

# Numerical stability

MATH 6610 Lecture 07

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Trefethen & Bau: Lecture 14, 15

# Numerical algorithms

Given  $f : \mathbb{C}^n \rightarrow \mathbb{C}^m$ , we wish to understand how roundoff errors affect evaluation of  $f$ .

This should depend on

- Loss of accuracy due to finite precision
- Conditioning of  $f$

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- Loss of accuracy due to finite precision
- Conditioning of  $f$

Let  $\tilde{f} : \mathbb{C}^n \rightarrow \mathbb{C}^m$  denote the actual algorithmic implementation of  $f$ .

We might hope that

$$\frac{\|f(x) - \tilde{f}(x)\|}{\|f(x)\|} = \mathcal{O}(\epsilon_{\text{mach}}),$$

but this is typically too much to ask for if  $f$  is ill-conditioned.

## Forward stability

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and this motivates a definition.

### Definition

An algorithm  $\tilde{f}$  is forward stable if, for every  $x \in \mathbb{C}^n$ , we have

$$\frac{\|\tilde{f}(x) - f(\tilde{x})\|}{\|f(\tilde{x})\|} = \mathcal{O}(\epsilon_{\text{mach}}),$$

for some  $\tilde{x}$  satisfying  $\|x - \tilde{x}\| = \|x\|\mathcal{O}(\epsilon_{\text{mach}})$ .

A forward stable algorithm gives an “approximately correct answer to a closely related question.”

$$\frac{\|\tilde{f}(x) - f(\tilde{x})\|}{\|f(\tilde{x})\|} = \mathcal{O}(\epsilon_{\text{mach}}), \quad (1)$$

for some  $\tilde{x}$  satisfying  $\|x - \tilde{x}\| = \|x\|\mathcal{O}(\epsilon_{\text{mach}})$ .

If  $\tilde{f}$  is forward stable, we can show that  $\tilde{f}$  produces a reasonable approximation to  $f$ .

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This error estimation procedure, requiring the establishment of (1), is *forward error analysis*.

Showing forward stability (1) is frequently technical and difficult.



# Backward stability

A dual, but somewhat stranger+stronger notion of stability is backward stability.

## Definition

An algorithm  $\tilde{f}$  is backward stable if, for every  $x \in \mathbb{C}^n$ , we have

$$\tilde{f}(x) = f(\tilde{x}), \quad (2)$$

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A backward stable algorithm gives an “exact answer to a closely related question.”

If  $\tilde{f}$  is backward stable, then showing accuracy of the algorithm  $\tilde{f}$  is easier.

Estimating error by establishing (2) is *backward error analysis*.

Backward stability is frequently easier to show than forward stability.

# Examples

Assume some floating-point axioms:

1. For each  $x \in \mathbb{R}$ , then  $fl(x) = x(1 + \epsilon)$  for  $|\epsilon| \leq \mathcal{O}(\epsilon_{\text{mach}})$ .
2. For floating-points numbers  $x, y \in \mathbb{R}$ , then  $x \odot y = (x \cdot y)(1 + \epsilon)$  for  $|\epsilon| \leq \mathcal{O}(\epsilon_{\text{mach}})$ . ( $\cdot = +, -, \times$ )

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The floating-point implementation of  $f(x, y) = xy^T$  is *not* backward stable.