Mechanical Properties of Snow as a Random Heterogeneous Material using Uintah

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March 17, 2008

Fourth International MPM Workshop, University of Utah

Outline

- Motivation
- Stochastic reconstruction of snow microstructure
- Representative Volume Element
 - Elastic
 - Viscoplastic
- Application Microscale plane strain indentation
- Future work







Motivation: large uncertainties in properties

- Environmental conditions dictate snow metamorphism ('sintering' process)
- Metamorphism determines microstructure
- Microstructure determines properties
 - Mechanical (elasticity, viscoplasticity, damage, fracture...)
 - Physical (thermal conductivity, permeability, dielectric constant...)
- Density alone is insufficient to characterize properties
- Process -> microstructure -> properties







Applications

- Vehicle-snow interaction (ground and air vehicles)
- Civil infrastructure (foundation, pavement, runway ...)
- Avalanche
- Sports
- Geophysical
- Extraterrestrial (comets ...)







Vehicle-Snow Interaction

Tire/Vehicle Dynamics



Tire-Snow Interactions







Tire Models









2-D Tire-Snow Interaction: Abaqus, 200 kg/m^3, Drucker-Prager (CRREL) model



Density distribution, grey region indicates density larger than 700 kg/m3

Stochastic Reconstruction of Snow Microstructure from X-Ray Tomography Images

- Properties of snow strongly depend on microstructure one major source of uncertainties
- Structure-property relationships needed to understand physical mechanisms of deformations and failure
- Build digital stochastic models to represent snow microstructures
- Stochastic geometry and mechanics







What is stochastic reconstruction?



Real microstructure

Simulated one

Generate a simulated microstructure having the same statistical characteristics as the real one

Statistical Information from Snow Microstructure

Porosity (pore volume fraction)



Probability that two points a distance r apart will lie in pore space

Two-point probability function

Reconstruction Steps using Gaussian Random Fields

- 1. Find one-point and two-point correlation functions from snow images
- 2. Solve for level cut parameter

$$\alpha = \sqrt{2} \operatorname{erf}^{-1} \left(1 - 2p_{expt} \right)$$

Determine function g from experimental one-point and two-point correlation functions by solving:

$$I(g(r_i)) = 2\pi \left(p_{\text{expt}} - p_{\text{expt}}^{(2)}(r_i) \right)$$

- 3. Solve three unknown parameters in g: ξ , r_c , d
- 4. Numerically generate Fourier transform coefficients
- 5. Perform 3D inverse FFT to generate discrete GRF
- 6. Perform one-level cut to get phase function in spatial domain

$$p_{\text{expt}}, p_{\text{expt}}^{(2)}(r_i) \to \alpha, g(r_i) \to \xi, r_c, d \text{ (i.e. } \rho(k)) \to Y_{\alpha\beta\gamma} \to y_{lmn} \to \phi(\mathbf{r}_{lmn})$$







Skyscan 1172 Microtomography



Snow Sample Holder



Grey-level Cross-Sectional Image Sieved Snow < 1 mm Grain Size



Brighter pixels represent ice

7.344 mm by 7.344 mm, density 387 kg/m³ Resolution:1225 by 1225, Pixel size: 6 micron

3-D Visualization of a Cube of Snow Microstructure Side Length = 3.618 mm



Link to reconstructed

Reconstruction results



Reconstruction Results



Link to real one

Reconstructed microstructure

Representative Volume Element (RVE)

- Definition
- Elastic Properties
 - Theoretical bounds
 - Initial results
- Viscoplastic Properties
 - SUVIC-I
 - Initial results







Representative Volume Element (RVE) for Mechanical Properties

- Definition (Nemat-Nasser and Hori):
 - RVE for a material point of a continuum mass is a material volume which is statistically representative of the infinitesimal material neighborhood of that material point.
 - RVE is the volume element over which homogenization can be performed.
 - Size of an RVE depends on the physical or mechanical properties of interest.
 - Size of an RVE requires a tolerance.
 - Size of an RVE should be independent of boundary conditions.
 - Size of volume smaller than RVE is called an SVE (statistical volume element).







Return

RVE of Elastic Moduli

- Numerical calculation of elastic moduli of scanned images and reconstructed volume.
- Using elastic material properties so 'error' due to creep or timedependent effects won't be present.
- Relatively 'easy' to conduct.
- Several numerical methods available finite element method using voxel-based or solid-based mesh.
- Material Point Method (MPM) used:
 - Snow is considered as a semi-granular material.







Elastic Moduli using Uintah MPM Implicit

- Unconfined compression
- Load-displacement -> Macroscopic stress and strain ->Young's modulus and Poisson's ratio
- Largest size 2.8 million cells, 83 million particles
- Nominal density 387 $\frac{kg}{3}$
- Ice properties
 - Young's modulus 9.3 GPa
 - Poisson's ratio 0.325







Hashin-Sritkman Upper Bound

 ϕ_1 = volume fraction of air ϕ_2 = volume fraction of ice

G, K = Shear and bulk modulus of ice.

$$K_{U} = K\phi_{2} - \frac{\phi_{1}\phi_{2}K^{2}}{K\phi_{1} + \frac{4}{3}G}$$
$$G_{U} = G\phi_{2} - \frac{\phi_{1}\phi_{2}G^{2}}{G\phi_{1} + H_{2}}$$
$$H_{2} = G\left[\frac{\frac{3}{2}K + \frac{4}{3}G}{K + 2G}\right]$$

Uintah Results - Young's Modulus



Uintah Results - Poisson's Ratio



Viscoplasticity SUVIC-I (Aubertin and Lee)

- Strain rate history-dependent Unified Viscoplastic model with Internal variables for Crystalline materials Ice
- Isotropic polycrystalline ice at

 $T \ge -55^{\circ}C; 10^{-8} \le \varepsilon \le 10^{-2} s^{-1}; 0.04 \text{MPa} \le \sigma_{eqiv} \le 20 \text{ MPa}$

- Unified model plasticity, creep and their interactions are modeled in the same way
- Three internal variables: back stress (kinematic hardening), yield and drag stress (isotropic hardening)
- Evolution of the state variables: combined action of hardening, dynamic recovery
- Viscoplastic introduction of a yield surface makes a clear distinction between elastic and inelastic behavior.







SUVIC-I - continued

- Part of the inelastic strains are recoverable grain boundary sliding, reverse motion of dislocations (backstress)
- Hardening has mixed (kinematic and isotropic) nature related to the existence of internal stresses
- Kinematic hardening due to backstress created by directional obstacles to dislocations motion.







Summary of SUVIC-I

 $\dot{\varepsilon}_{ij} = \dot{\varepsilon}_{ij}^e + \dot{\varepsilon}_{ij}^i; \quad \dot{\varepsilon}_{ij}^e = \frac{S_{ij}}{2C} + \frac{\dot{\sigma}_{kk}}{\Omega K} \delta_{ij}.$ $\dot{\varepsilon}_{ij}^{i} = A \left\langle \frac{X_{ae} - R}{K} \right\rangle^{N} n_{ij} \exp\left(-\frac{Q}{R T}\right), \ n_{ij} = \frac{3}{2} \frac{S_{ij} - B_{ij}}{X},$ $X_{ae} = \sqrt{\frac{3}{2} \left(S_{ij} - B_{ij} \right) (S_{ij} - B_{ij})}$ $\dot{\varepsilon}_{e}^{i} = \sqrt{\frac{2}{3}} \dot{\varepsilon}_{ij}^{i} \dot{\varepsilon}_{ij}^{i} = A \left\langle \frac{X_{ae} - R}{K} \right\rangle^{N} \exp\left(-\frac{Q}{R T}\right)$ $\dot{B}_{ij} = \frac{2}{3} A_1 \dot{\varepsilon}^i_{ij} - \frac{A_1}{B} B_{ij}, B_e = B_0 \left(\frac{\dot{\varepsilon}^i_e}{\dot{\varepsilon}}\right)^{\frac{1}{n}}$ $\dot{R} = A_3 \dot{\varepsilon}_e^i \left(1 - \frac{R}{R} \right), \dot{K} = A_5 \dot{\varepsilon}_e^i \left(1 - \frac{K}{K} \right).$ $R' = R_0 \left(\frac{\dot{\varepsilon}_e^i}{\dot{\varepsilon}_0}\right)^{\frac{1}{n}}, K' = \left(\frac{\dot{\varepsilon}_e^i}{A \exp\left(-\frac{Q}{R T}\right)}\right)^{N} \left(X_{ae}' - R'\right)$ $X_{ae} = \sigma' - B_{e}; \sigma' = \sigma_0 \left(\frac{\dot{\varepsilon}_{e}^i}{\dot{\varepsilon}}\right)^{\frac{1}{n}}$

Numerical Integration

$$\begin{split} \Delta \varepsilon^{i} &= \Delta t \left[(1 - \theta) \dot{\varepsilon}_{t}^{i} + \theta \dot{\varepsilon}_{t + \Delta t}^{i} \right]; \ 0 \leq \theta \leq 1 \\ \dot{\varepsilon}_{t + \Delta t}^{i} &= \dot{\varepsilon}_{t}^{i} + \sum_{i} \frac{\partial \dot{\varepsilon}^{i}}{\partial \beta_{i}} \dot{\beta}_{i} \Delta t. \\ \dot{\sigma}_{ij} &= \left[L_{ijkl} - \frac{\xi}{1 + \xi} \frac{1}{\bar{H}} P_{ij} Q_{kl} \right] \dot{\varepsilon}_{kl} - \frac{\dot{\varepsilon}_{t}^{i}}{1 + \xi} P_{ij} \end{split}$$







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Viscoplastic Behavior – Uintah MPM Implicit SUVIC-I



Microscale Plane Strain Indentation (1/3) (7.344mm x 7.344mm x 0.012 mm) Uintah MPM Implicit SUVIC-I













Microscale Plane Strain Indentation (2/3)









Plane Strain Indentation @20% strain (3/3)



Future Work

- Obtain statistical distributions of the elastic and tangent moduli of real and simulated snow
- Optimize the code for SUVIC-I
- Implement damage, failure models of ice into Uintah
- Conduct simulations of triaxial cell and micropenetrometer (snow pen)
- Conduct microscale tension/compression experiments inside MicroCT and compare with simulations
- Develop continuum constitutive laws
- ...







Acknowledgements

- Dr. James Guilkey (University of Utah) for MPM and Uintah
- Dr. Sally Shoop (US Army CRREL) for vehicle-snow interaction
- Dr. Jerry Johnson (US Army CRREL) for snow physics
- Automotive Research Center (ARC) an Army Center of Excellence in the modeling and simulation of ground vehicles led by the University of Michigan
- U.S. Army TARDEC and YPG
- UAF Arctic Regions Supercomputing Center (ARSC)







Thank You!

Questions?





