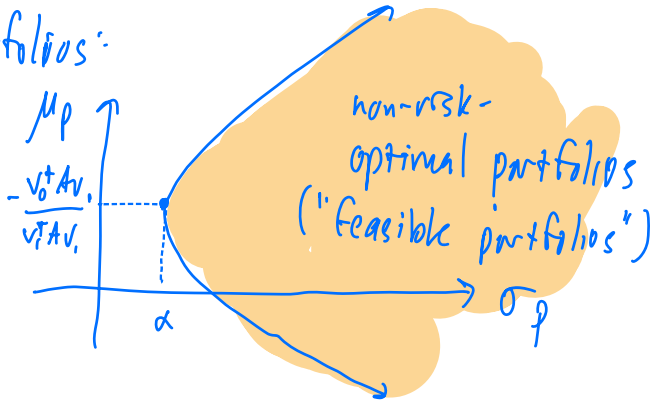
$$\alpha^2 = v_0^T A v_0 - \frac{(v_0^T A v_1)^2}{v_1^T A v_1}$$

$$\beta^2 = \frac{v_0^T A v_0}{v_1^T A v_1} - \left(\frac{v_0^T A v_1}{v_1^T A v_1} \right)^2$$

Vertex: $\mu_p = -\frac{v_0^T A v_1}{v_1^T A v_1}$

$$\sigma_p = \alpha > 0$$

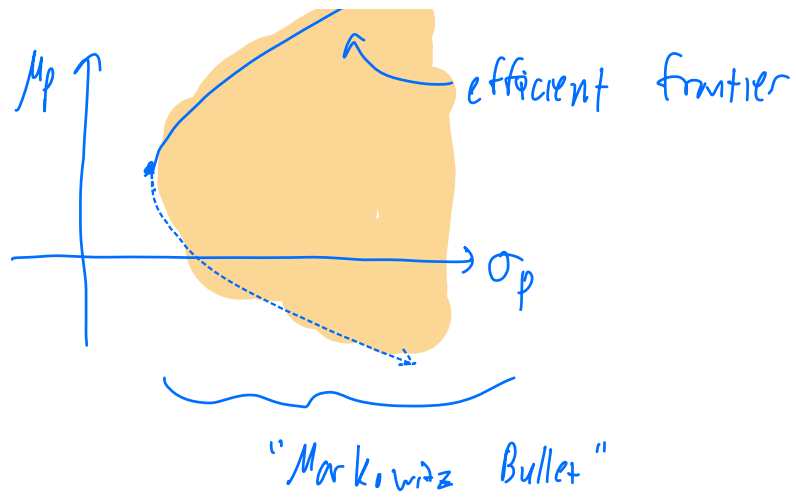
Risk-optimal portfolios:



There is a global variance-minimizing portfolio @ the vertex, i.e. at $\mu_p = -\frac{v_0^T A v_1}{v_1^T A v_1} =: \mu_0$

There is an efficient frontier: set of risk-optimal portfolios whose μ_p is maximized for a fixed σ_p .





An explicit result

Define some auxiliary quantities:

$$\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} \mathbf{1}^T \mathbf{A}^{-1} \mathbf{1} \\ \mathbf{1}^T \mathbf{A}^{-1} \boldsymbol{\mu} \\ \boldsymbol{\mu}^T \mathbf{A}^{-1} \boldsymbol{\mu} \end{pmatrix},$$

$$\mathbf{v}_0 = \frac{c\mathbf{A}^{-1}\mathbf{1} - b\mathbf{A}^{-1}\boldsymbol{\mu}}{ac - b^2} \in \mathbb{R}^N,$$

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Theorem

Consider the N -security Markowitz portfolio with our assumptions. Then:

- The unique risk-optimal portfolio with expected return rate μ_P is $\mathbf{w} = \mathbf{v}_0 + \mu_P \mathbf{v}_1$.
- The set of risk-optimal portfolios is a parametric curve in the (σ_P, μ_P) plane, given by,

$$\frac{\sigma_P^2}{\sigma_G^2} + \frac{(\mu_P - \mu_G)^2}{d^2} = 1.$$

- The global risk-minimizing portfolio has coordinates (σ_G, μ_G) given by

$$\sigma_G^2 = \mathbf{v}_0^T \mathbf{A} \mathbf{v}_0 - \frac{(\mathbf{v}_0^T \mathbf{A} \mathbf{v}_1)^2}{\mathbf{v}_1^T \mathbf{A} \mathbf{v}_1}, \quad \mu_G = -\frac{\mathbf{v}_0^T \mathbf{A} \mathbf{v}_1}{\mathbf{v}_1^T \mathbf{A} \mathbf{v}_1}.$$

As with the 2-security case, the efficient frontier corresponds to the portfolios on the “upper half” of the risk-minimizing hyperbola.

I.e., a risk-minimizing portfolio with coordinates (σ_P, μ_P) is *efficient* if $\mu_P \geq \mu_G$.

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In the N -security case, there are many more *feasible* portfolios than simply the risk-optimal ones.

In particular, the region of feasible portfolios in the (σ_P, μ_P) plane is the region contained within the hyperbola.

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This region of feasible portfolios is called the *Markowitz bullet*, with the risk-optimal portfolios forming the bullet boundary, the efficient frontier the upper part of this boundary, and the global risk-minimizing portfolio the tip of the bullet.

Portfolios without short selling

L09-S07

Efficient portfolios can correspond to substantially leveraged portfolios.

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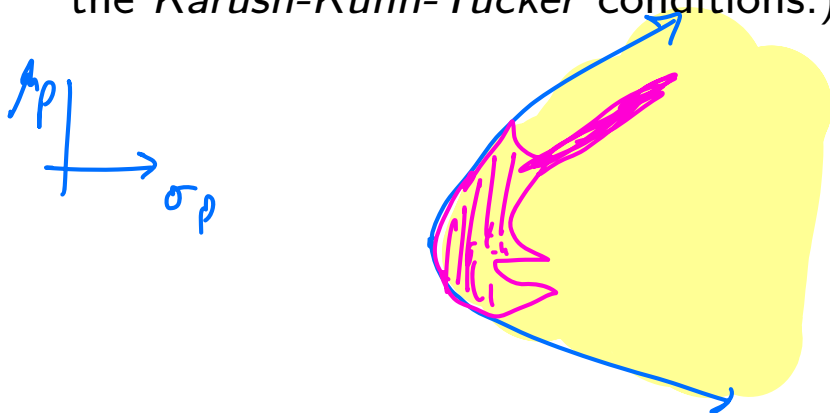
$$\min_w \mathbf{w}^T \mathbf{A} \mathbf{w} \text{ subject to } \langle \mathbf{w}, \mathbf{1} \rangle = 1, \text{ and}$$

$$\langle \mathbf{w}, \boldsymbol{\mu} \rangle = \mu_P, \text{ and}$$

$$w_i \geq 0, \quad i = 1, 2, \dots, N.$$

This is an inequality-constrained optimization problem.

The method of Lagrange multipliers can no longer handle this problem. (We need instead the *Karush-Kuhn-Tucker* conditions.)



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Typically we rely on numerical software to solve this problem, but generically the solution set is some subset of the Markowitz bullet, with the efficient frontier a subset of the bullet boundary.

 Petters, Arlie O. and Xiaoying Dong (2016). *An Introduction to Mathematical Finance with Applications: Understanding and Building Financial Intuition*. Springer. ISBN: 978-1-4939-3783-7.