L18-S00

Eigenvalue algorithms: Power iteration

MATH 6610 Lecture 18

October 19, 2020

Trefethen & Bau: Lectures 12, 25

Eigenvalues

We've seen that eigenvalues, i.e., numbers λ such that

$$Av = \lambda v, \qquad (v \neq 0)$$

play fundamental roles in linear algebra. How are eigenvalues computed?

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$$Av = \lambda v \quad \iff \quad p_A(\lambda) \coloneqq \det (A - \lambda I) = 0.$$

While conceptually easy, this turns out to be very difficult practically.

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Polynomial roots

We are trying to compute λ satisfying

 $p_{A}(\lambda) = 0.$ $A \in \mathbb{C}^{n \times n} \qquad p_{A}(\lambda) = \lambda^{n} + \sum_{j=0}^{n-1} a_{j} \lambda^{j}$ $g_{A}(\lambda) = \lambda^{n} + \sum_{j=0}^{n-1} a_{j} \lambda^{j}$

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The first, sobering reality: there is no explicit way to do this in general.

Theorem (Abel)

Let $n \ge 5$. There is an $n \times n$ matrix A, with rational entries, having an eigenvalue λ that <u>cannot</u> be expressed via elementary arithmetic operations on rational numbers (additions/subtraction, multiplication/division, rational exponentiation).

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Note that this contrasts with other operations like LU factorizations, QR factorizations, determinants,

(orthogonalizing vectors)

The result: we cannot obtain *explicit* expressions for eigenvalues in general. We must build approximations from iterative applications of elementary arithmetic operations.

Polynomial rootfinding

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1.) • x² − 2x + 1: The (relative) condition number of the roots is unbounded
 2.) • ∏ⁿ_{j=1}(x − x_j): tiny perturbations in monomial coefficients can cause wild changes in roots

1.)
$$p_A(x) = x^2 - 2x + 1 = (x - 1)^2$$

 $= x^2 + ax + b \quad (a = -2, b = 1)$
consider $f = \mathbb{R}^2 \longrightarrow \mathbb{R}$ that maps monit poly we fit cients
to a root of p_A . (say, largest root.)

$$f\begin{pmatrix} a \\ b \end{pmatrix} = 1 \implies \forall f = \varepsilon$$

$$\| \nabla (f) \| = \varepsilon_{3}$$

$$f(\frac{4}{6}) = 1 \implies \Delta f = \varepsilon$$

$$\|\Delta(\frac{6}{6})\| = \varepsilon^{2}$$

$$\chi = \frac{\varepsilon/\varepsilon^{2}}{\frac{4(\varepsilon)}{100}} = O(\frac{1}{\varepsilon}) 7 \text{ so as } \varepsilon \downarrow O,$$

$$1 \qquad \frac{1}{\sqrt{5}}$$

This operation is ill-conditioned.
2.)
$$\prod_{j=1}^{n} (x - x_{j}), \quad \text{Chorse } n = 20, \quad x_{j} = j$$

xn+ Žq; xj "Wilkinson's polynomial" Perturbing q by O(10⁻¹³) results in O(1) changes to roots. This is an unstable operation (computing roots from monic crefficients).

Polynomial rootfinding



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- $x^2 2x + 1$: The (relative) condition number of the roots is unbounded
- $\prod_{j=1}^{n} (x x_j)$: tiny perturbations in monomial coefficients can cause wild changes in roots

Conclusion: rootfinding is (typically) a bad idea.

Power iteration, I

We'll specialize discussion to Hermitian matrices, with simple eigenvalues.

(why? Formulas and ideas simplify a lot.) $A \in \mathbb{C}^{n \times n} \rightarrow A = V \wedge V^*$, $VV^* = I$ $Jigg(\Lambda)$ are real-valued. & distinct.

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Power iteration, I

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Let $(\lambda_1, v_1)_{n=1}^N$ be the ordered eigenpairs of an $n \times n$ matrix A. The ordering is such that $|\lambda_1| > |\lambda_2| > \cdots$

 $(\lambda_{\eta}, V_{n})_{\eta=1}^{N}$

Let
$$v \in \mathbb{C}^n$$
, $v = \sum_{j=1}^n c_j v_j$ (mustly use care about
s=1 c_j v_j (mustly use care about
case when $c_j \neq 0$).

$$A_{V} = V \Lambda V^{*} \left(\sum_{j=1}^{n} c_{j} v_{j} \right) = \sum_{j=1}^{n} \lambda_{j} c_{j} v_{j}$$
$$A^{2}_{V} = V \Lambda V^{*} \left(\sum_{j=1}^{n} \lambda_{j} c_{j} v_{j} \right) = \sum_{j=1}^{n} \lambda_{j}^{2} c_{j} v_{j}$$

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$$\implies \mathcal{A}^{k} v = \sum_{j=1}^{n} C_{j} \lambda_{j}^{k} v_{j}$$
$$= \lambda_{j}^{k} \left[c_{j} v_{j} + \left(\frac{\lambda_{2}}{\lambda_{j}}\right)^{k} c_{2} v_{j} + \cdots + \left(\frac{\lambda_{n}}{\lambda_{j}}\right)^{k} c_{n} v_{n} \right]$$
$$\stackrel{1}{\xrightarrow{l}} 0 a_{s} k T \infty \qquad 0 a_{s} k T \infty$$

 $A^{k}v \xrightarrow{kTor} \lambda_{i}^{k}c_{i}v_{i} \rightarrow this is an eigenvector of A.$ How to compute λ_{i} ? $R_{A}(v) \coloneqq \frac{v^{*}Av}{||v||_{2}^{2}}$ Recall: $R_{A}(v_{i}) = \lambda_{i}$ If I compute a good approximation to V_{i}

 $\Rightarrow \lambda_1 = R_{A}(v_1)$

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The first algorithm we consider, power iteration, exercises two properties:

• For large k,
$$\frac{A^k x}{\|A^k x\|_2}$$
 converges to v_1 .

• If
$$v \approx v_1$$
, then $R_A(v) \coloneqq \frac{v^* A v}{\|v\|_2^2}$ is approximately λ_1 .

Power iteration, II

Here is a simplistic algorithm to compute the dominant eigenvalue of A: Initialize with a vector v (e.g., randomly):

1.
$$v \leftarrow \frac{Av}{\|Av\|_2}$$

2.
$$\lambda \leftarrow R_A(v)$$

3. Return to step 1

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When to terminate iteration? E.g., at step 3 keep track of $||Av - \lambda v||_2$.

This is *not* a particularly useful algorithm, but it does converge.

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Theorem

If the initial vector is not orthogonal to v_1 , then at iteration k, power iteration produces vector v and eigenvalue estimate λ satisfying,

$$\left\|v-v_{1}\right\|_{2}=\mathcal{O}(r^{k}),$$

where $r = |\lambda_2/\lambda_1|$.<

$$\|\lambda - \lambda_1\| = \mathcal{O}(r^{2k}),$$

"Proot" of Theorem : Assume v at iteration k Satisfies $||v - v_1||_2 = O(r^k)$. $\lambda @$ iteration | k is $\lambda = R_A(v)$ Taylor series around $v = V_1$: $R_A(v) = R_A(v_1) + \nabla R_A(v_1) \cdot (v - v_1) + O(||v - v_1||^2)$ $\int_{-\pi}^{\pi} dv = V_1$

$$\begin{aligned} & \left| R_{4}(v) - R_{4}(v_{1}) \right| \leq \nabla R_{4}(v_{1}) \cdot (v - v_{1}) + O(||v - v_{1}||^{2}) \\ & \lambda_{1} \\ & Show \quad \nabla R_{4}(v_{1}) = 0 \\ & A \text{ is real-valued,} \\ & A \text{ is real-symmetric.} \\ & v = (w_{1} - w_{n})^{*}, \quad w_{3} \in \mathbb{R} \\ & R_{4}(v) = \frac{\sum_{i,j=1}^{n} w_{i} A_{i,j} w_{j}}{\sum_{j=1}^{n} w_{j}^{2}} \end{aligned}$$

$$\frac{2}{\partial w_{e}} R_{A}(w) = \frac{\left(\sum_{i=1}^{n} A_{i,e} w_{i} + \sum_{i=1}^{n} A_{e_{i}} w_{i}\right) \|w_{i}\|^{2} - 2w_{e}(A_{v,w})}{\|w_{i}\|^{4}}$$

$$= \frac{2(A_{w})_{e} \cdot \|w_{i}\|^{2} - 2v_{e}(A_{v,v})}{\|v_{i}\|^{4}}$$

$$= \frac{2}{\|v_{i}\|^{2}} \left((A_{v})_{e} - v_{e}R_{A}(v)\right)$$

$$= \forall R_{A}(v) = \frac{2}{\|v_{i}\|^{2}} (A_{v} - v \cdot R_{A}(v))$$

$$\forall R_{A}(v_{i}) = \frac{2}{\|v_{i}\|^{2}} (A_{v} - v \cdot R_{A}(v))$$

$$= \frac{2}{\|v_{i}\|^{2}} (A_{v_{i}} - v_{i}R_{A}(v_{i}))$$

Deflation

We have only discussed how to compute a single eigenvalue.

To compute the rest, deflation techniques, which reduce A to an $(n-1)\times(n-1)$ matrix are used.

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The simplest (and neither efficient nor stable) deflation technique is Hotelling deflation:

If (λ, v) are a "converged" eigenpair for some eigenpair of A, then define

$$A_2 \coloneqq A - \lambda v v^*.$$

Then the dominant eigenpair of A_2 is (λ_2, v_2) Subsequently, power iteration can be used to compute λ_2 .

Recall A symmetric =>
$$A = \sum_{s=1}^{\infty} \lambda_s v_s v_s^*$$

$$\rightarrow A - \lambda_1 V_1 v_1^* = \sum_{j=2}^{n} A_j v_j v_j^* := A_2$$
rank is (n-1)

Now: run pourse iteration on $A_2 \rightarrow results$ in (A_2, v_2) $A_3 = A_2 - A_2 v_2 v_2^*$ continue.

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A full power iteration algorithm employs the basic iterative scheme, along with a termination criterion, and some deflation technique.