Geometric Transformations and Image Warping: Mosaicing

CS 6640 Ross Whitaker. Guido Gerig SCI Institute, School of Computing University of Utah

(with slides from: Jinxiang Chai, TAMU)

faculty.cs.tamu.edu/jchai/cpsc641_spring10/lectures/lecture8.ppt

Applications

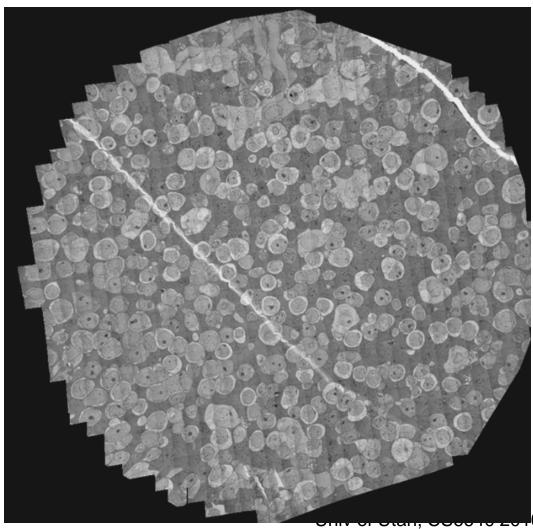


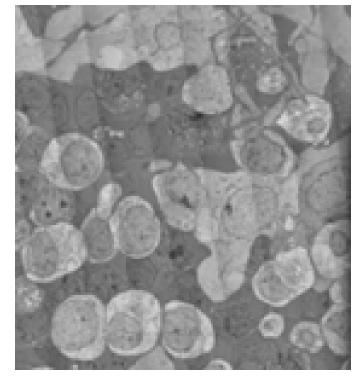
Saint-Guénolé Church of Batz-sur-Mer Equirectangular 360° by Vincent Montibus

Univ of Utah, CS6640 2010

×

Microscopy (Morane Eye Inst, UofU, T. Tasdizen et al.)







Mosaic Procedure

Basic Procedure

- Take a sequence of images from the same position
 - Rotate the camera about its optical center
- Compute transformation between second image and first
- Transform the second image to overlap with the first
- Blend the two together to create a mosaic
- If there are more images, repeat

Image Mosaic

Is a pencil of rays contains all views

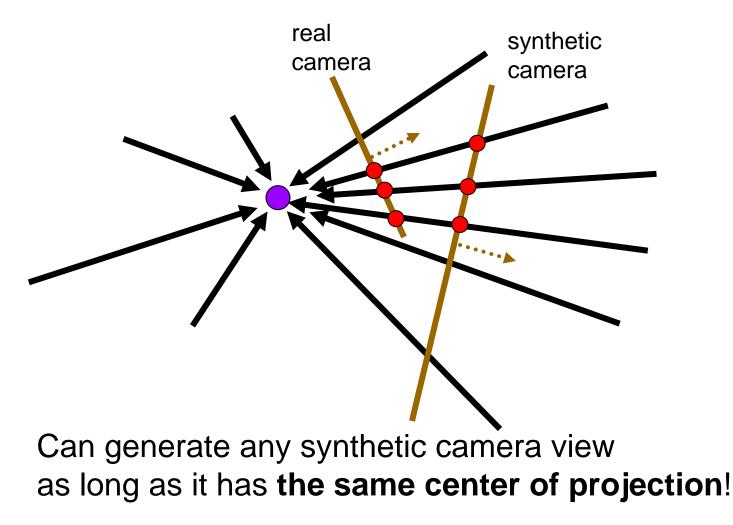
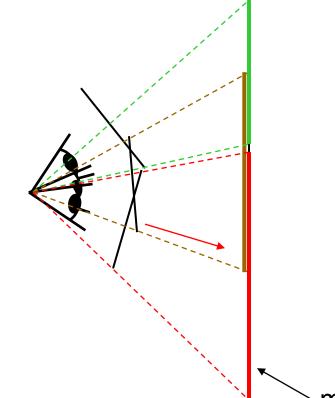


Image Re-projection



mosaic PP

The mosaic has a natural interpretation in 3D

- The images are reprojected onto a common plane
- The mosaic is formed on this plane
- Mosaic is a synthetic wide-angle camera

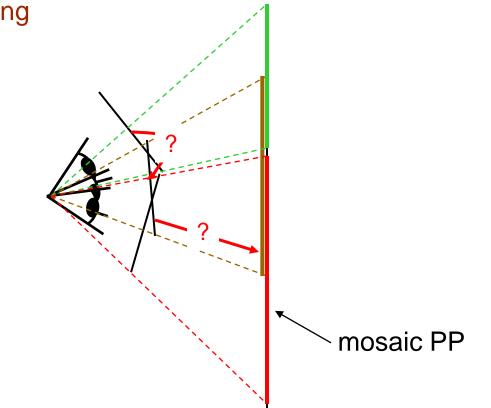
Issues in Image Mosaic

How to relate two images from the same camera center?

- image registration

How to re-project images to a common plane?

- image warping



3D Perspective and Projection

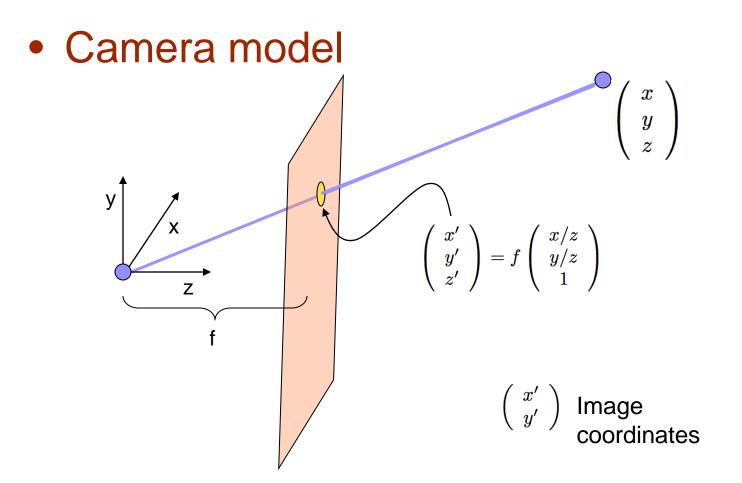


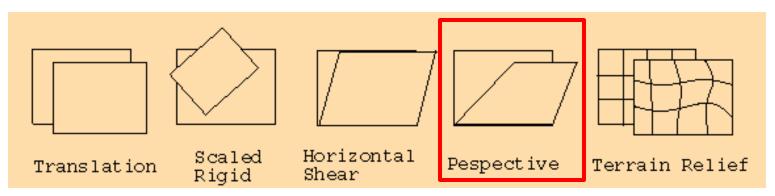
Image Homologies

 Images taken under cases 1,2 are perspectively equivalent to within a linear transformation

- Projective relationships - equivalence is

$$\left(\begin{array}{c}a\\b\\c\end{array}\right) \equiv \left(\begin{array}{c}d\\e\\f\end{array}\right) \iff \left(\begin{array}{c}a/c\\b/c\\1\end{array}\right) = \left(\begin{array}{c}d/f\\e/f\\1\end{array}\right)$$

Transformations



$$\begin{pmatrix} X' \\ Y' \\ 1 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

affine

$$\begin{pmatrix} X' \\ Y' \\ W \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

New image coordinates can be found as $x^\prime = X^\prime / W, \, y^\prime = Y^\prime / W$

x', y': homographies

Materials

- Excellent material to derive homography matrix:
 - <u>www.cs.toronto.edu/~jepson/csc2503/tutor</u> <u>ial2.pdf</u>
 - <u>www.cs.toronto.edu/pub/jepson/teaching/vi</u> <u>sion/2503/tutorial2.pdf</u>

Perspective Projection Properties

- Lines to lines (linear)
- Conic sections to conic sections
- Convex shapes to convex shapes
- Foreshortening



Transforming Images To Make Mosaics

Linear transformation with matrix P

$$\bar{x}^* = P\bar{x} \qquad P = \begin{pmatrix} p_{11} & p_{12} & p_{13} \\ p_{21} & p_{22} & p_{23} \\ p_{31} & p_{32} & 1 \end{pmatrix} \qquad \begin{array}{ccc} x^* & = & p_{11}x + p_{12}y + p_{13} \\ y^* & = & p_{21}x + p_{22}y + p_{23} \\ z^* & = & p_{31}x + p_{32}y + 1 \\ \end{array}$$

Perspective equivalence

y'

Multiply by denominator and reorganize terms

$$\begin{array}{rcl} x' & = & \frac{p_{11}x + p_{12}y + p_{13}}{p_{31}x + p_{32}y + 1} & & p_{31}xx' + p_{32}yx' - p_{11}x - p_{12}y - p_{13} & = & -x' \\ & & p_{31}xy' + p_{32}yy' - p_{21}x - p_{22}y - p_{23} & = & -y' \end{array}$$

Linear system, solve for P

$$\begin{pmatrix} -x_1 & -y_1 & -1 & 0 & 0 & 0 & x_1x'_1 & y_1x'_1 \\ -x_2 & -y_2 & -1 & 0 & 0 & 0 & x_2x'_2 & y_2x'_2 \\ & \vdots & & & & \\ -x_N & -y_N & -1 & 0 & 0 & 0 & x_Nx'_N & y_Nx'_2 \\ 0 & 0 & 0 & -x_1 & -y_1 & -1 & x_1y'_1 & y_1y'_1 \\ 0 & 0 & 0 & -x_2 & -y_2 & -1 & x_2y'_2 & y_2y'_2 \\ & \vdots & & & \\ 0 & 0 & 0 & -x_N & -y_N & -1 & x_Ny'_N & y_Ny'_N \end{pmatrix} \begin{pmatrix} p_{11} \\ p_{12} \\ p_{13} \\ p_{21} \\ p_{23} \\ p_{23} \\ p_{31} \\ p_{32} \end{pmatrix} = \begin{pmatrix} -x'_1 \\ -x'_2 \\ \vdots \\ -x'_N \\ -y'_1 \\ -y'_2 \\ \vdots \\ -y'_N \end{pmatrix}$$

Image Stitching

•						(
---	--	--	--	--	--	---

Stitch pairs together, blend, then crop

Image Stitching

A big image stitched from 5 small images

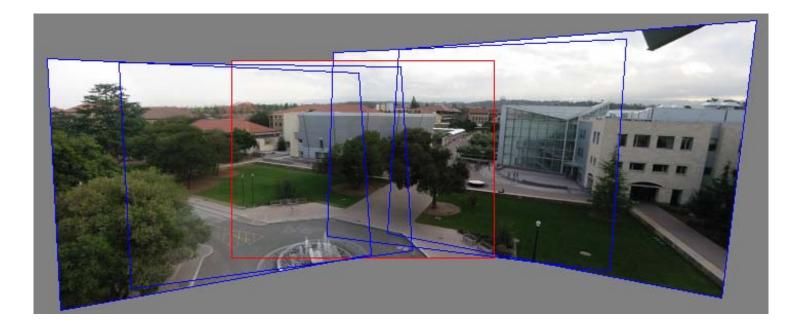


Image Mosaicing



4 Correspondences



5 Correspondences



6 Correspondences



Mosaicing Issues

- Need a canvas (adjust coordinates/origin)
- Blending at edges of images (avoid sharp transitions)
- Adjusting brightnesses
- Cascading transformations

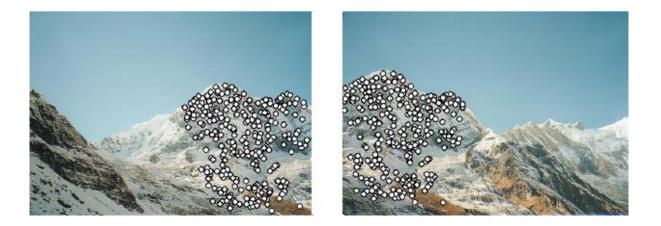
Recognizing panoramas

• A fully automatic 2D image stitcher system



Recognizing panoramas

• A fully automatic 2D image stitcher system



- Image matching with <u>SIFT</u> features
- For every image, find the M best images with RANSAC
- Form a graph and find connected component in the graph
- Stitching and blending.

Automatic Solutions

Intensity Based Image Mosaicing

• Transformation:

$$x_i' = \frac{m_0 x_i + m_1 y_i + m_2}{m_0 x_i + m_7 y_i + 1}$$

$$y_i' = rac{m_3 x_i + m_4 y_i + m_5}{m_6 x_i + m_7 y_i + 1}$$

- Problem: Determining the transformation parameters m_i between every two adjacent images, in order to merge the set of images into a single complete image.
- **Idea**: to choose the parameters **m**_i such that the sum of squared difference between all pixels between the two images is minimized

$$E = \sum_{i} \left[I^{'}\left(x_{i}^{'},y_{i}^{'}
ight) - I\left(x_{i},y_{i}
ight)
ight]^{2} = \sum_{i} e_{i}^{2}$$

- Non-linear minimization, e.g. by Levenberg Marquardt algorithm