

# **Eurographics 2006**

State-of-the-art in Real-time, Interactive

Massive Model Visualization

Putting Theory into Practice (Inigo Quilez, VRcontext)

September 2006





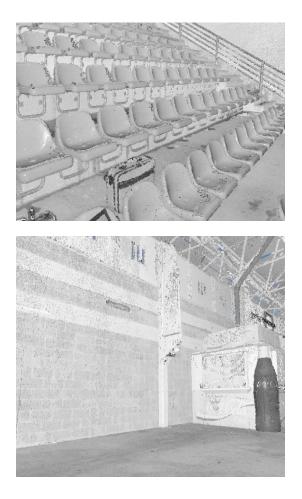


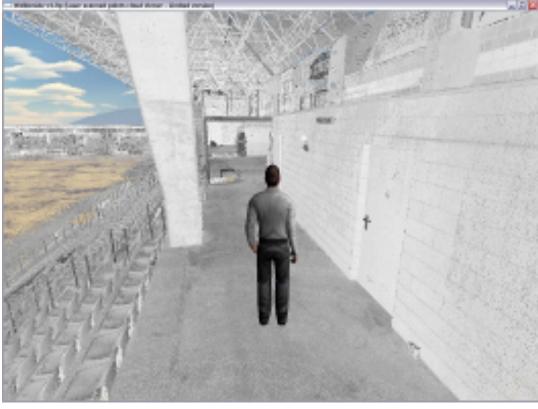
VR support, camera collision detection, real-time monitoring and controlling, database links, scene editing – scripting, fast model loading, moving object

## **Lasser scanning - pointclouds**



About 100 billion pointsWith collision detection





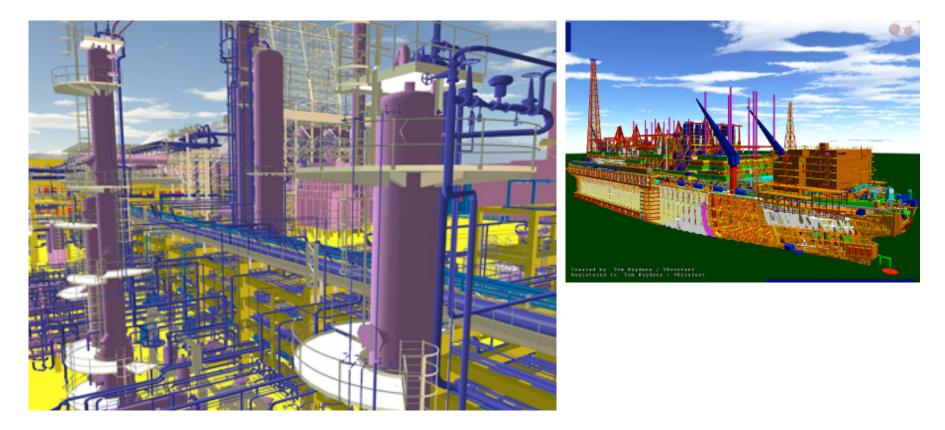
UEFA stadium, 2.5 billion points dataset – 200 scans

# **CAD** File



•An FPSO with more than 1 billion polygons

- •A refinery with 4 million objects (>1 billion polygons)
- •A nuclear reactor room with more than 1 million primitives





- 1. Most real data is bad formed
- 2. About data set size gamming technology are unsuitable for massive models
- 3. About quality

- 4. Other practial problems
- 5. Somehow incorrect assumtions on the research



- 1. Most real data is bad formed
- 2. About data set size gamming technology are unsuitable for massive models
- 3. About quallity

- 4. Other practial problems
- 5. Incorrect assumptions on academic research

## 1. Most real data is bad formed



- CAD models:
  - T junctions
  - incorrectly oriented geometry
  - not orientable geometry
  - duplicated geometry
  - clashes
- Laser scanned point clouds
  - noise
- GIS
  - less than optimal triangulation



- 1. Most real data is bad formed
- 2. About data set size

gamming technology are unsuitable for massive models

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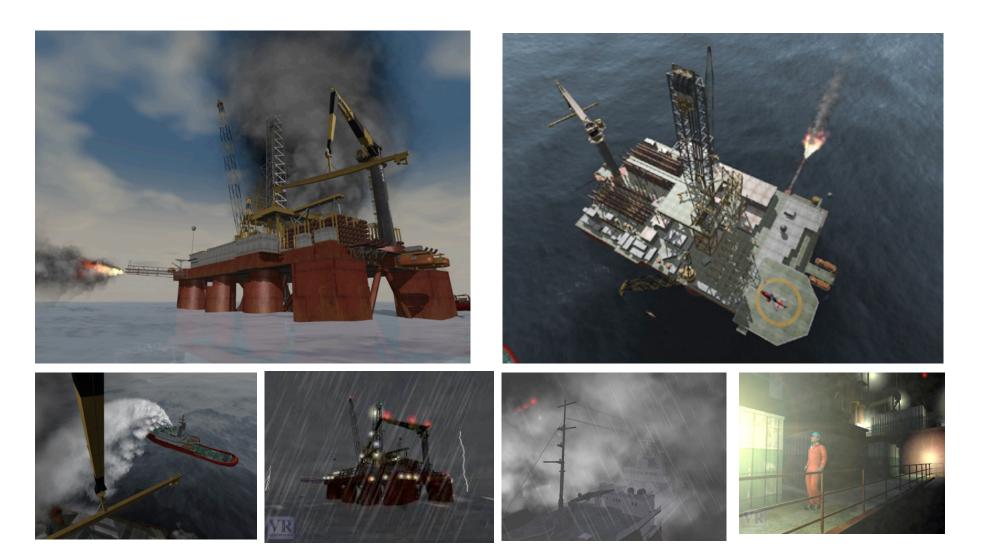
## 2. Data set size



- Game technology and most scientific visualization techniques cannot do
  - Shadows
  - Advanced (global) lighting



## 2. Data set size (demo)



VRcontext, September 2006

www.VRcontext.com



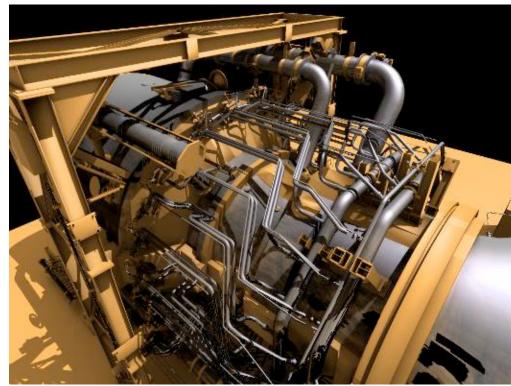
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# 3. Raytracing – the solution for quality...



- It scales well with polycount
- Shading effort is the minimun possible



7 million polygons + AO

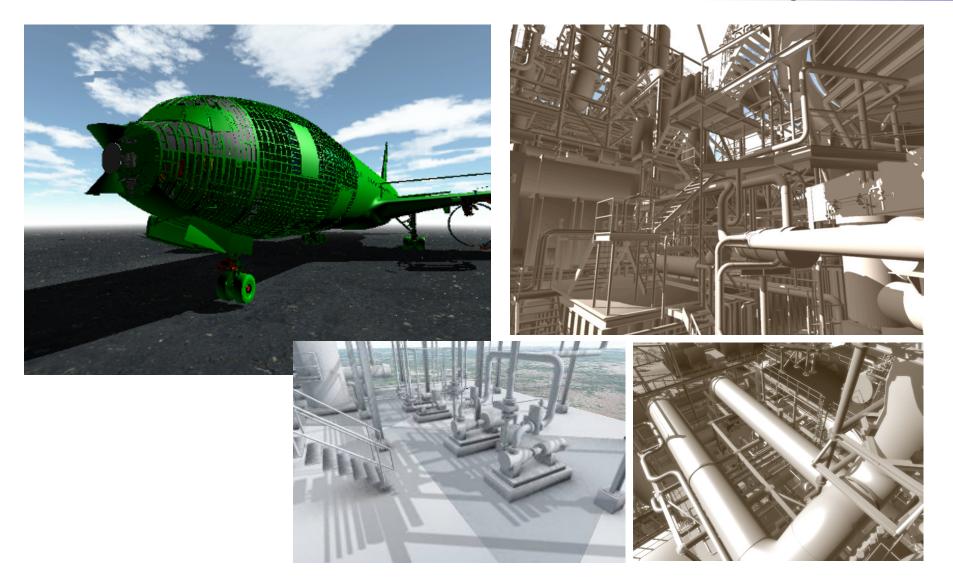


5 million polygons

VRcontext, September 2006

## ... with massive models. Or may be not?







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## 4. Other problems



- SDKs
  - how to hide our implementation, and still keep maximun performance
- Moving objects
  - the evil of most algorithms
- Document/export management
  - delta exporting, incremental precomputations affects data structures
- File formats
  - too many standards means no standard
- Virtual Reality setup
- Marketing, the money



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# **5. Incorrect assumtions**

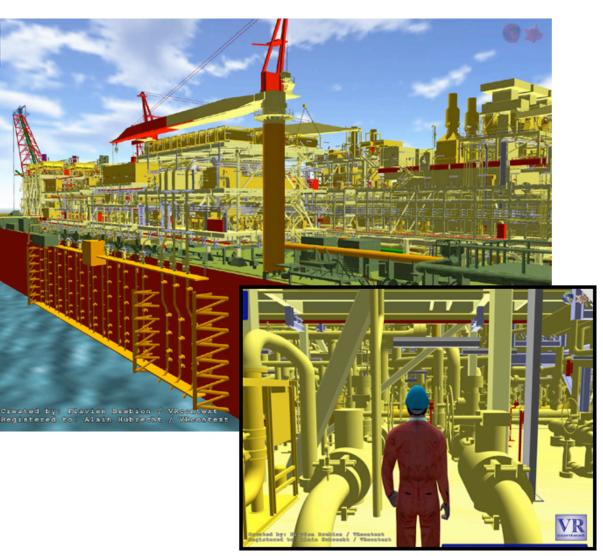
- Frame to frame coherence
- Out of core?
- Medium density model



## **5. Density of the models**



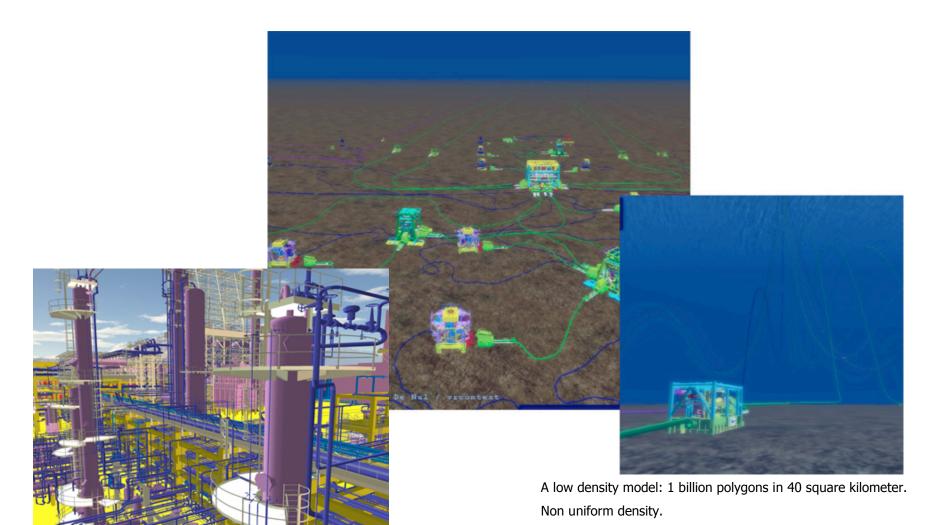
- High Density
  D > 10k t/m<sup>3</sup>
  DR ~ 1:10<sup>3</sup>
- Medium Density
  D ~ 100-1k t/m<sup>3</sup>
  DR ~1:10<sup>5</sup>
- Low Density
  D < 1tri/m<sup>3</sup>
  DR >1:10<sup>6</sup>



A typical medium density model (600 million polygons)

#### Low Density models





2 million objects in 5 square kilometers. Uniform density.



#### Conclusion

- Many models, not possible to tune for just one type
- Fast research often means simple solutions
- It's not clear what's the best technology, so the product has as much software engineering as pure visualization work.
- Still need to work on low density models and high quallity shading.