# Integration/differentiation with polynomial approximations 

## MATH 6610 Lecture 27

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## Polynomial approximation

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The basic ideas:

- Given function data at some points, we can construct a polynomial interpolant.
- (Interpolatory quadrature) Integration: we approximate the integral of the function as the integral of the polynomial interpolant.
- (Finite differences) Differentiation: we approximate the derivative of the function as the derivative of the polynomial interpolant.

Interpolatory quadrature
With $x_{1}, \ldots, x_{n}$ unique, fixed nodes on $[a, b]$, and $f$ a given continuous function: Define $I_{n-1}: C([a, b]) \rightarrow P_{n-1}$ as the interpolation operator:

$$
\begin{aligned}
I_{n-1} f & :=\sum_{j=1}^{n} f\left(x_{j}\right) \ell_{j}(x), & \ell_{j}(x) & :=\prod_{\substack{k=1, \ldots, n \\
k \neq j}} \frac{x-x_{k}}{x_{j}-x_{k}} \\
& =\sum_{j=1}^{n} c_{j} x^{j-1}, & V c & =f .
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An interpolatory quadrature rule is a set of nodes $\left\{x_{j}\right\}$ and weights $\left\{w_{j}\right\}$ that results from using the integral of $I_{n-1} f$ to approximate the integral of $f$ :

$$
\int_{a}^{b} f(x) \mathrm{d} x \approx \int_{a}^{b}\left[I_{n-1} f\right](x) \mathrm{d} x=: \sum_{j=1}^{n} w_{j} f\left(x_{j}\right)
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There are two ways to compute such nodes and weights, depending on the algorithmic strategy for $I_{n-1}$.

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## Example

Compute weights for the quadrature rule $\sum_{j=-1}^{1} w_{j} f(j)$ that is accurate to as high a polynomial degree as possible.

## Interpolatory quadrature accuracy

The standard way to compute error estimates for polynomial quadrature: Taylor series arguments.

Typically one utilizes an error estimate for interpolation. For $n$-point interpolation on $[a, b]$, exact on $P_{n-1}$ :

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f(x)-\left[I_{n-1} f\right](x)=\frac{f^{(n)}(\xi)}{n!} \prod_{j=1}^{n}\left(x-x_{j}\right), \quad \xi=\xi(x) \in[a, b]
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Chaining this together with an integral:

$$
\left|\int_{a}^{b} f(x) \mathrm{d} x-\int_{a}^{b}\left[I_{n-1} f\right](x) \mathrm{d} x\right| \leqslant \frac{(b-a)^{n+1}}{n!} \max _{x \in[a, b]}\left|f^{(n)}(x)\right|
$$

## Types of quadrature rules

$$
\int_{a}^{b} f(x) \mathrm{d} x \approx \sum_{j=1}^{n} w_{j} f\left(x_{j}\right)
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There are several special types of quadrature rules:

- Equidistant nodes: "Newton-Cotes" rules
- "Closed": the endpoints are nodes (e.g., $a, b$ )
- "Open": all nodes are interior to the interval
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- Chebyshev/arcsine-like nodal arrangements: Clenshaw-Curtis quadrature, Fejér quadrature
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- Hermite quadrature: uses derivatives as well as function values
- Gaussian quadrature: Fixing $n$, has the maximum possible polynomial degree of exactness.

Finite difference formulas
With $x_{1}, \ldots, x_{n}$ unique, fixed nodes on $[a, b]$, and $f$ a given continuous function: Define $I_{n-1}: C([a, b]) \rightarrow P_{n-1}$ as the interpolation operator:

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A finite difference formula rule is a set of nodes $\left\{x_{j}\right\}$ and weights $\left\{w_{j}\right\}$ that results from using the derivative of $\left[I_{n-1} f\right](x)$ to approximate $f^{\prime}(x)$.
Some minor differences from the quadrature case:

- The weights depend on the location $x$.
- The weights can be defined by means other than interpolation.

Again, there are multiple ways to compute weights depending on how the interpolant is identified.

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## Example

Compute a 3-point finite-difference formula on the nodes $\{-1,0,1\}$ for differentiation at $x=0$.

## Order of accuracy

Error estimates for finite difference formulas are computable via Taylor's Theorem. Recall that interpolation error on the interval $[a, b]$ scales like $(b-a)^{n+1}$.

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To standardize this, we typically assume equidistant nodes, with a spacing of $h>0$. The order of accuracy of a finite difference formula is typically $\mathcal{O}\left(h^{k}\right)$ for some integer $k$.

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## Example

Compute a finite difference formula and order of accuracy (error estimate) for the three finite difference formulas:

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\begin{aligned}
f^{\prime}(x) & \approx w_{1} f(x)+w_{2} f(x+h) \\
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Odds and ends: higher-order derivatives can be approximated, function derivatives instead of function values can be used, etc.

