# CS 6230: High-Performance Computing and Parallelization – Introduction to MPI

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#### **Distributed Computing**





(BlueGene/L - Image courtesy of IBM / LLNL)

MPI is the de facto standard for programming distributed processes.

A large API with over 300 functions exists and is widely supported.

Several popular and robust (free) implementations: MPICH and OpenMPI



## How Widely Used Is MPI?

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### Why MPI is Complex: Collision of Features

- Send
- Receive
- Send / Receive
- Send / Receive / Replace
- Broadcast
- Barrier
- Reduce
- Non Wildcard receives
- Wildcard receives
- Tag matching
- Communication spaces

- Rendezvous mode
- Blocking mode
- Non-blocking mode
- Reliance on system buffering
- User-attached buffering
- Restarts/Cancels of MPI Operations

An MPI program is an interesting (and legal) combination of elements from these spaces

#### So What is MPI Anyway?

MPI is not a language. It is an API.

Application Programming Interface (API): An API defines the calling conventions and other information needed for one software module (typically an application program) to utilize the services provided by another software module.

MPI provides a collection of functions that allow interprocess communication through an MPI communications "layer".

One compiles "with" MPI.

#### **Programming and Compiling**

C++/MPI Code From Practical 1

```
#include <iostream>
#include "mpi.h"
```

using namespace std;

```
int main(int argc, char ** argv){
    int mynode, totalnodes;
```

```
MPI_Init(&argc,&argv);
MPI_Comm_size(MPI_COMM_WORLD, &totalnodes);
MPI_Comm_rank(MPI_COMM_WORLD, &mynode);
```

cout << "I am process " << mynode << " out of " << totalnodes << endl;

MPI\_Finalize();

return 0;

}

mpicc –o prac1 prac1.cpp

or

g++ -o prac1 -l <header path> -L <MPI library path> -Impi prac1.cpp

This produces an executable prac1

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# MPI "Boot"

MPI "Boot" (called different things per implementation) starts a daemon per machine – sometimes called the MPI daemon.

This daemon waits for an MPI job to be started using mpirun.



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#### **Groups and Communicators**

- A group defines the participants in the communication of a communicator. It is actually an ordered collection of processes, each with a rank.
- Message passing in MPI is via communicators, each of which specifies a set (group) of processes that participate in the communication.
- Communicators can be created and destroyed dynamically by coordinating processes.
- Information about topology and other attributes of a communicator can be updated dynamically.

#### **Groups and Communicators**

- Group Functions start with MPI\_Group\_\*
  - MPI\_Group\_rank
  - MPI\_Group\_size
  - MPI\_Group\_create
- Communicator Functions start with MPI\_Comm\_\*
  - MPI\_Comm\_rank
  - MPI\_Comm\_size
  - MPI\_Comm\_compare
  - MPI\_Comm\_dup

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## Predefined MPI Datatypes

MPI datatype	C datatype
MPI_CHAR	signed char
MPL_SHORT	singed short int
MPI_INT	signed int
MPI_LONG	singed long int
MPI_UNSIGNED_CHAR	unsigned char
MPI_UNSIGNED_SHORT	unsigned short int
MPI_UNSIGNED	unsigned int
MPI_UNSIGNED_LONG	unsigned long int
MPI_FLOAT	float
MPLDOUBLE	double
MPI_LONG_DOUBLE	long double
MPLBYTE	
MPL_PACKED	



## **Predefined MPI Operations**

Operation Name	Meaning
MPI_MAX	Maximum
MPI_MIN	Minimum
MPI_SUM	Sum
MPI_PROD	Product
MPI_LAND	Logical and
MPI_BAND	Bitwise and
MPI_LOR	Logical or
MPI_BOR	Bitwise or
MPI_LXOR	Logical exclusive or
MPI_BXOR	Bitwise exclusive or
MPI_MAXLOC	Maximum and location of maximum
MPI_MINLOC	Minimum and location of minimum

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#### **Output Considerations**

This is probably what you see as output on your screen:

Hello world from processor 0 of 4 Hello world from processor 3 of 4 Hello world from processor 2 of 4 Hello world from processor 1 of 4

Note: This makes assumptions about the output device and how the MPI subsystem is handling standard output.

# **MPI** Function Declarations



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# Notes on MPI\_Send

- Must be specific as to the process to whom you are sending (no wildcard).
- dest and comm are used together in concert to determine to whom a process is sending.
- Send assumes that the message in memory to be sent is contiguous.
- Tags are integers which are used to distinguish between particular messages sent from one process to another.
- MPI\_Send is blocking the function will only return when the user can reuse the memory which was passed.

# **Receiving in MPI**





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## Notes on MPI\_Recv

- The count within the MPI\_Recv denotes the size of the buffer into which the system may place an incoming message. It is not used to select which message is received.
- Assuming the same tags, messages are received in their sending order. Tags are used to distinguish between messages on the incoming message stack.
- MPI\_Recv is blocking. It will only return after the message has been received (otherwise an error has occurred which will be denoted in the error and status information).

### **Predefined MPI Constants**

- MPI\_ANY\_SOURCE (Wildcard Source)
- MPI\_ANY\_TAG (Wildcard Tag)
- These can only be used with Receive (and its variants). There is no such thing as a wildcard Send.

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```
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               Example Serial Program
#include<iostream.h>
int main(int argc, char * argv[]){
  int sum;
  sum = 0;
  for(int i=1;i<=1000;i++)</pre>
     sum = sum + i;
  cout << "The sum from 1 to 1000 is: " << sum << endl;
  return 0;
}
```

```
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```



#### **Example Parallelization of Serial Program**

```
#include<iostream.h>
#include<mpi.h>
```

```
int main(int argc, char * argv[]){
    int mynode, totalnodes;
    int sum,startval,endval,accum;
    MPI_Status status;
```

```
MPI_Init(argc,argv);
MPI_Comm_size(MPI_COMM_WORLD, &totalnodes);
MPI_Comm_rank(MPI_COMM_WORLD, &mynode);
```

```
sum = 0;
startval = 1000*mynode/totalnodes+1;
endval = 1000*(mynode+1)/totalnodes;
```

The Programmer Does the Partitioning Work

```
for(int i=startval;i<=endval;i++)</pre>
```

```
sum = sum + i;
```

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## **Example Parallelization of Serial Program**

```
for(int i=startval;i<=endval;i++)</pre>
     sum = sum + i;
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  if(mynode!=0)
    MPI_Send(&sum, 1, MPI_INT, 0, 1, MPI_COMM_WORLD);
  else
    for(int j=1;j<totalnodes;j++){</pre>
      MPI_Recv(&accum, 1, MPI_INT, j, 1, MPI_COMM_WORLD, &status);
      sum = sum + accum;
    }
  if(mynode == 0)
    cout << "The sum from 1 to 1000 is: " << sum << endl:
 MPI_Finalize();
  return 0;
}
```

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# Key Concepts

#### Key Concept

• Almost everything in MPI can be summed up in the single idea of "Message Sent - Message Received".

#### Key Concept

• There **must** be a one-to-one correspondence between MPLSend and MPLRecv commands. For every message sent using MPLSend, there must be an explicit receiver using MPLRecv.

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Terminology: Correctness

**Deadlock**: An error condition common in parallel programming in which the computation has stalled because a group of processes are blocked and waiting for each other in a cyclic configuration.

Example of a Deadlock Scenario:

Process 0	Process 1
MPI_Send(,1,)	MPI_Send(,0,);
MPI_Recv(,1,)	MPI_Recv(,0,);

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Terminology: Correctness

**Race condition**: An error condition peculiar to parallel programs in which the outcome of a program changes as the relative scheduling of processes varies.

Example of a Race Condition Scenario:

Process 0	Process 1	Process 2
MPI_Send(,2,)	MPI_Send(,2,)	MPI_Recv(a,MPI_ANY_SOURCE) // Accomplish Func A with data a
		MPI_Recv(b,MPI_ANY_SOURCE) // Accomplish Func B with data b

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#### Terminology: Latency

**Latency**: The fixed cost of serving a request, such as sending a message or accessing information from a disk. In parallel computing, the term most often is used to refer to the time it takes to send an empty message over the communication medium, from the time the send routine is called to the time the empty message is received by the recipient.



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# Terminology: Bandwidth

**Bandwidth**: The capacity of a system, usually expressed as items per second. In parallel computing, the most common usage of the term "bandwidth" is in reference to the number of bytes per second that can be moved across a network link.

Notes:

- Can increase the bandwidth by making the "pipe" larger.
- Larger bandwidth does not equate to lower latency.

# MPI\_Isend

int $MPI_{-}I$	lsend(				
	void*	message	/*	in	*/,
	$\operatorname{int}$	$\operatorname{count}$	/*	in	*/,
	MPI_Datatype	datatype	/*	in	*/,
	$\operatorname{int}$	$\operatorname{dest}$	/*	in	*/,
	$\operatorname{int}$	$\operatorname{tag}$	/*	in	*/,
	MPI_Comm	$\operatorname{comm}$	/*	in	*/,
	$MPI_Request^*$	request	/*	out	*/)

### Notes on MPI\_Isend

- MPI\_Isend is non-blocking. The function is used to "initiate" a send and returns immediately. This does not mean that one can reuse the memory as the message may not have been read out of memory yet.
- MPI\_Wait or Test is used to bring closure to the nonblocking send operation.
- Isend can be received by all of the various blocking and non-blocking receives.

## MPI\_Irecv

int MPI\_Irecv( /\* void\* message /\* int  $\operatorname{count}$ datatype /\* MPI\_Datatype /\* int dest /\* int  $\operatorname{tag}$ MPI\_Comm /\* comm MPI\_Request\* /\* request

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 $\operatorname{in}$ 

out

### Notes on MPI\_Irecv

- MPI\_Irecv is non-blocking. The function is used to "initiate" a recv and returns immediately. This does not mean that one can use the memory as the message may not have been read into memory yet.
- MPI\_Irecv can be used with any of the blocking or non-blocking MPI send calls.



# Notes on MPI\_Wait

- The Wait function does not return until the request which was initiated by an Isend or Irecv has completed.
- The wait is the point at which the process blocks. If one does not want to block, one can use Test (but test requires polling to see when the process finally completes).

# MPI\_Sendrecv

int MPI_Send:	recv(
---------------	-------

void*	$\operatorname{sendbuf}$	/*	in	*/,
$\operatorname{int}$	$\operatorname{sendcount}$	/*	in	*/,
MPI_Datatype	$\operatorname{sendtype}$	/*	in	*/,
$\operatorname{int}$	$\operatorname{dest}$	/*	in	*/,
$\operatorname{int}$	$\operatorname{sendtag}$	/*	in	*/,
void*	$\operatorname{recvbuf}$	/*	out	*/,
$\operatorname{int}$	$\operatorname{recvcount}$	/*	in	*/,
MPI_Datatype	recvtype	/*	in	*/,
$\operatorname{int}$	source	/*	in	*/,
MPI_Datatype	recvtag	/*	in	*/,
MPI_Comm	comm	/*	in	*/,
$MPI_Status^*$	status	/*	out	*/)

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## Notes on MPI\_Sendrecv

- The sendrecv command is used whenever two processes are going to "swap" data. Note it is not required that the swapping be symmetrical – each process within the pair may send different data (different types and different number).
- MPI contains a Sendrecv\_replace operator which technically only works when buffering exists within the system.





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## **Predefined MPI Operations**

Operation Name	Meaning
MPI_MAX	Maximum
MPI_MIN	Minimum
MPI_SUM	Sum
MPI_PROD	Product
MPI_LAND	Logical and
MPI_BAND	Bitwise and
MPI_LOR	Logical or
MPI_BOR	Bitwise or
MPI_LXOR	Logical exclusive or
MPI_BXOR	Bitwise exclusive or
MPI_MAXLOC	Maximum and location of maximum
MPI_MINLOC	Minimum and location of minimum

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#### MPI\_Allreduce

int MPI\_Allreduce( void\* void\* int MPI\_Datatype MPI\_Op MPI\_Comm

operand	/*	$\operatorname{in}$	×
result	/*	out	k
count	/*	in	×
datatype	/*	in	k
operator	/*	in	×
comm	/*	in	k

#### **MPI\_Gather**

int MPI\_Gather( void\* sendbuf in /\* in sendcount int /\* MPI\_Datatype in sendtype /\* void\* recvbuf out /\* inint recvcounts /\* inMPI\_Datatype recvtype MPI\_Comm /\* in  $\operatorname{comm}$ 

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# MPI\_Gatherv

$int MPI_Gatherv($				
void*	$\mathbf{sendbuf}$	/*	in	*/
$\operatorname{int}$	$\operatorname{sendcount}$	/*	in	*/
MPI_Datatype	$\operatorname{sendtype}$	/*	in	*/
void*	$\operatorname{recvbuf}$	/*	out	*/
$\operatorname{int}$	recvcounts[]	/*	in	*/
$\operatorname{int}$	displacements[]	/*	in	*/
MPI_Datatype	recvtype	/*	in	*/
$\operatorname{int}$	root	/*	in	*
MPI_Comm	comm	/*	in	*

,

#### MPI\_Allgather

#### int MPI\_Allgather(

void\* a int a MPI\_Datatype a void\* a int a MPI\_Datatype a MPI\_Comm a

sendbuf sendcount sendtype recvbuf recvcount recvtype comm in \*/, in \*/, in \*/, out \*/, in \*/, in \*/, in \*/,

/\*

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### MPI\_Allgatherv

#### int MPI\_Allgatherv(

void*	$\mathbf{sendbuf}$	/*
$\operatorname{int}$	sendcount	/*
MPI_Datatype	sendtype	/*
void*	$\operatorname{recvbuf}$	/*
$\operatorname{int}$	recvcounts[]	/*
$\operatorname{int}$	displacements[]	/*
MPI_Datatype	recvtype	/*
MPI_Comm	comm	/*

\*/, in\*/, in\*/, in\*/, out \*/ in\*/, in\*/, in\*/) in

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# MPI\_Scatter

int MPI_Sca	tter(				
V	oid*	$\operatorname{sendbuf}$	/*	in	*/,
ir	nt	$\operatorname{sendcount}$	/*	$\operatorname{in}$	*/,
$\mathbf{N}$	IPI_Datatype	sendtype	/*	in	*/,
V	oid*	$\operatorname{recvbuf}$	/*	out	*/,
ir	nt	recvcount	/*	in	*/
$\mathbf{N}$	IPI_Datatype	recvtype	/*	$\operatorname{in}$	*/,
ir	nt	root	/*	$\operatorname{in}$	*/,
Ν	IPI_Comm	comm	/*	$\operatorname{in}$	*/)

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# MPI\_Scatterv

int MPI\_Scatterv(

void*	sendbuf	/*	in	*/,
$\operatorname{int}$	sendcounts[]	/*	in	*/,
$\operatorname{int}$	displacements[]	/*	in	*/,
MPI_Datatype	sendtype	/*	in	*/,
void*	recvbuf	/*	out	*/,
$\operatorname{int}$	recvcount	/*	in	*/
MPI_Datatype	$\operatorname{recvtype}$	/*	in	*/,
$\operatorname{int}$	root	/*	in	*/,
MPI_Comm	comm	/*	in	*/)

# MPI\_Alltoall

int MPI_Alltoa	ll(				
void	*	$\operatorname{sendbuf}$	/*	in	*/,
$\operatorname{int}$		$\operatorname{sendcount}$	/*	in	*/,
MPI	Datatype	sendtype	/*	in	*/,
void	*	recvbuf	/*	out	*/,
$\operatorname{int}$		recvcount	/*	in	*/
MPI	Datatype	recvtype	/*	in	*/,
MPI	Comm	$\operatorname{comm}$	/*	in	*/)



## MPI\_Alltoallv

int MPI\_Alltoallv(

int sendcounts[] $/*$ in $*/$	/,
	/,
int send_displacements[] /* in $*/$	
MPI_Datatype sendtype $/*$ in $*/$	',
void* recvbuf /* out $*/$	/,
int recvcounts[] $/*$ in $*/$	/
int $recv_displacements[] /* in */$	$^{\prime},$
MPI_Datatype recvtype $/*$ in $*/$	/,
$MPI_Comm  comm  /*  in  */$	/)