

## Project 2: Diffeomorphic Image Registration I

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In this project you will implement geodesic shooting for diffeomorphic image registration in 2D. Along with a written report, you should turn in all source code that you write. In this first part, you will implement only the methods needed to shoot a geodesic forward in time. In the second part (coming later), you will implement a gradient descent methods for doing image matching.

**Methods:** You will need to implement functions that perform the following operations:

1. **Lie Algebra Operations.** You will need to have functions to compute the  $L$  and  $K$  operators,  $\text{ad}$ , and  $\text{ad}^\dagger$ .
2. **Geodesic Shooting.** Given an initial velocity (vector field),  $v_0$ , solve the geodesic equation in the Lie algebra. In the end, you should have a time-varying velocity field  $v_t$ , for  $t \in [0, 1]$ .
3. **Integrate a Velocity Flow.** Given a time-varying velocity field,  $v_t$ , integrate the inverse diffeomorphism using the equation:

$$\frac{d\phi_t^{-1}}{dt} = -D\phi_t^{-1}v_t.$$

4. **Transform an Image.** Given an image  $I$  and a diffeomorphism  $\phi_1^{-1}$ , transform the image by  $I \circ \phi_1^{-1}$ . Use bilinear interpolation to resample the transformed image.

**Experiments:** For these experiments, you will use images and momenta fields provided here:

<http://www.sci.utah.edu/~fletcher/CS7640/hw2/>

1. **Random Initial Velocities.** Generate a momentum vector field that is independent Gaussian values:  $m \sim N(0, \lambda)$ . Use your kernel operator to convert this into an initial velocity vector field:  $v = Km$ . Shoot a geodesic using this initial velocity.
2. **Provided Initial Velocities.** Download the provided initial momenta. Again, convert them to initial velocities using your kernel operator, and shoot the resulting geodesics.

**Report:** You should submit a report (either as html or pdf) describing your work. Be sure to include the following:

- Repeat both the shooting experiments with varying values for the metric parameters (the  $\alpha$  and  $k$  in  $L = (1 - \alpha\Delta)^k$ ). What is the effect of different parameters? What range seems to give valid deformations?
- Shoot the geodesic for each experiment. Deform the given images by the resulting diffeomorphism,  $\phi_t^{-1}$ , for several times in the interval  $0 \leq t \leq 1$ . (You should generate a smooth deformation of the initial image.)

- **Optional:** Plot a deforming grid over the image. This is a good way to check if your transformation is staying diffeomorphic (the grid lines should stay smooth and not get crossed up.) If you are using R or Matlab, grid lines can easily be displayed as the contours of your  $\phi^{-1}$  coordinates.
- Make sure that your geodesic equation (roughly) preserves the magnitude of the velocity. That is, demonstrate that  $\|v_t\|$  is constant in  $t$  up to numerical integration error. Be sure to use the Riemannian metric to compute the velocity norm.
- **Optional:** You can implement time integrals with a first-order Euler integration, or you might try a more advanced numerical integrator, such as Runge-Kutta.