

## Forced oscillation and resonance

MATH 2250 Lecture 25  
Book section 5.6

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In systems whose homogeneous equations exhibit harmonic motion,

$$mx'' + cx' + kx = f(t),$$

the forcing function  $f$  is often an oscillatory function, e.g,  $f(t) = \sin(\omega t)$  or  $f(t) = \cos(\omega t)$ .

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There are two regimes of interest: the undamped, and the damped case.

# Undamped forced oscillations

Consider the DE

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where  $F_0$  and  $\omega$  are given constants.

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where

$$\omega_0 = \sqrt{\frac{k}{m}}, \quad A = \frac{F_0/m}{\omega_0^2 - \omega^2}.$$

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If we further impose  $x(0) = x'(0) = 0$ , then we have

$$x(t) = -A \cos(\omega_0 t) + A \cos(\omega t),$$

$$x(t) = 2A \left( \sin \frac{1}{2} \omega_0 t \right) \left( \sin \frac{1}{2} \omega t \right)$$

Thus, the solution is a faster frequency modulated by a slower one.

## Pure resonance

In our undamped forced oscillations case, if  $\omega = \omega_0$ , some coefficients blow up.

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The solution to the DE in this case is

$$x(t) = c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t) + c_3 t \cos(\omega_0 t) + c_4 t \sin(\omega_0 t).$$

Therefore, this model contains solutions whose amplitudes *grow* in time.

Generally speaking, this is interpreted as instability of a system.



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For this reason, the solution component from the homogeneous component is called the **transient** solution.

But the particular solution is one of the form  $\cos(\omega t)$  and  $\sin(\omega t)$  and thus are **steady periodic** components.

Thus, the full solution is a sum of transient and steady periodic components.

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Using undetermined coefficients, we can compute that the particular (steady periodic) solution is of the form

$$x_p(t) = C(\omega) \cos(\omega t - \alpha),$$

where

$$C(\omega) = \frac{F_0}{\sqrt{(k - m\omega^2)^2 + (c\omega)^2}}.$$

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Thus for  $\omega > 0$  there is a maximum (but finite!) value of  $C(\omega)$  occurs if  $c < \sqrt{2km}$ .

The  $\omega$  that causes this maximum  $C(\omega)$  results in **practical resonance**.