



A Topology Based Visualization for Exploring Data with Uncertainty

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Outline

- Introduction
- Related Work
- Method
 - Contour Tree Layout and Tree View Graph Design
 - Contour Tree-Based Uncertainty Visualization
 - User Interface Design
- Experimental results
- Conclusion & Future Plans



Introduction

Why topology based visualization for uncertainty?

The challenges of handling 3D data with uncertainty

- Qualification
- Representation
- Interaction

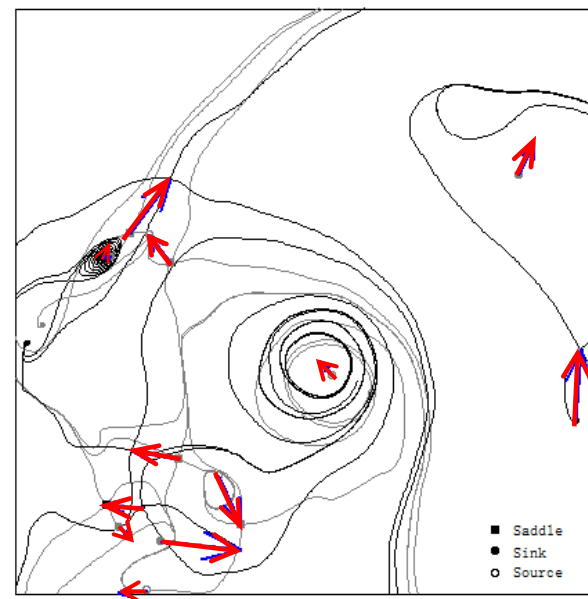
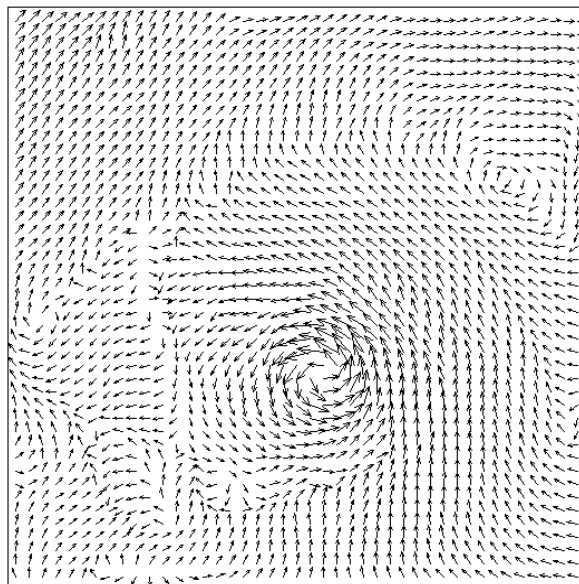
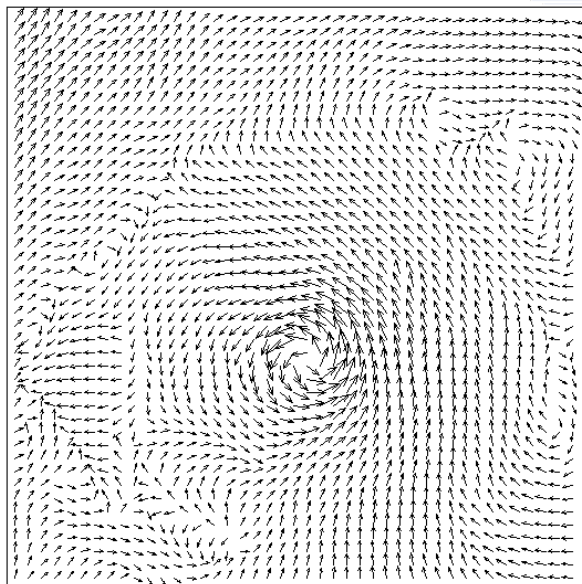
Challenges of handling uncertainty of 3D Data

Quantification

Data-level uncertainty: the uncertain numerical values of a data

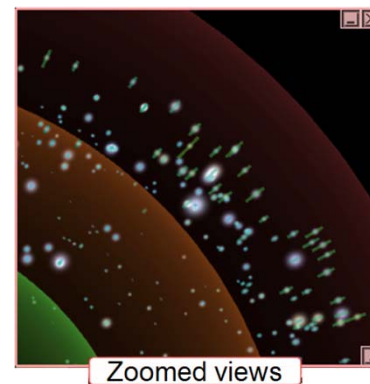
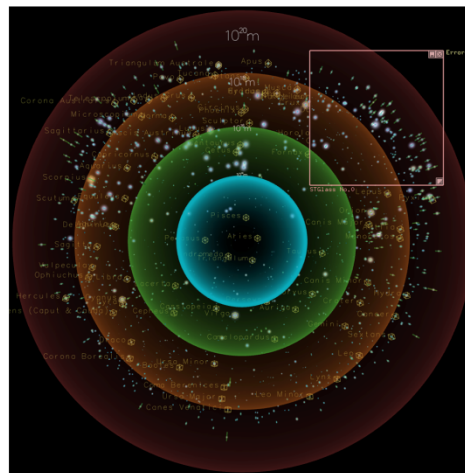
Feature-level error: the uncertain deviations of a feature, e. g., a sink or a source, a maximum or a minimum, in the data

The gap between data-level uncertainty and feature-level uncertainty ...

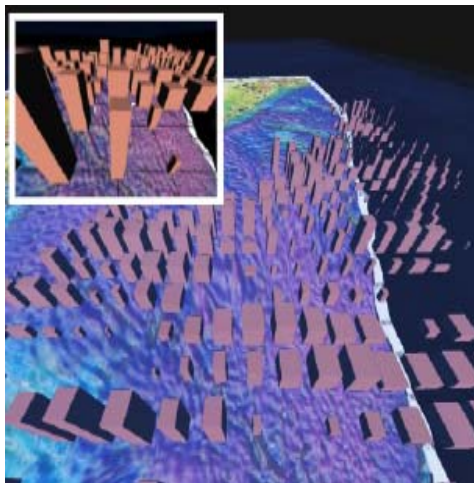


Representation

- Information overload
- Cluttered display
- Occlusion

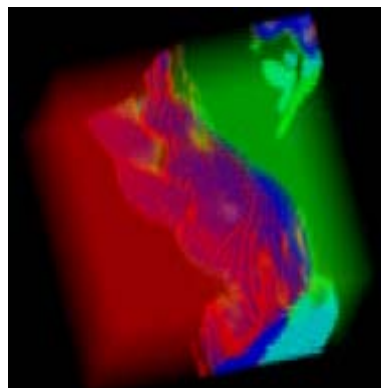


Positional uncertainty of stars
with error bars, H. Li, 2007



Box glyphs
Schmidt, 2004

Uncertainty Volume Rendering
S. Djurcilov, 2001



Interaction

- Geometry bandwidth bottle neck
- Depth perception, cluttering, and occlusion
- Interaction inconvenience with 3D objects

The integrated visualization of both data and uncertainty information intensifies these issues!

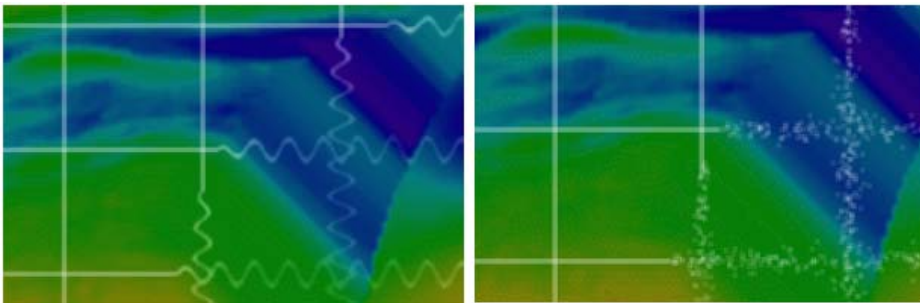


Related Work

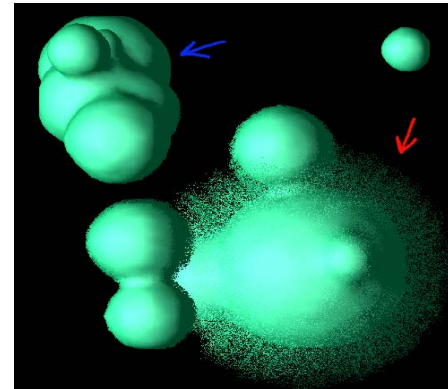
- General Uncertainty visualizations
- Contour uncertainty visualizations
- Contour tree and its applications

Uncertainty Visualization

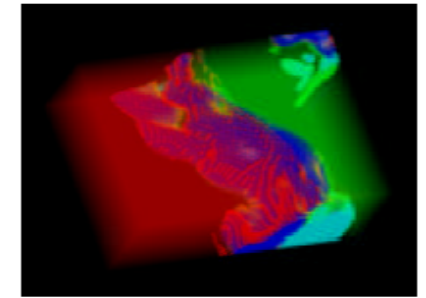
- **Visual blurring**



Procedural Annotation [Cedilnik 1997]

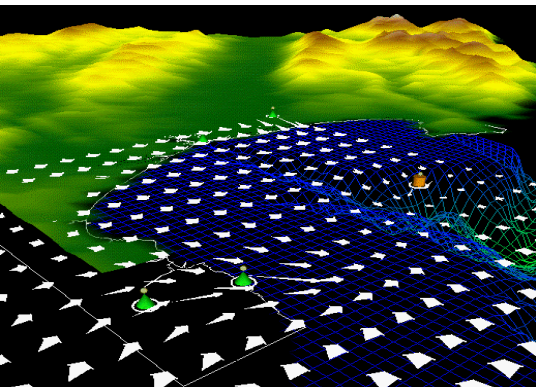


Point-based uncertainty model [Grigoryan 02]

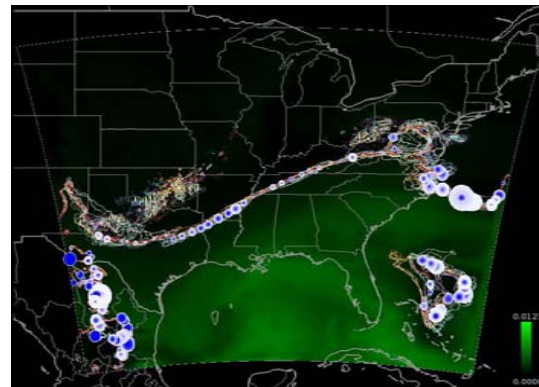


Uncertainty Volume Rendering [Djurcilov 01]

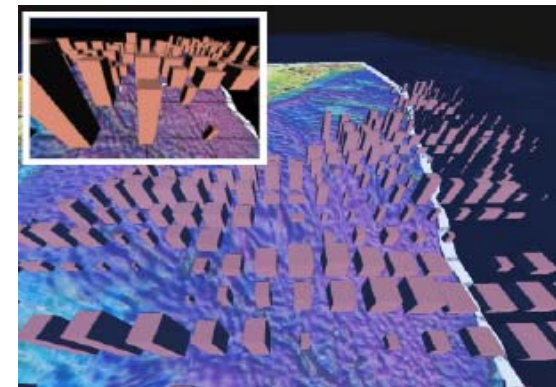
- **Quantitative glyph**



Vector glyph [Wittenbrink 96]



Graduated glyph [sanyal 2010]



Box glyphs [Schmidt 2004]

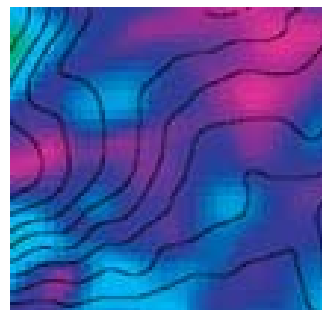
- **Animation, sonification, psycho-visual approaches, etc**

Uncertainty about contours

Probabilistic Iso-surface: random variable F at each data point with density function $f(z)$

Ken Brodlie, et al. 2008

Measurement errors:
Normal distribution

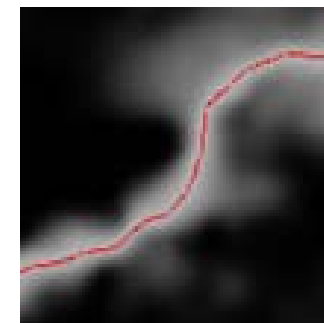


RMS error

Rounding errors:
Uniform distribution

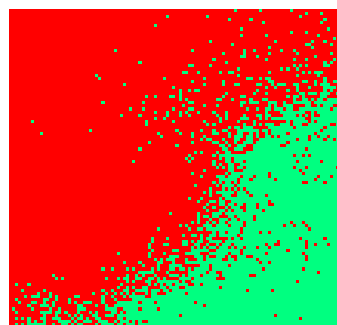


Contour bond

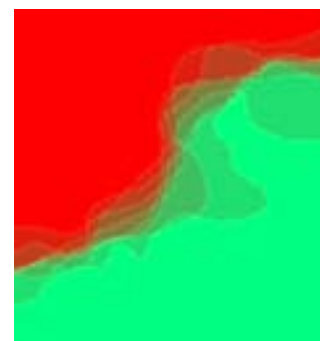


Fuzzy Contour

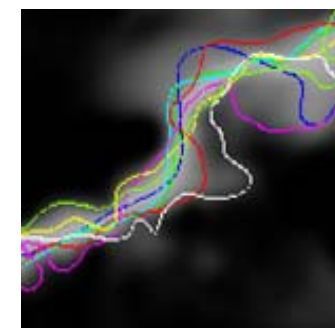
Ensemble computing:
Distribution derived from data



Probabilistic Model



Overlapping

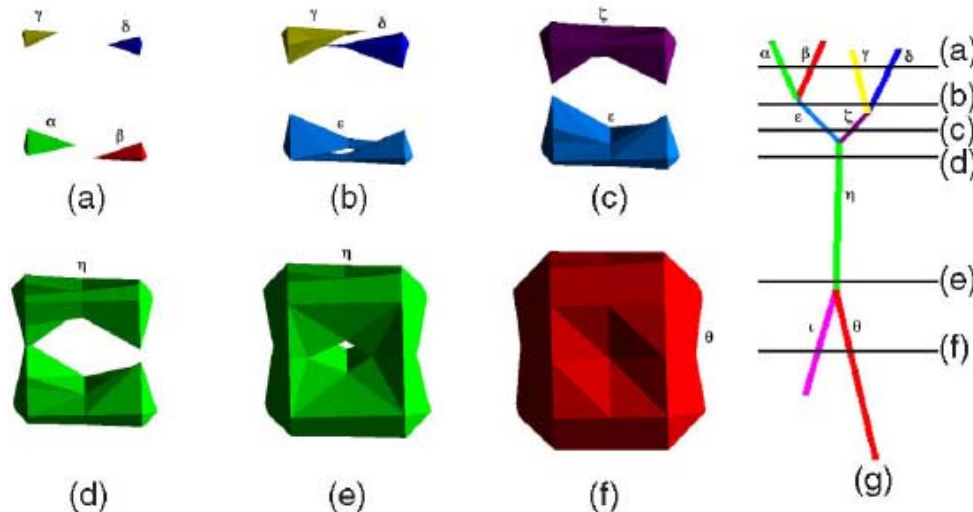


Spaghetti plots
looking at each model

Contour Tree

- A Contour Tree (CT):

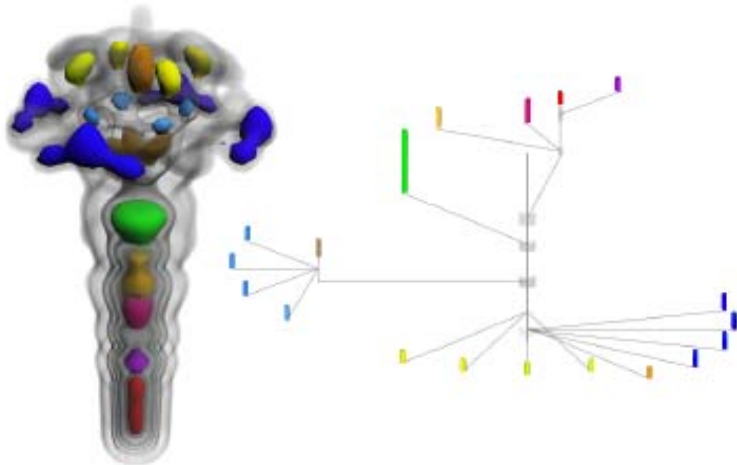
- A graph that tracks the evolution of contours in a scalar function
- Each edge represents a set of adjacent and uniform contours
- Each node represents a critical point where contours appear, disappear, or merge as the function value increases.
- One-one mapping from points in the tree to the contours of a scalar field



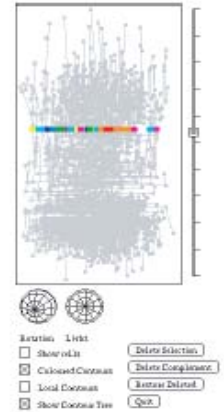
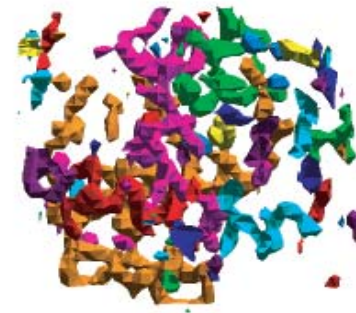
A scalar field (left) and its contour tree (right)

Contour Tree

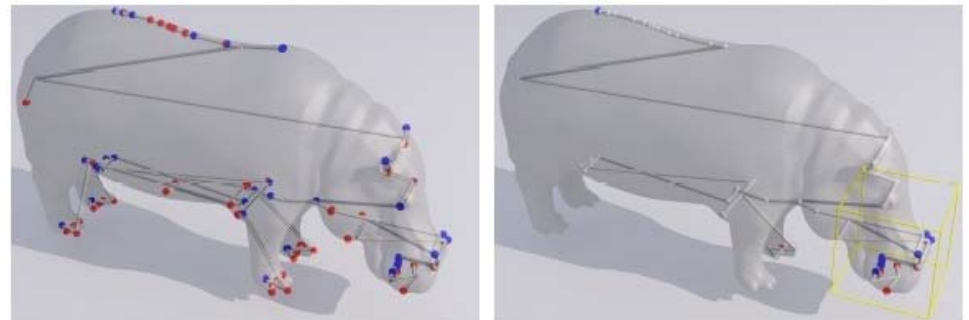
- Contour tree provide effective tools in many applications
 - Iso-value selection
 - Transfer function design
 - Hierarchical representation



Transfer function design using contour tree, [S. Dillard, 2007](#)



Contour selection for a molecule
[H. Carr, 2003](#)



Hierarchical contour tree
[V. Pascucci, 2004](#)



Method

- Method Overview
- Contour Tree Layout and Tree View Graph Design
- Contour Tree-Based Uncertainty Visualization
- User Interface Design

Method Overview

- Our goal:
 - Develop interactive tool to explore uncertain data
 - Fully explore uncertainty in data-level, contour-level, and topology level with intuitive uncertainty representation

Method Overview

- Method Components

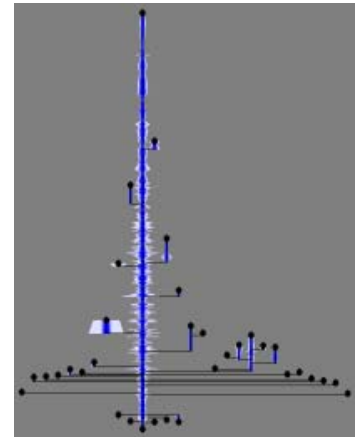
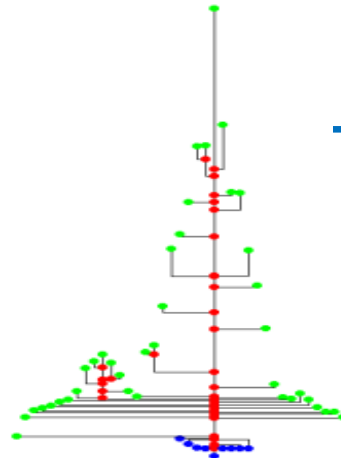
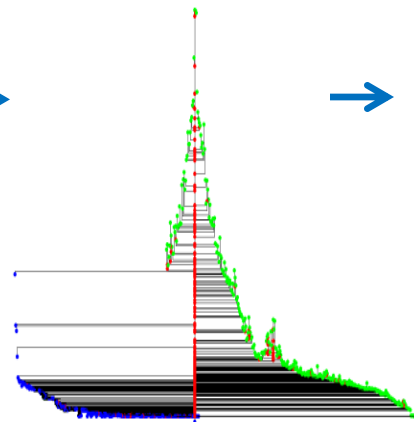
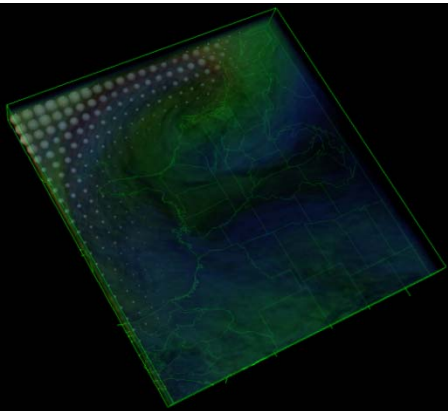
- Contour tree extraction [Carr et al. 2003]
- Contour tree simplification, layout, and interaction
- Contour tree-based uncertainty representation
- User interface

- Method Pipeline

Extract CT

Simplify CT

Represent uncertainty



Contour Tree simplification, Layout, and Interaction

- Contour tree simplification
- Contour tree layout
- Tree View Graph interaction design

Contour Tree Simplification

- Introduced to help represent and interact with large CTs
- Usually cancel edges repeatedly with increasing importance

Cancel a CT edge

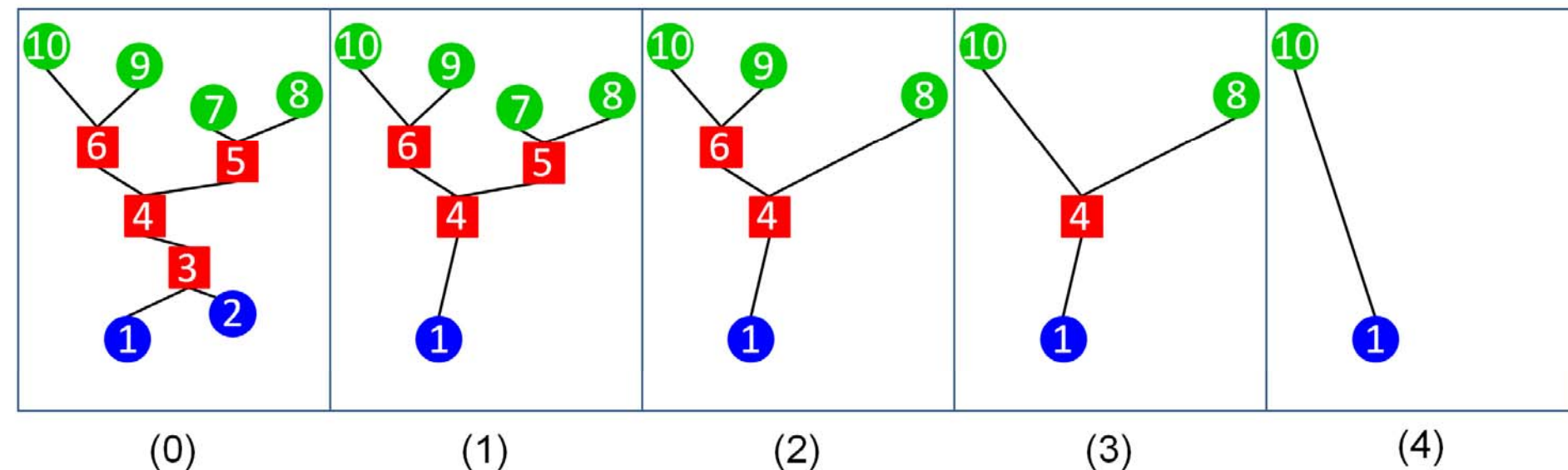


Persistence: the absolute difference in function value spanned by the two end points of a edge

Contour Tree Simplification

- Introduced to help represent and interact with large CTs
- Usually cancel edges repeatedly with increasing importance

Traditional bottom-up simplification



Contour Tree Simplification

New Top-down Contour Tree Simplification

- Find edges in decreasing persistence
- How it works?

The idea: Find reversed edge cancelation order of a bottom-up simplification

Two new lemmas:

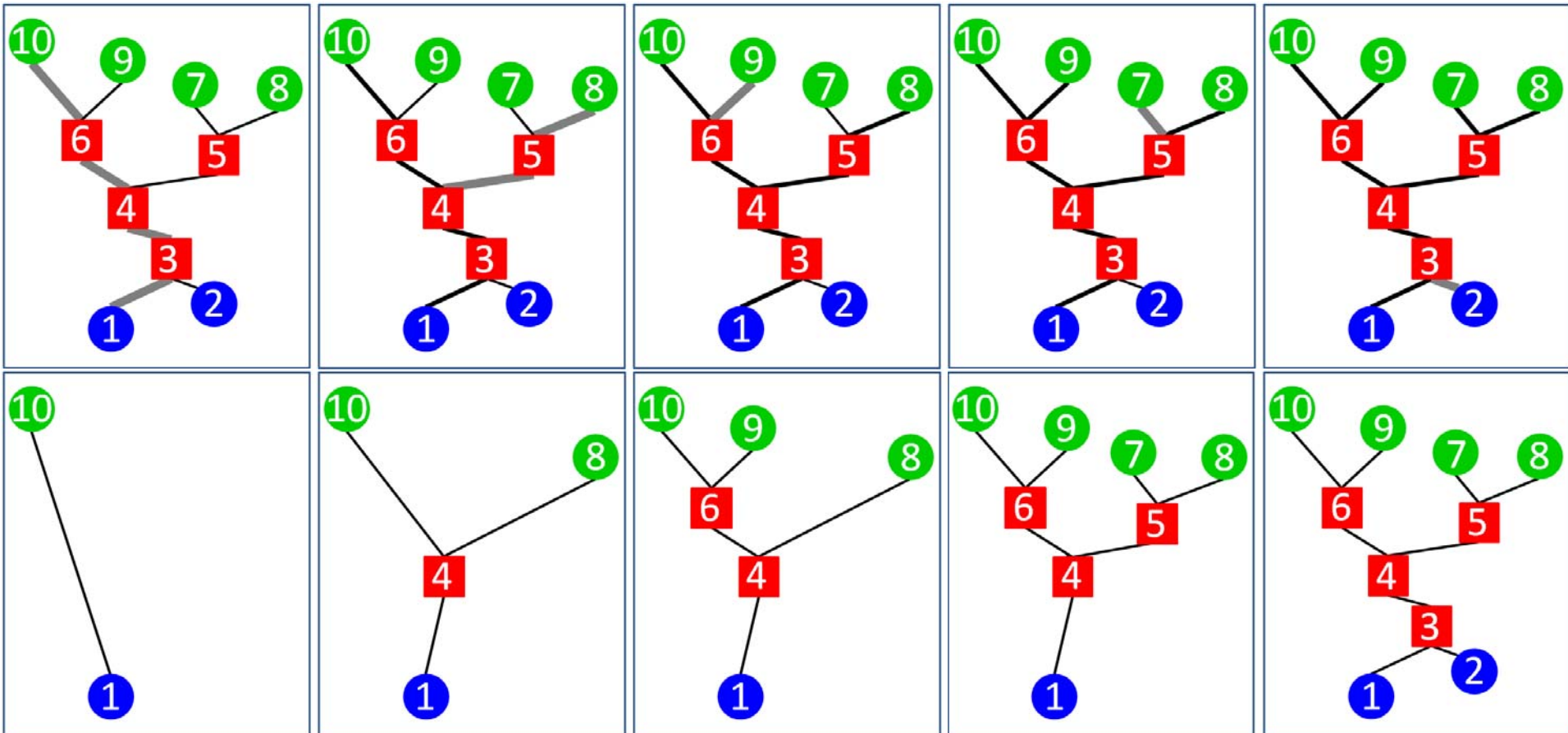
Lemma 1 The last cancelled pair in a bottom-up simplification is the pair of lowest minimum and the highest maximum that is searchable through a monotone path of CT.

Lemma 2 The $n+1$ th cancelled pair in a bottom-up simplification is the pair with the highest persistence among all the child branches in the simplified CT after cancelling n pairs.

Contour Tree Simplification

New Top-down Algorithm

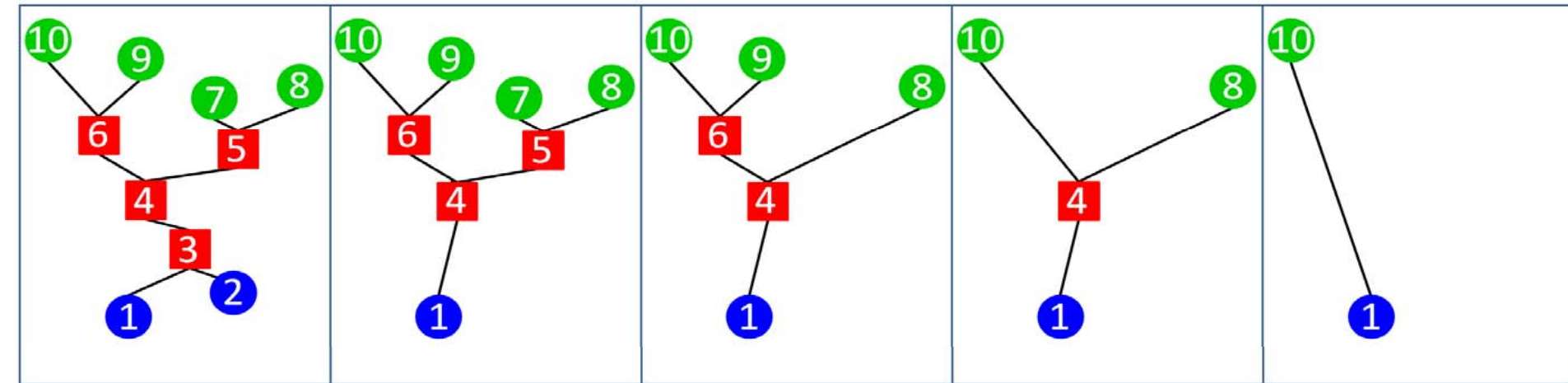
Top-down contour tree simplification



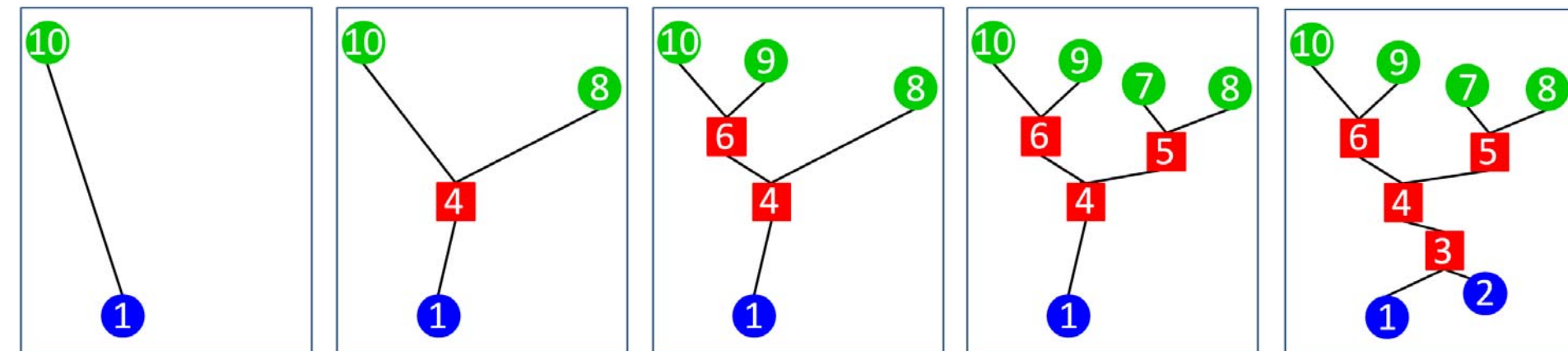
Contour Tree Simplification

Top-down Simplification VS Bottom-up Simplification

Bottom-up simplification - faster when the contour tree is small



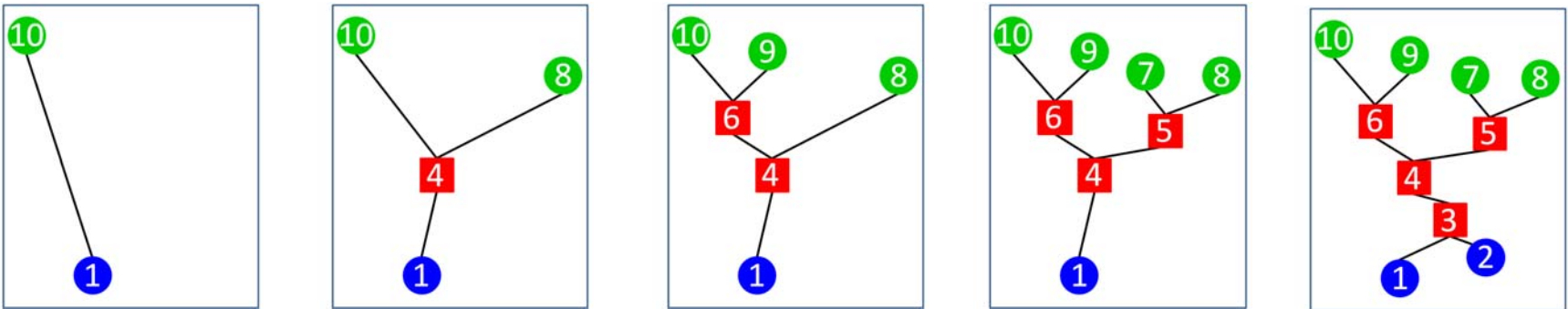
Top-down simplification - faster when the contour tree is large



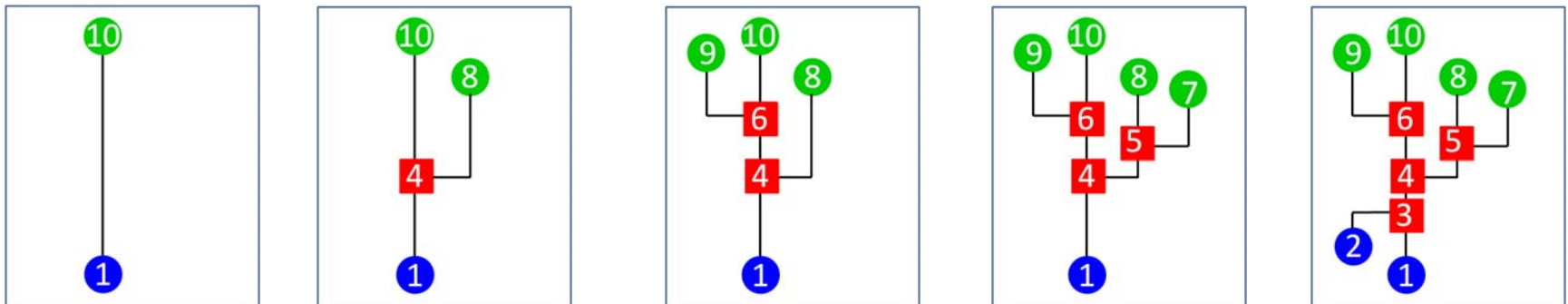
Contour Tree Layout Design

- The idea:
 - Recursively assign vertical slots to the branches of a CT
 - Driven by the top-down simplification

Grow ...

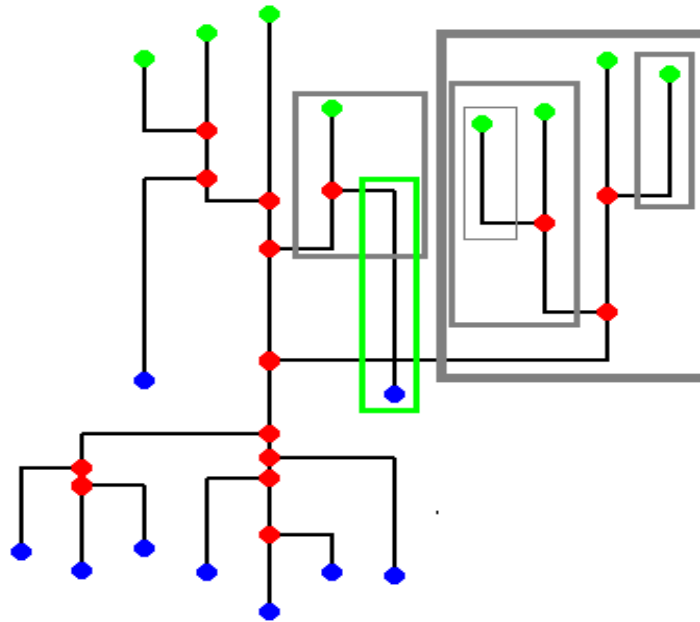


Display ...



Contour Tree Layout Design

- The idea:
 - Recursively assign vertical slots to the branches of a CT
 - Driven by the top-down simplification

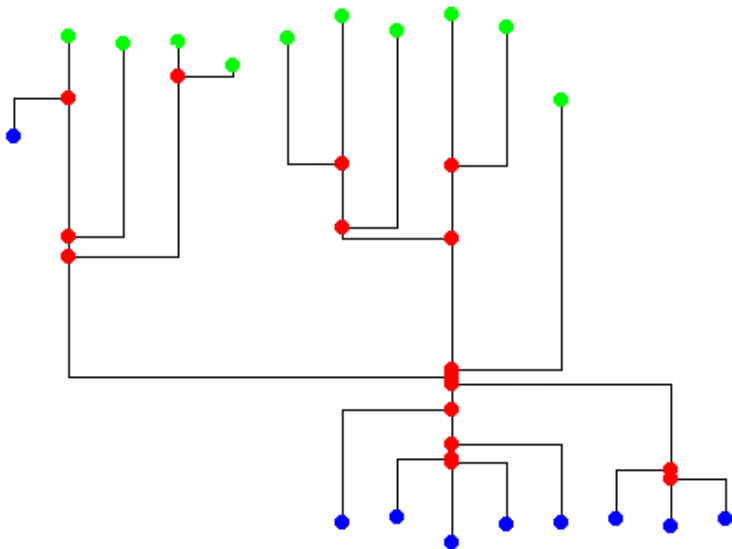


CT Simplification, Layout, and Interaction

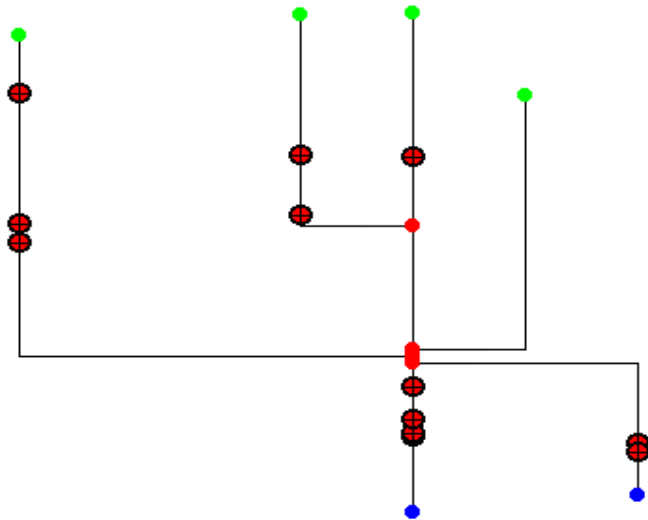
Interact with CT - Tree View Graph

- **The idea:**

- Adopt the intuitive tree view graph
- Users can collapse (or expand) a particular sub-tree to hide (or show) the items included in that sub-tree.



Original CT displayed with the new planar layout



Interactively simplified CT after user clicked on several nodes

CT-Based Uncertainty Visualization

- **Data-Level Uncertainty**
- **Contour-Level Uncertainty**
- **Topology-Level Uncertainty**

Data-level Uncertainty Visualization based on CT

- What is it?
 - The data-level uncertainty measures how uncertain the numerical values of data are along the contours
 - Measured by standard deviation (SD), inter-quartile range (IQR), and the confidence intervals (CI)
- Why visualize data-level uncertainty based on CT?
 - Avoid the issues when visualizing uncertainty within volume data (limited glyph resolution, cluttering, and occlusion)

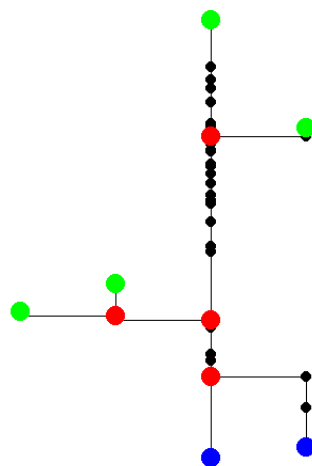
Data-level uncertainty Visualization based on CT

- How to visualize data-level uncertainty based on CT?
 - Attach uncertainty glyphs to a fully augmented CT
 - Avoid the visual cluttering and occlusion of viewing uncertainty within volume data



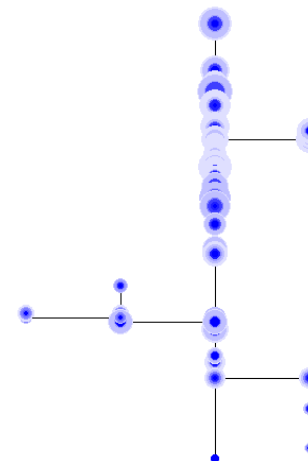
Circular graduated glyphs
Sanyal, 2010

+



A fully augmented CT
(with all the vertices of the data)

=



CT with uncertainty glyph

Contour-level uncertainty visualization based on CT

- What is it?
 - Contour-level uncertainty measures the positional uncertainty of a contour
- Why visualize contour-level uncertainty?
 - Users are interested in the most stable or unstable contours
 - Users' estimates tend to be inaccurate due to the randomness of the contour shape and length

Contour-level uncertainty visualization based on CT

- How to visualize contour-level uncertainty based on CT?

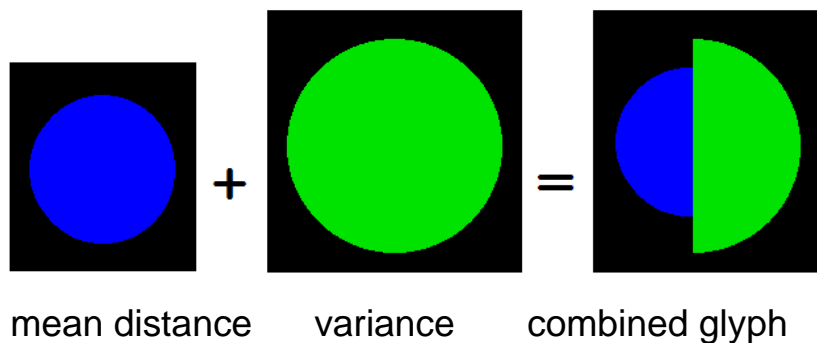
Let a contour of the ensemble mean be C , and corresponding contours of individual ensemble be $C_i, i=1, \dots, k$.

Two uncertainty metrics:

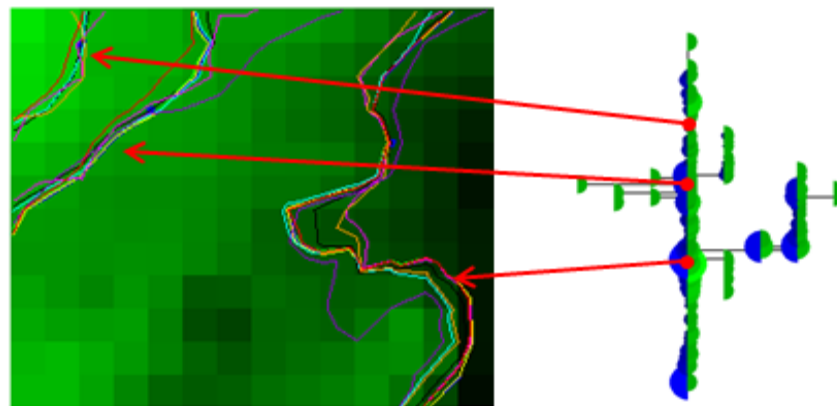
- (1) Average distance among contours of individual ensemble members:

$$mean = \sum distance(C, C_i) / k$$

(2) Variance:
$$va = \frac{\sum (difference(C, C_i) - mean)^2}{k}$$



Contour-level uncertainty glyph design



Each glyph on CT indicates uncertainty of a corresponding contour

Topology-level uncertainty visualization based on CT

- What is it?
 - Topology-Level Uncertainty measures uncertainty concerning the difference of Contour Tree among the ensemble members
- Why visualize topology-level uncertainty based on CT?
 - Contour tree summarize the topology of contours
 - A key to uncover how uncertain the topology is

CT-Based Uncertainty Visualization

Topology-level uncertainty visualization based on CT

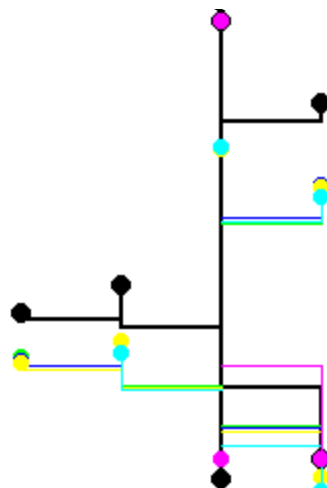
- How to visualize topology-level uncertainty based on CT?

The idea: Overlay the CTs of different ensemble members and the ensemble mean

Repeat for branches from high to low hierarchy:

Step 1: measure the distance between branches (s_a, u_a) in CTa and (s_b, u_b) in CTb at the same CT hierarchy $|f(s_a) - f(s_b)| + |f(u_a) - f(u_b)|$

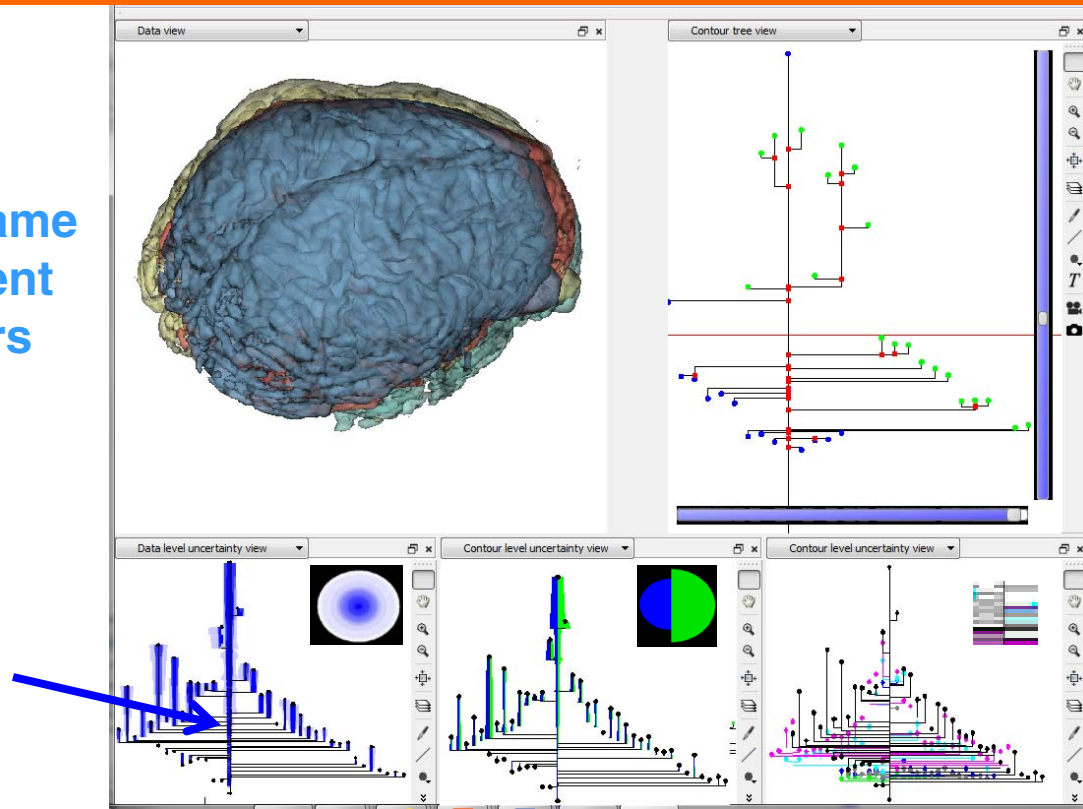
Step 2: Render the best matched branches (with minimum distance) of different CTs with the same horizontal location



All the matched branches are drawn with same x-coordinate

User Interface

Contours of the same iso-value in different ensemble members

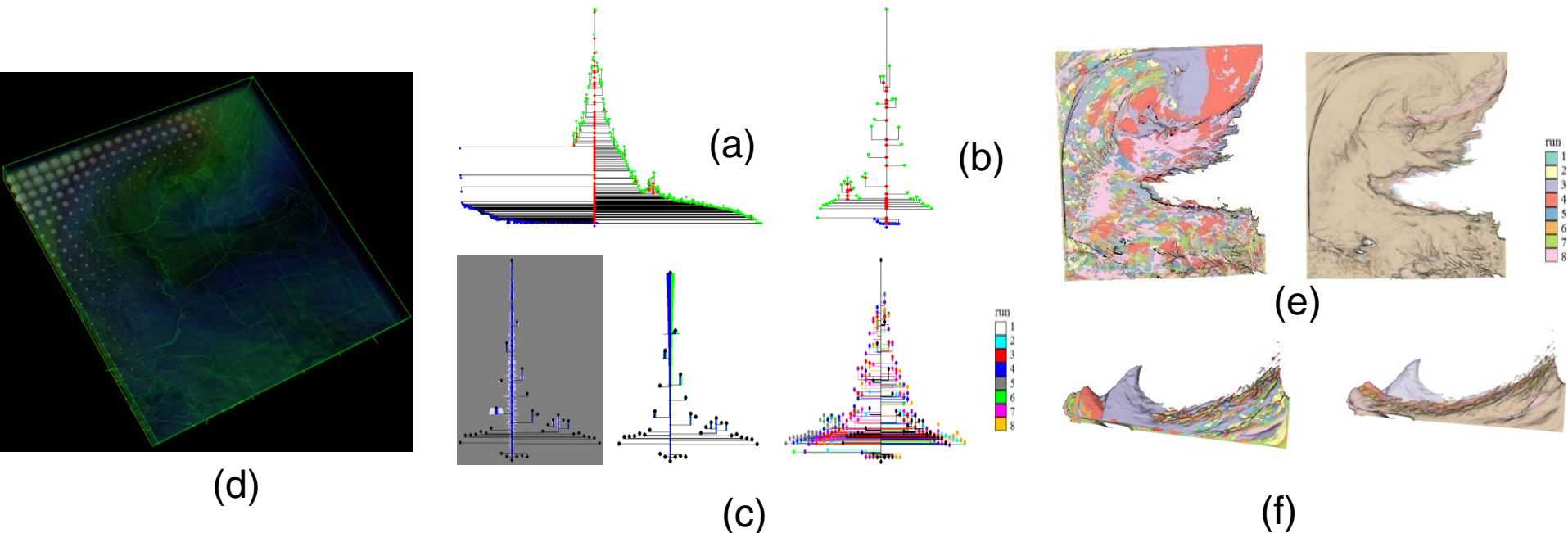


- (1) Use a horizontal slider on the bottom of the CT display to decide how many branches to be shown
- (2) Work on the tree view graph to remove the unwanted sub-trees
- (3)** Select contours to display by double-clicking on the CT based on the quantified uncertainty information attached in the CT

Experiments

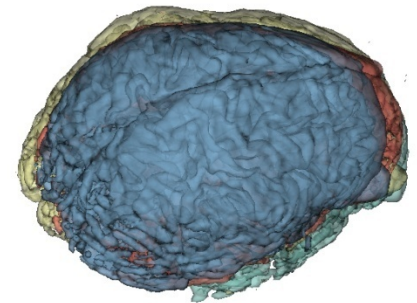
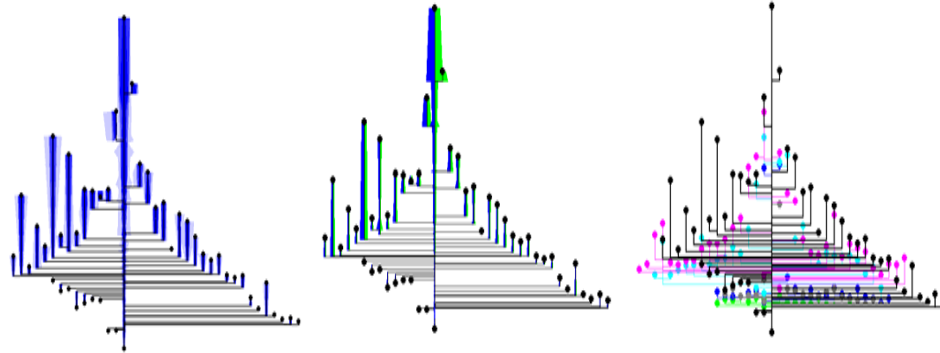
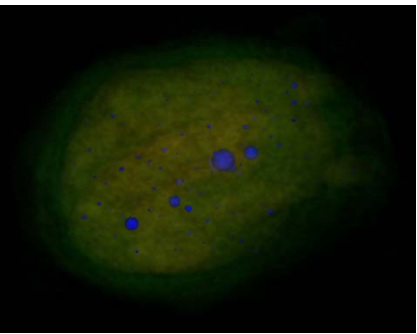
- WRF simulated data ensembles
- Volumetric medical data

WRF Weather ensembles



Weather data application. (a) Original contour tree. (b) Simplified contour tree. (c) Left to right: data-level uncertainty, contour-level uncertainty, and topology-level uncertainty shown in the simplified contour tree. (d) Volume rendering with uncertainty glyphs. (e) A set of contours with high data-level uncertainty. (f) A set of contours with high contour-level uncertainty. Both non-transparent and transparent iso-surfaces are shown.

Volumetric human brain



(a)

(b)

(c)

Medical data. (a) Volume rendering with uncertainty glyphs. (b) Three level of uncertainties shown in simplified contour tree. (c) A contours (of the same iso-value in different data)

Conclusion & future plan

- **Contributions:**
 - An efficient CT top-down simplification
 - A planar CT layout with low self-intersections and tree view graph interaction
 - A new paradigm of visualizing uncertainty based on CT with data-level, contour-level, and topology-level of
 - An interactive CT-based visualization for exploring 3D data guided by quantified uncertainty information

Conclusion & future plan

- **Future Plan**
 - Perfect uncertainty measurement, visualization effect, and interface design
 - Domain expert evaluation

Acknowledgments

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Question & Suggestion

