## CS 6170: Computational Topology, Spring 2019 Lecture 02 Topological Data Analysis for Data Scientists

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# Persistent Homology in a Nutshell



Wong et al. (2016)

# Previous Project Ideas

## Previous Course Projects

- Topology of Elementary Thermodynamic Models
- Pose Analysis of Thermal Images
- Using Mapper on Netflix data
- Visualizing Periodicity in Time Series Data
- Stratification Learning
- Persistence applied to decomposed spaces
- Prediction of Grasp Stability using Topological Data Analysis
- Distributing the Mapper Algorithm
- Topology in Uncertain Visualization
- Topological data analysis of mice pregnancy data
- Jacobi Set in Discrete Morse Theory
- Using Mapper Explore High Dimensional Data
- Visualization of Sensor Network Coverage with Sensor Location Uncertainty

## Pose Analysis of Thermal Images

- Prediction of Grasp Stability using TDA
- Moving Sensor Coverage
- A TDA of IED Explosions in Afghanistan 2004-2009
- Study and Verification of Topological Strata of Weighted Complex Networks
- Analysis of High Dimensional Autism Brainwave Data Using Mapper
- Openspace and Disperse
- Topology guides volume exploration
- TDA for Bird Migration
- Semantic Segmentation with Topological Methods

### Pose Analysis of Thermal Images



S. Anderson and D. Geisler, 2017

#### Analysis of Netflix Data



M. Annasamy and S. Brooks, 2017

## Visualizing Periodicity in Time Series Data



J. Boyer and S. Ram, 2017

#### Theory: Stratification Learning Using Sheaves\*



A. Brown, 2017, Brown and Wang (2018)

#### Theory: Persistence applied to decomposed spaces

Consider the space Y:



K. Childers, 2017

#### Theory: Jacobi Set in Discrete Morse Theory



P. Klacansky, 2017. Edelsbrunner and Harer (2004)

## A TDA of IED Explosions in Afghanistan 2004-2009



#### P. Narayanan, 2017

https://www.theguardian.com/world/datablog/2010/jul/26/wikileaks-afghanistan-ied-attacks

#### Prediction of Grasp Stability using TDA



A. Conkey, 2017

Image Courtesy: http://www.pacman-project.eu/news/

## Distributed Computation of the Mapper Algorithm

#### A Original Point Cloud





D Clustering and network construction



Image courtesy Lum et al. (2013) P. English, 2017.

### Topology for Uncertainty Visualization



S. Mehrpour and N. Farhoudi, 2017.

## TDA of Pregnancy Mice\*



Which mice are pregnant? Data from Smarr et al. (2016). V. Jose and A. Sharma, 2017. Sharma (2018)

## TDA of Pregnancy Mice\*



Which jet lagged mice are pregnant? V. Jose and A. Sharma, 2017. Sharma (2018)

#### Song Similarities via Homology of Chroma Features



## Sensor Network Coverage with Location Uncertainty\*



T. Sodergren and J. Lohse, 2017. Sodergren et al. (2017) http://www.sci.utah.edu/~tsodergren/prob\_net\_vis\_working/

## Moving Sensor Coverage

• When a loop is broken we lose a significant amount of coverage



D. Mcclelland and M. Matheny, 2017.

### Astronomy: Open Space and DisPerse



M. Territo, 2017. www.openspaceproject.com

## Topology Guided Volume Exploration



Tooth after per-segment classification and removal of background. The Inner pocket and boundary are clear to see and not affected by removal of noise

W. Usher, Q. Wu , 2017.

## TDA for Birth Migration



J. Wagstaff, 2017.

# Semantic Segmentation with Topological Methods: CNN





(a) Input from PhC-U373 Dataset (b) Segmented Result from the Trained Network

D. Wang, 2017.

#### Data has shape and shape matters

Possible quote by G. Carlsson.

### Graphs and Connected Components

Book Chapter A.I.

## Graphs in DS



https://www.flickr.com/photos/frauhoelle/8464661409



pixabay.com

#### Definition (Graph)

An abstract graph is a pair G = (V, E) consisting of a set of vertices V, a set of edges E for each pair of vertices.

- A graph is *simple* if no two edges connect the same two vertices and there is no self-loop.
- A complete graph contains an edge for every pair of vertices.
- A *regular graph* contains vertices with the same degree.



## Simplex

- $K_n$ : a complete graph with n vertices.
- $K_n$  represents edges of a (n-1)-simplex.





#### Definition (Connected Graph)

A simple graph is *connected* if there is a path between every pair of vertices. A *connected component* (CC) of a graph is a maximal subgraph that is connected.

- A *path* between vertices u and v is a sequence of vertices  $u = u_0, u_1, \cdots, u_k = v$ , with an edge between  $u_i$  and  $u_{i+1}$  for each  $0 \le I \le k-1$ .
- Simple path: all vertices are distinct (no loops)
- Path length: number of edges traversed

#### Tree, spanning tree

- A *tree* is an undirected graph in which any two vertices are connected by exactly one path.
- The smallest connected graph is a tree (n vertices, n-1 edges).
- Deleting any edge disconnects the tree.
- A spanning tree of a graph G = (V, E) is a tree T = (V, E') with  $E' \subseteq E$ .



https://commons.wikimedia.org/wiki/File:Minimum\_spanning\_tree.svg

#### Definition (Separation)

A separation is a non-trivial partition of the vertices; that is,  $V = U \cup W$  where U and W are nonempty, such that no edge connects a vertex in U with a vertex in V.

- A simple graph is *connected* iff it has no separation.
- A simple graph is *connected* iff it has a spanning tree.



### Algorithms to test connectivity of a graph

- DFS: depth-first search
- BFS: breadth-first search
- Union-find



https://upload.wikimedia.org/wikipedia/commons/3/33/Breadth-first-tree.svg https://commons.wikimedia.org/wiki/File:Depth-first-tree.svg

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