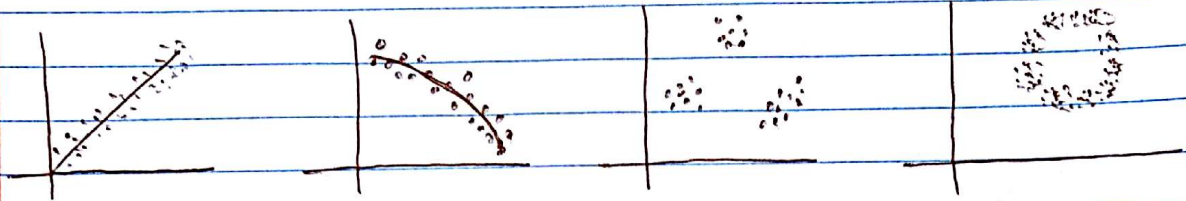


①

Data has shape; Shape matters; shape has meaning



Shape can have different meaning at different scales



⇒ Depending on scale, data can be sampled from set of discs or from a single annulus.

→ Today we'll look at (a) Connectivity (b) Union-find

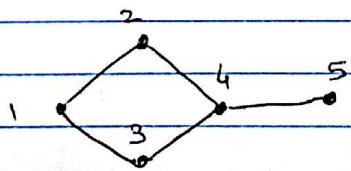
motivating data type: Graphs (Nodes and edges)

eg.

(i) Abstract Graphs: Social Networks, Biological networks (Gene Expression etc.)

(ii) Embedded Graphs: Graphs where nodes and edges have spatial meaning (co-ordinates)  
- transportation networks, SBC road grid etc.

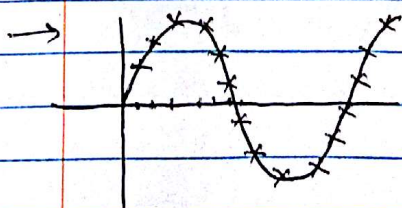
→ Abstract graphs are discrete graphs. Pair of sets  $G = (V, E)$ , where  $E \subseteq V \times V$



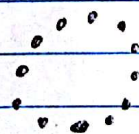
$$\Rightarrow V = \{1, 2, 3, 4, 5\}$$

$$E = \{12, 13, 24, 34, 45\}$$

→ Embedded graphs are continuous: Geometry matters.

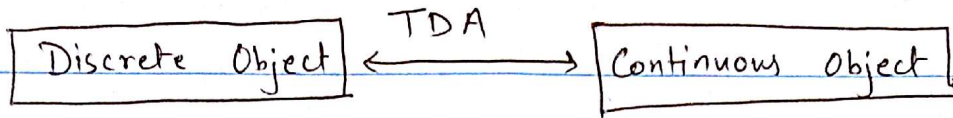


x → points sampled from periodic signal



Delayed Window Embedding  
moving window of consecutive pairs of points plotted as  $x, y$  co-ordinates maps periodic signal to circle.

(2)



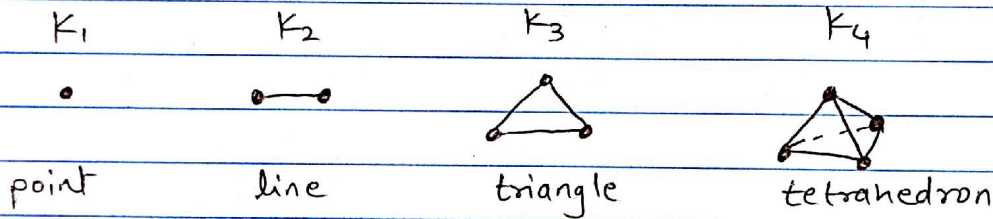
Def<sup>n</sup>: Simple graph: (a) No multi-edges  
(b) No self loops  
 $G = (V, E)$  with  $|V| = n$  then  $|E| \leq \binom{n}{2}$

Def<sup>n</sup>: Complete Graph ( $K_n$ ): Simple graph with all possible edges.  $\forall K_n = (V, E) : |V| = n, |E| = \binom{n}{2}$

→  $K_n$  is a regular graph of degree  $(n-1)$ .

Def<sup>n</sup>: Regular graph: all vertices have same degree.

→  $K_n$  represents edge of  $(n-1)$ -simplex



Def<sup>n</sup>: Given a graph  $G = (V, E)$  a path  $\gamma(u, v)$  is a sequence of vertices  $\{u_0 = u, u_1, u_2, \dots, u_k = v\}$  such that edge  $u_i u_{i+1} \in E$  for all vertices  $u_i$  in sequence.

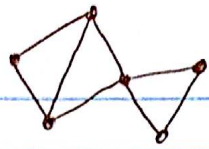
→ Simple Path: all vertices are distinct (No loops in the path)

→ Path length: ~~Number of vertices~~ Number of edges traversed  
(Number of hops)

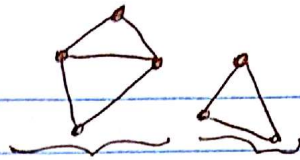
Def<sup>n</sup>: A simple graph is connected if there is a path between every pair of vertices.

A connected component (CC) of a graph is a maximal sub-graph that is connected.

3



Connected



Connected components

→ Algorithms to test whether a graph is connected:  
 ① DFS: depth first search    ② BFS: Breadth first

→ We will see another algorithm called union-find.

Claim: Smallest connected graph is a tree. ( $n$  vertices,  $n-1$  edges)  
 deleting any edge disconnects the tree.

Def<sup>n</sup>: Spanning tree: Given graph  $G = (V, E)$ , spanning tree of  $G$  is a tree  $T = (V, E')$  which is the connected subgraph of  $G$  with minimum number of edges

Def<sup>n</sup>: Separation: Non-trivial partition of vertex set such that  $V = U \cup W$  then no edges connect vertices from  $U$  to vertices in  $W$ .

Claim: Graph is connected  $\iff$  it has spanning tree  
 Graph is connected  $\iff$  it has no separation.

## # Topological Spaces

Def<sup>n</sup>: A topological space is path connected if every pair of points is connected by a path eg. points on a disk

Def<sup>n</sup>: A separation of topological space  $X$  is a partition  $X = U \cup W$  with non-empty, open subsets.

→ Topological space is connected if there is no separation

→ path connected  $\implies$  connected But connected  $\not\implies$  path connected.  
 eg. Topologist's sin curve.