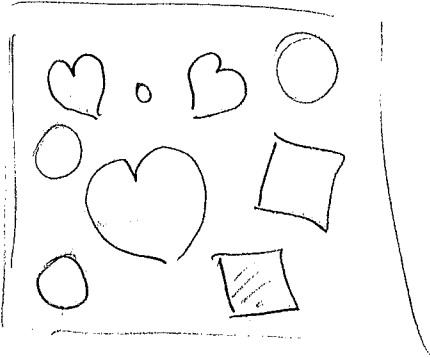


Image Analysis: Fourier Harmonics

02/25/2010

Guido Gerig (1)

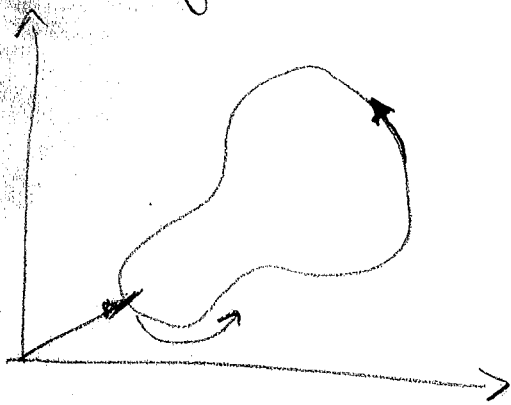


Equivalence classes:



- Simplified description of object (small set of parameters)
- "Gestalt" parameters: Robust w.r.t. small deformations, continuous
- Invariant under:
 - scaling
 - translation
 - rotation
- Either area or contour

Boundary Descriptors:



$$\underline{x}(s) = \begin{pmatrix} x(s) \\ y(s) \end{pmatrix} \quad s: 0, \dots, L$$

$\Rightarrow \underline{x}(s)$ is periodic with s

s measured on arclength center

Invariance: Two contours are equivalent $\underline{x}_1 \sim \underline{x}_2$ if $\underline{x}_1 = \alpha \cdot R \cdot \underline{x}_2 + t$ | scaling, rotation, translation

Equivalence: Reflexivity: $\underline{x}_1 \sim \underline{x}_1$

Symmetry: $\underline{x}_1 \sim \underline{x}_2 \Rightarrow \underline{x}_2 \sim \underline{x}_1$

Transitivity: $\underline{x}_1 \sim \underline{x}_2$ and $\underline{x}_2 \sim \underline{x}_3 \Rightarrow \underline{x}_1 \sim \underline{x}_3$
group property of linear

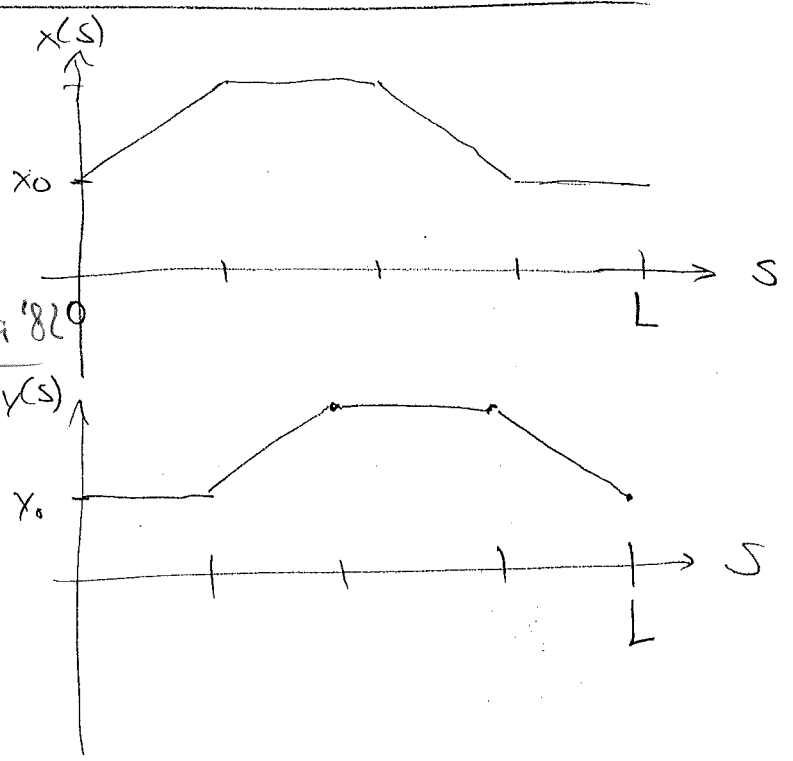
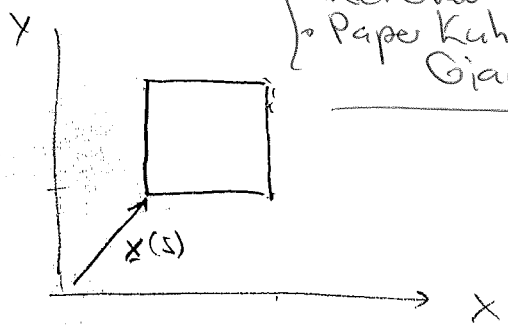
Reflexivity: $x=1, y=0, t=0$

Symmetry: $\frac{1}{2}(x_1 - t) = R x_2 \Rightarrow x_2 = R^{-1}(\frac{1}{2}(x_1 - t))$

Transitivity: ...

Fourier Descriptors:

Material: Chapters
 Example: Brechtbücher
 Kelener
 Paper Kuhl & Giardina '82



idea: $\left. \begin{matrix} x(s) \\ y(s) \end{matrix} \right\}$ Fourier Series

Kuhl & Giardina (1982):

$$x(s) = A_0 + \sum_{n=1}^{\infty} a_n \cos 2\pi(n/L)s + b_n \sin 2\pi(n/L)s$$

$$y(s) = B_0 + \sum_{n=1}^{\infty} c_n \cos \frac{2\pi n s}{L} + d_n \sin \frac{2\pi n s}{L}$$

$$A_0 = \frac{1}{L} \int_0^L x(s) ds \quad B_0 = \frac{1}{L} \int_0^L y(s) ds$$

$$a_n = \frac{2}{L} \int_0^L x(s) \cos \frac{2\pi n s}{L} ds \quad b_n = \dots$$

$$c_n = \frac{2}{L} \int_0^L y(s) \cos \frac{2\pi n s}{L} ds \quad d_n = \dots$$

more elegant: complex notation: $Z(s) = x(s) + j y(s) = |Z| e^{j\phi}$

$$Z(s) = \sum_{n=-\infty}^{\infty} Z_n e^{2\pi j (\frac{n}{L})s}$$

Series of complex exponential functions

$$= Z_0 + \sum_{n=1}^{\infty} (Z_n e^{2\pi j (\frac{n}{L})s} + Z_{-n} e^{-2\pi j (\frac{n}{L})s})$$

$$Z_0 = \frac{1}{L} \int_0^L Z(s) ds = \frac{1}{L} \int_0^L (x(s) + i y(s)) ds$$

$$\left. \begin{aligned} \text{Re}(Z_0) &= \frac{\sum x}{L} = \bar{x} \\ \text{Im}(Z_0) &= \frac{\sum y}{L} = \bar{y} \end{aligned} \right\} \begin{array}{l} \text{Center of} \\ \text{gravity} \\ \text{of center} \end{array}$$

$$Z_n = \frac{2}{L} \int_0^L Z(s) e^{j \frac{2\pi}{L} ns} ds$$

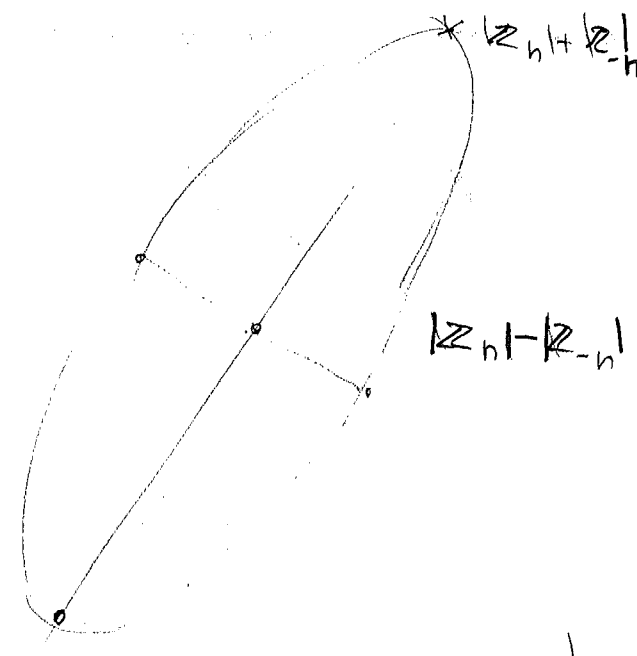
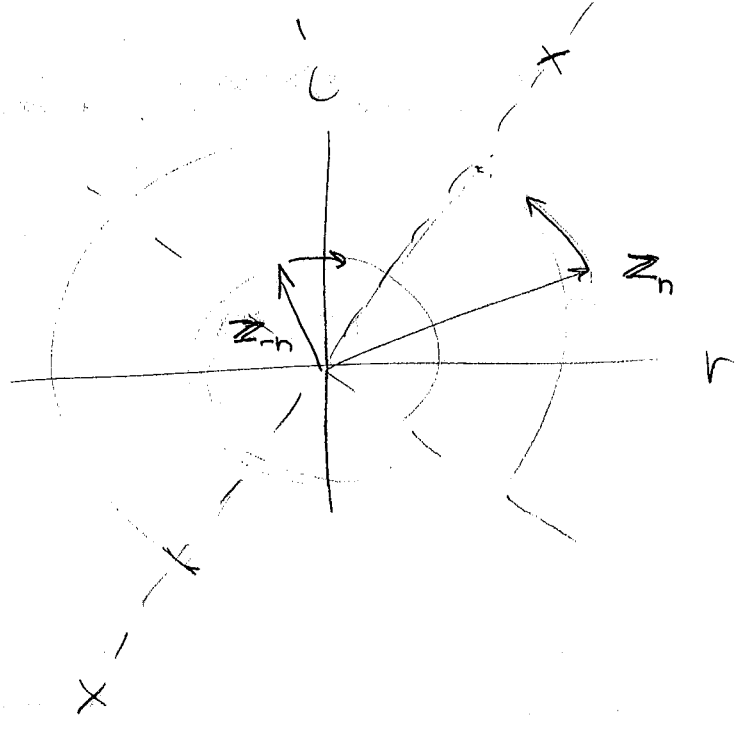
$$Z_{-n} = \frac{2}{L} \int_0^L \underbrace{Z(s)}_{x(s)+iy(s)} \underbrace{e^{-j \frac{2\pi}{L} ns}}_{\text{rotator in complex space}} ds$$

$Z_n^* = Z_{-n}$
conj. complex

$$Z(s) = Z_0 + \sum_{n=1}^{\infty} (Z_n e^{2\pi j (\frac{n}{L})s} + Z_{-n} e^{-2\pi j (\frac{n}{L})s})$$

\uparrow
 center of gravity, translation

$\underbrace{\hspace{15em}}_?$



show!

harmonic contributions: ellipses

$n=1$: $2\pi i \frac{s}{L}$: ellipse surrounded once for $0, L$

$n=2$: $2\pi i \frac{2s}{L}$: ellipse surrounded twice for $0, L$

$n=n$: ...

$$\Rightarrow Z(s) = Z_0 + \sum_{n=1}^{\infty} \text{ellipses}$$

superposition of ellipses



clockwise of rotating points

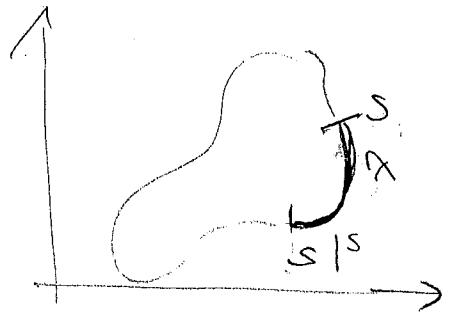
Java Demo's

Invariance

given $z(s)$

• Translation: Set z_0 to ϕ

• Starting Point: (series exp. varies with selection of starting point)



$$s = |s|^{\lambda} + \lambda$$

λ makes quantities that result from shifting by λ

$$z_n(s) = z(|s|^{\lambda} + \lambda) = \sum z_n e^{\frac{2\pi j n (|s|^{\lambda} + \lambda)}{L}} =$$

$$z_n^{\lambda}(|s|^{\lambda}) = \sum_{n=-\infty}^{\infty} z_n e^{\frac{2\pi j n |s|^{\lambda}}{L}} \cdot e^{\frac{2\pi j n \lambda}{L}}$$

$$\Rightarrow z_n^{\lambda} = z_n \cdot e^{jn\theta} \quad \theta = \frac{2\pi \lambda}{L}$$

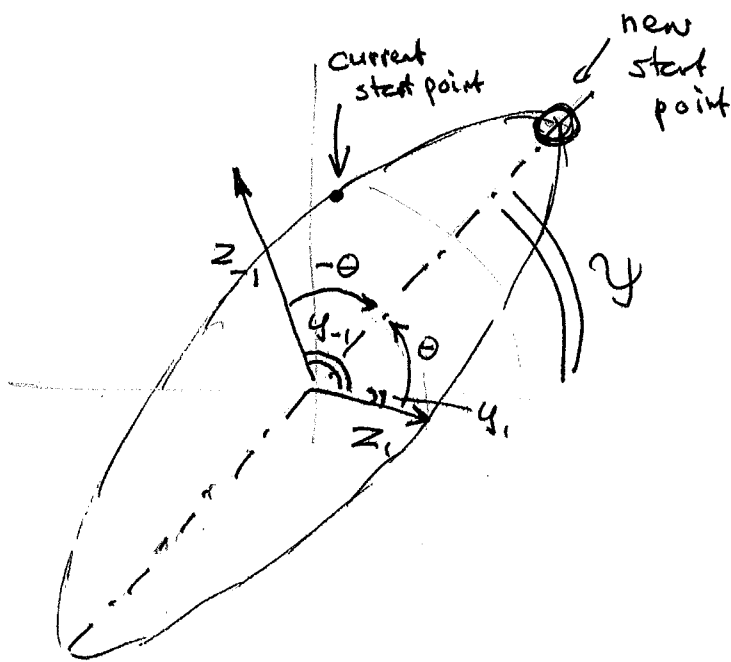
\Rightarrow with θ : we can move the starting point to an arbitrary position along the contour,

good choice?

e.g.: vertex of first order ellipse

Fourier Harmonics II

6a

Start point

$$z_{-1} : \varphi_{-1} \quad ; \quad z_1 = r_1 e^{i\varphi_1}$$

$$z_1 : \varphi_1 \quad ; \quad z_2 = r_2 e^{i\varphi_2}$$

$$\varphi_1 + \theta = \varphi_{-1} - \theta = \psi$$

(angle of ellipse)

$$2\theta = \varphi_{-1} - \varphi_1$$

$$\boxed{\theta} = \frac{\varphi_{-1} - \varphi_1}{2} : \text{"shift" angle}$$

$$\boxed{\psi} = \varphi_1 + \theta = \frac{\varphi_1 + \varphi_{-1}}{2}$$

rotation of ellipse

$$\Rightarrow \text{elli}_1 |^v = z_1 e^{i(\varphi_1 + \theta)} + z_{-1} e^{i(\varphi_{-1} - \theta)}$$

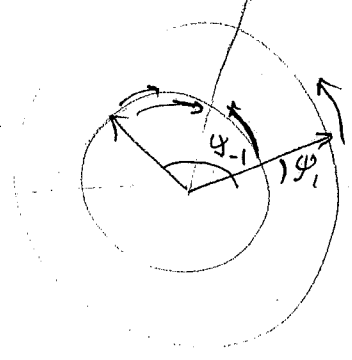
$$= z_1 e^{i(\psi)} + z_{-1} e^{i(\psi)}$$

$$\text{vertex} = (z_1 + z_{-1}) \cdot e^{i(\psi)}$$

how to find?

02/25/2010

66



vertex: both poles in phase!

$$\psi_1 + \theta = \psi_{-1} - \theta = \psi$$

$$2\theta = \frac{\psi_{-1} - \psi_1}{2} \quad \text{necessary shift}$$

$$\Rightarrow \psi = \frac{\psi_1 + \psi_{-1}}{2} \quad \text{posn. of main axis}$$

(shifting starting point = rotation in parameter space, the unit circle)

do it: $\text{elli.} = z_1 e^{j(\psi_1 + \theta)} + z_{-1} e^{j(\psi_{-1} - \theta)}$

$$\text{vertex} = (z_1 + z_{-1}) e^{j\psi}$$

\Rightarrow first ellipse: calculate θ through current starting point
rotate coefficients by $|z_n| = z_n e^{j\theta}$

o Rotation: rotate coordinate system by ψ or object by $-\psi$

$$z|^{R}(s) = z(s) \cdot e^{-j\psi} = \sum_{n=-\infty}^{\infty} z_n e^{-j\psi} \cdot e^{\frac{2\pi i n s}{T}}$$

$$|z_n|^R = z_n e^{-j\psi}$$

why did we use ψ ? main axis of first ellipse becomes new real axis



Problem: ellipse has two vertices \rightarrow ambiguity!

important! all coefficients multiplied by the same phase

• Scaling

02/25/2010

7

$$z|^{s}(s) = \alpha z(s) = \sum_{n=-\infty}^{\infty} (\alpha z_n) e^{\frac{2\pi j n s}{L}}$$

$$z_n|^{s} = \alpha z_n \quad | \text{ scale factor } \alpha$$

normalization, e.g. long axis of first ellipse

becomes 1:
$$\alpha = \frac{1}{|z_1| + |z_{-1}|}$$

• all together:

calculate $z(s) = z_0 + \sum \text{ellipses} \dots$

first ellipse z_1, z_{-1} gives $\psi, \theta, z_1, z_{-1}$

$$\Rightarrow z_n|^{V,R,S,T} = \sum_n z_n \frac{e^{j(n\theta - \psi)}}{|z_1| + |z_{-1}|}$$

$z_0 = 0$

\Rightarrow object representations become independent of

T, R, S , start point,

z_n = descriptor,
shape feature vector

• truncation

$$z(s) = \sum_{n=-N}^N z_n e^{\frac{2\pi j n s}{L}}$$

$$f(s) = z(s) - z^c(s) = \sum_{|n| > N} z_n e^{\frac{2\pi j n s}{L}}$$

mean square error ϵ_2

$$\epsilon_2^2 = \int_0^L |f(s)|^2 ds$$

$$= \int_0^L \left| z(s) - \sum_{|n|>N} z_n e^{\frac{2\pi i n s}{L}} \right|^2 ds = \int_0^L |f(s)|^2 ds$$

energy in image space

$$= \dots = L \sum_{|n|>N} |z_n|^2 = L \sum_{|n|>N} r_n^2 = \epsilon_2^2$$



Sentence of Parseval

energy in frequency space

|| mse between parametrized curves via ||
 || sum of coefficients ||

$$\int_0^L |z(s)|^2 ds = L \cdot \sum_{k=-\infty}^{\infty} |z_n|^2$$

energy in image space

energy in frequency space (coefficients)

Classification of Objects

80

model object g : descriptor $\{z_n[g]\}$

unknown object u : descriptor $\{z_n[u]\}$

classification distance:

$$D[g] = \sum_{n=-N}^N |\tilde{z}_n[g] - z_n[u]|^2$$

if several models:

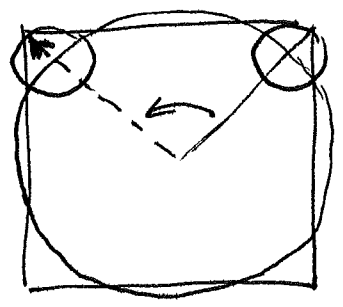
- calculate distances $D[g_1]$
 $D[g_2]$
 \vdots
 $D[g_k]$

- assign new object u to class g_i
with smallest distance:

$$i = \underset{g_i}{\operatorname{argmin}} \{D[g_i], g_i = \text{objects}\}$$

Quiz: Approximation of square

Fourier → sharp cusps/corners?



which orders will be necessary?

- order $\boxed{1}$: circle
- ⇒ ~~order 4~~: NO

order 1: we move $+90^\circ$

order x : also $+90^\circ$ for corner correction

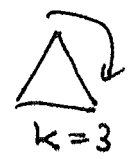
or: $\underline{360^\circ + 90^\circ} = 450^\circ$

full cycle: $4 \cdot 450^\circ = 1800$
 $= 5 \cdot 360^\circ \Rightarrow \boxed{5}$ order

or: $\underline{-270^\circ}$

full cycle: $4 \cdot -270^\circ = -1080^\circ$
 $= 3 \cdot -360^\circ \Rightarrow \boxed{3}$ order

In general: coefficients for rotational symmetry?



Repetition: $\frac{2\pi}{k}$

rule: $Z(s + \frac{L}{k}) = e^{\frac{2\pi j}{k}} Z(s)$

shift by $\frac{L}{k}$
 \Rightarrow
 rotation in
 parameter space

$\Rightarrow Z(s + \frac{L}{k}) - e^{\frac{2\pi j}{k}} Z(s) = 0$

(coefficients the same after object)
 rotation with $\frac{2\pi}{k}$

$\Rightarrow \sum Z_n e^{\frac{2\pi j n s}{L}} e^{\frac{2\pi j n}{k}} - \sum Z_n e^{\frac{2\pi j n s}{L}} e^{\frac{2\pi j n}{k}} = 0$

$\Rightarrow \sum Z_n e^{\frac{2\pi j n s}{L}} \cdot e^{\frac{2\pi j n}{k}} \left(e^{2\pi j \left(\frac{n-1}{k}\right)} - 1 \right) = 0$

$e^{2\pi j \left(\frac{n-1}{k}\right)} = 1$

$\frac{n-1}{k} \in \mathbb{N}_1 = \{1, 2, \dots\}$

(similar in other direction)