L14-S00

## Matrix inverses

MATH 2250 Lecture 14 Book section 3.5

September 20, 2019

Linear systems

## The identity matrix

We first define a special matrix, the  $n \times n$  identity matrix,

$$\boldsymbol{I} = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix}$$

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#### L14-S01

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This matrix effects multiplicative identity: if A is a matrix comprised of columns  $a_j$ 

$$\boldsymbol{A} = \begin{bmatrix} \boldsymbol{a}_1 & \boldsymbol{a}_2 & \cdots & \boldsymbol{a}_n \end{bmatrix},$$

then via matrix multiplication operations, we can see that

$$AI = [a_1 \ a_2 \ \cdots \ a_n] = A.$$

Similarly, one can show that IB = B for any matrix B with n rows.

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$$AB = BA = I.$$

If we can find such a matrix, we call B the **matrix inverse** of A, and write  $B = A^{-1}$ .

If A has a matrix inverse, we say that A is **invertible**.

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#### Example

Determine whether or not the following matrix is invertible, and if so compute its inverse.

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## L14-S03

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But with matrices, even if  $\boldsymbol{A}$  is not the zero matrix, sometimes we cannot invert it.

However, if an inverse exists, then it's unique:

#### Theorem

If an  $n \times n$  matrix A has a matrix inverse  $A^{-1}$ , then  $A^{-1}$  is the unique matrix inverse of A.

## $2\times 2$ matrix inverses

There is an explicit formula for the inverse of a  $2\times 2$  matrix:

#### Theorem

Consider a general  $2 \times 2$  matrix:

$$oldsymbol{A} = \left( egin{array}{c} a & b \ c & d \end{array} 
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Then A is invertible if and only if  $ad - bc \neq 0$ , and in this case its inverse is

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## Inverses of matrix products

#### L14-S05

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Inverses of matrix products involves a reversal of order: if A and B are both invertible matrices of the same size, then

$$(AB)^{-1} = B^{-1}A^{-1}.$$

Furthermore, for any integer  $k \ge 1$ ,

$$\left(\boldsymbol{A}^{-1}\right)^{k} = \left(\boldsymbol{A}^{k}\right)^{-1}$$

## Linear systems and matrix inverses

Recall that we often write linear systems with  $\boldsymbol{n}$  equations and  $\boldsymbol{n}$  unknowns in matrix form as

$$Ax = b$$
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where A is a known  $n \times n$  matrix, b is a known  $n \times 1$  vector, and x is the unknown  $n \times 1$  vector.

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#### Example

Use matrix inverses to solve the system

$$2x_1 + x_2 = 3 -x_1 + x_2 = 6$$

### L14-S07

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These row operations therefore transform A to I. Conceptually, we can use the same row operations to transform I to A.

Practically, we do this by performing Gaussian elimination on the matrix concatentation  $\begin{bmatrix} A & I \end{bmatrix}$ .

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## Example

Use Gaussian elimination to compute the matrix inverse of

$$\left(\begin{array}{cc} 2 & 1 \\ -1 & 1 \end{array}\right)$$

## $3\times3$ matrix inverse

#### L14-S08

#### Example

Compute the inverse of the matrix

$$\boldsymbol{A} = \left( \begin{array}{ccc} 4 & 3 & 2 \\ 5 & 6 & 3 \\ 3 & 5 & 2 \end{array} \right)$$

# Singular matrices

L14-S09

Matrix invertibility has strong connections to solutions of linear systems.

A square matrix A is called **singular** if the equation Ax = 0 has a solution  $x \neq 0$ .

A matrix that is not singular is **non-singular**.

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#### Theorem

If A is a square  $n \times n$  matrix, the following are all equivalent statements:

- 1. A is invertible.
- 2. A is non-singular (i.e., Ax = 0 is true only for x = 0)
- 3. A is row-equivalent to I.
- 4. The equation Ax = b has a unique solution for any  $n \times 1$  vector b.