SCIENTIFIC VISUALIZATION TODAY'S DEMO



https://www.youtube.com/watch?v=ufirpyUGPLk
3:55 m

The Gebelein man story

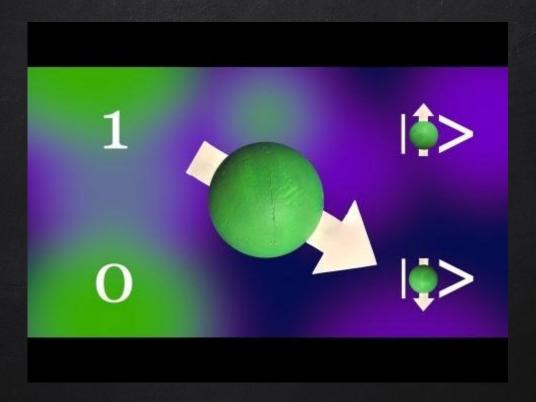


https://www.youtube.com/watch?v=Q4Z3W1RXh_g

ANNOUNCEMENT

- Bonus 6: sign up for today's demo session, starting at 1:20 p.m. until
 2:00 p.m.
 - 1 bonus point. 10–15 students in each session of 20 m.
- Aaron Knoll will give a guest lecture on scientific computing and volume rendering next week!
- ☐ Explain HW 6

FUTURE OF COMPUTING? QUANTUM COMPUTING



https://www.youtube.com/watch?v=g_laVepNDT4

ROBOTICS

What are the future of Robots?



ROBOTS

Are these robots?

- ☐ A light switch
- A security cam
- ☐ An electric mixer
- □ A computer
- □ A car







ROBOT CHARACTERISTICS

Robots generally have some capabilities in each of the following categories:

- Sense: can detect the environment around it
- Plan: can modify its behavior based on what it senses
- Act: can move itself or manipulate the environment

The School of Computing is one of a few departments with a Robotics degree track. The course structure follows a Perception-Cognition-Action plan.

ROBOT APPLICATIONS

Robots are used in applications that are:

- □ Dirty
- Dangerous
- □ Dull

Examples?

More recently, are seen as social machines:

Toys and Home assistants





EXAMPLES OF ROBOTS

- Military: Big Dog https://www.youtube.com/watch?v=cHJJQOzNNOM
- □ Home: Roomba http://www.youtube.com/watch?v=LQ-jv8g1YVI
- Industrial: Car assembly line https://www.youtube.com/watch?v=3CzuQ3DtsPc&feature=fvw
- Medical: DaVinci https://www.youtube.com/watch?v=VJ_3GJNz4fg



https://www.youtube.com/watch?v=3lGTk1nefQM

ROBOT ARCHITECTURES

Ser	nse-Plan-Act: very much like Al problem
	Recognizing a dark spot as a shadow rather than a hole in the floor takes experiences and context
	Makes the assumption that action in a complex world requires human levels of intelligence
	We should make robots that are as human-like as possible, in Al and in physical capabilities
	What are some advantages of a human-sized and human-like in capability robot?

http://www.ai.sri.com/videos/ Watch SHAKEY

ROBOT ARCHITECTURES

Insect Behaviors:

- Cockroaches are very successful, yet are not "smart"
 - We don't need human capabilities, just insect-level performance
- Collection of competing behaviors
- ☐ Complexity emerges from simple rules
 - ☐ Roomba uses this paradigm
 - Called a subsumption architecture



https://www.youtube.com/watch?v=C9p8B7-5MTI

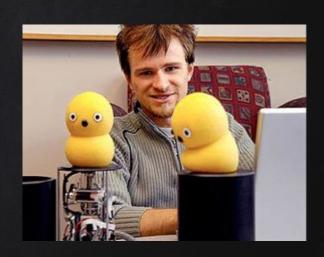
CURRENT DIRECTIONS: MILITARY

- Afghanistan may be the first robotic war
 - ☐ 1 robot for every 50 soldiers
- US military wants autonomous vehicles
 - Avoid convoy deaths
- Robots now have weapons
- https://www.youtube.com/watch?v=WfxshX5kReA
- □ https://www.youtube.com/watch?v=Ci7EFmO260E
- □ http://www.youtube.com/watch?v=yliThCy3RxY&feature=related



CURRENT DIRECTIONS - SOCIAL

- Health care robots
 - □ Interaction with patients
- ☐ Therapy Robots
 - Simplified relationships with autism patients
- In home assistance for elderly
- MIT's Nexi robot
 - Uncanny valley
 - □ http://www.youtube.com/watch?v=XrmrU7P-ysA



CURRENT DIRECTIONS: CONSUMER

- Chores
 - □ Vacuum
 - ☐ Gutter
 - □ Pool
- □ Toys



http://www.youtube.com/watch?v=G5d3A-SV9Vo&feature=fvwrel

CONCLUSIONS

- Robotics is a huge growth area
- Used any place that work is
 - Dangerous
 - □ Dirty
 - Automation
 - Repetitive tasks
 - ☐ Assisting people



Any questions?

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http://www.sci.utah.edu/~beiwang/teaching/cs1060.html

CREDITS

Special thanks to all the people who made and released these awesome resources for free:

- Presentation template by <u>SlidesCarnival</u>
- Photographs by <u>Unsplash</u>