

# CS 6170: Computational Topology, Spring 2019

## Lecture 03

Topological Data Analysis for Data Scientists

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# Topological Spaces

Book Chapter A.I.

## Definition (Topological space)

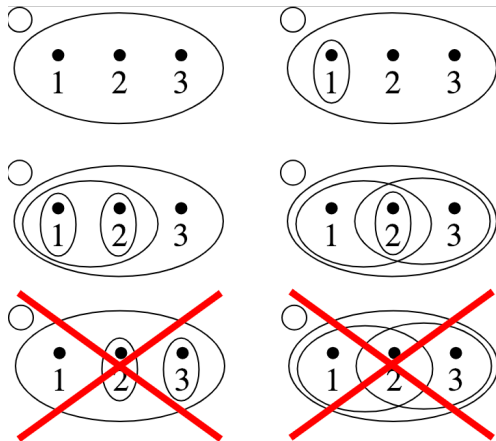
A *topological space* is an ordered pair  $(\mathbb{X}, \mathcal{U})$ , where  $\mathbb{X}$  is a set,  $\mathcal{U}$  is a collection of subsets of  $\mathbb{X}$ , such that:

- The empty set and  $\mathbb{X}$  itself belong to  $\mathcal{U}$ .
- Any arbitrary (finite or infinite) union of members of  $\mathcal{U}$  still belongs to  $\mathcal{U}$ .
- The intersection of any finite number of members of  $\mathcal{U}$  still belongs to  $\mathcal{U}$ .

The elements of  $\mathcal{U}$  are called *open sets* and the collection  $\mathcal{U}$  is called a *topology* on  $\mathbb{X}$ .

- The pair  $(\mathbb{X}, \mathcal{U})$  is called a *topological space*.
- We usually assume that  $\mathcal{U}$  is understood, and refer to  $\mathbb{X}$  as a topological space.

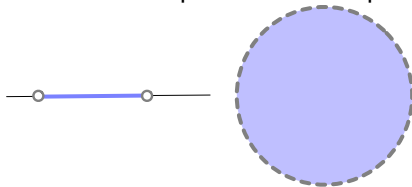
# Topological spaces



Topologies on a three-point set.

# Open set

- An open set is an abstract concept generalizing the idea of an open interval in the real line.
- A set is open if it doesn't contain any of its boundary points.
- Any collection of sets can be called open, as long as the union of an arbitrary number of open sets is open, the intersection of a finite number of open sets is open, and the space itself is open.
- A subset  $U \subset \mathbb{R}^n$  is called *open* if given any point  $x \in U$ , there exists a real number  $\epsilon > 0$  such that for all points  $y \in \mathbb{R}^n$  such that  $\text{dist}(x, y) < \epsilon$ , then  $y \in U$ .
- A *closed set* if a set whose complement is an open set.



# Topological space (point set topology)

Examples of topological spaces  $(\mathbb{X}, \mathcal{U})$ :

- $\mathbb{X} = \{1, 2, 3\}$ ,  $\mathcal{U} = \{\emptyset, \{1, 2, 3\}\}$ .  $\mathcal{U}$  is a (trivial) topology on  $\mathbb{X}$ .
- $\mathbb{X} = \{1, 2, 3\}$ ,  $\mathcal{U}$  is the power set of  $\mathbb{X}$ .
- $\mathbb{X}$  is the real line  $\mathbb{R}^1$ .  $\mathcal{U}$  is the set of all open intervals on the real line  $\mathbb{R}^1$ .
- We refer to  $\mathbb{X}$  as a topological space assuming  $\mathcal{U}$  is understood.

# Continuous function

- A continuous function is a function for which sufficiently small changes in the input result in arbitrarily small changes in the output [wikipedia].
- A function  $f : \mathbb{X} \rightarrow \mathbb{Y}$  is *continuous* if the pre-image of every open set is open.
- Example of a discontinuous function,  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,

$$f(x) = \begin{cases} 0, & \text{if } x \leq 0; \\ 1, & \text{otherwise.} \end{cases}$$

For any  $0 < \epsilon < 1$ ,  $(-\epsilon, +\epsilon)$  is open,  $f^{-1}((-\epsilon, +\epsilon))$  is not.

## Definition (Path connectivity)

A topological space is *path-connected* if every pair of points is connected by a path.

- A function between topological spaces  $f : \mathbb{X} \rightarrow \mathbb{Y}$  is *continuous* if the preimage of every open set is open.
- A *path* is continuous function from the unit interval  $\gamma : [0, 1] \rightarrow \mathbb{X}$ .

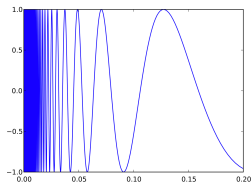


# Separation of a topological space

## Definition (Separation)

A *separation* of a topological space  $\mathbb{X}$  is a partition  $\mathbb{X} = U \cup W$  into two non-empty, open subsets that are disjoint. A topological space is *connected* if it has no separation.

- Connectedness is strictly weaker than path-connectedness.
- A topological space that is connected but is not path-connected:  
topologist's sine curve:  $T = \{(x, \sin(\frac{1}{x})) : x \in (0, 1]\} \cup \{(0, 0)\}$



# Union-Find

Book Chapter A.I.

# Union-find on a high level

- Given a set of elements which are partitioned into subsets, you have to keep track of the connectivity of each element in a particular subset or connectivity of subsets with each other.
- To do this operation efficiently, you can use union-find data structure.  
Galler and Fischer (1964); Galil and Italiano (1991)

<https://www.hackerearth.com/practice/notes/disjoint-set-union-union-find/>

# Algorithmic question of deciding connectedness

- Union-find: a disjoint-set data structure.
- A data structure that tracks a set of elements partitioned into a number of disjoint (non-overlapping) subsets.
- Represent each set as a tree of elements (thinking **grapes**).
- Maintain a collection of sets under three operations (book notations):
  - **MakeSet(x)**: Create a set containing a single element  $x$ .
  - **Find(x)**: Return the root of the tree containing  $x$ .
  - **Union(x,y)**: Make the root of tree containing  $x$  to also be the root of tree containing  $y$ .

## A social network example (slightly different perspective)

- There are 5 people A, B, C, D and E.
- A is a friend of B, B is a friend of C, D is a friend of E.
- As we can see:
  - A, B and C are connected to each other.
  - D and E are connected to each other.
- Use union-find to check whether one friend is connected to another in a direct or indirect way or not.
- We can also determine the two different disconnected subsets:  $\{A, B, C\}$  and  $\{D, E\}$ .

You have to perform two types of operations here:

- **Union (A, B)**: connect two elements A and B.
- **FindPath(C, D)**: find if there is any path connecting two elements C and D.

- Galil, Z. and Italiano, G. (1991). Data structures and algorithms for disjoint set union problems. *ACM Computing Surveys*, 23.
- Galler, B. A. and Fischer, M. J. (1964). An improved equivalence algorithm. *Communications of the ACM*, 7:301–303.